

BPM Inputs to Physics Requirements at NSLS-II



Yong HU

NSLS-2 Controls Group

EPICS Meeting@BNL, Oct. 12, 2010

Outline

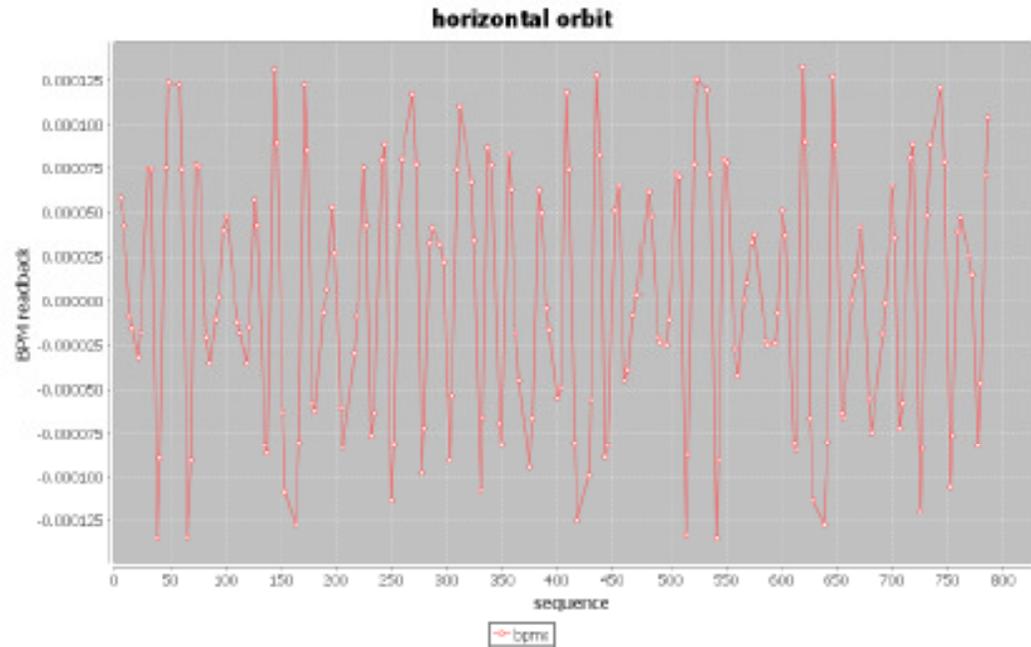
- ❑ **Overview of NSLS-2 BPM (beam position monitor)**
- ❑ **Procedure to use BPM for fast orbit feedback (FOFB)**
 - 1) **Beam-based alignment (BBA): BPM-to-Quad offset, golden orbit;**
 - 2) **Response matrix (RM/IRM): global RM for FOFB;**
 - 3) **FOFB enable: when it's ready to go;**
 - 4) **DC shift from fast corrector to slow corrector;**
 - 5) **Disable FOFB when failures (lost communication, etc.) happen;**
- ❑ **BPM data associated with physics applications and requirements**
 - 1) **ADC raw data: diagnostics;**
 - 2) **TBT(turn-by-turn): very useful for machine commissioning and study;**
 - 3) **FA (fast acquisition, ~10KHz): FOFB, machine protection interlock, etc.;**
 - 4) **SA (slow acquisition, ~10Hz): very important; BBA, RM, closed orbit display;**
- ❑ **Controls implementation**
- ❑ **Conclusions**

Overview of NSLS-2 BPM System (architecture)

- **BPM System:** pick-up (i.e. button) + **electronics/receiver + controls** + HLA/physics(i.e. orbit server by Guobao)



7mm / 4.47 mm button
By Igor Pinayev (physicist)



HLA: Orbit display
By Guobao Shen

Overview of NSLS-2 BPM System (architecture)

commercial BPM:
Libera Brilliance



Temperature controlled rack
+/-0.1 DegreeC

3 Liberars:
2 Liberars 2.0 + 1 Libera 1.46



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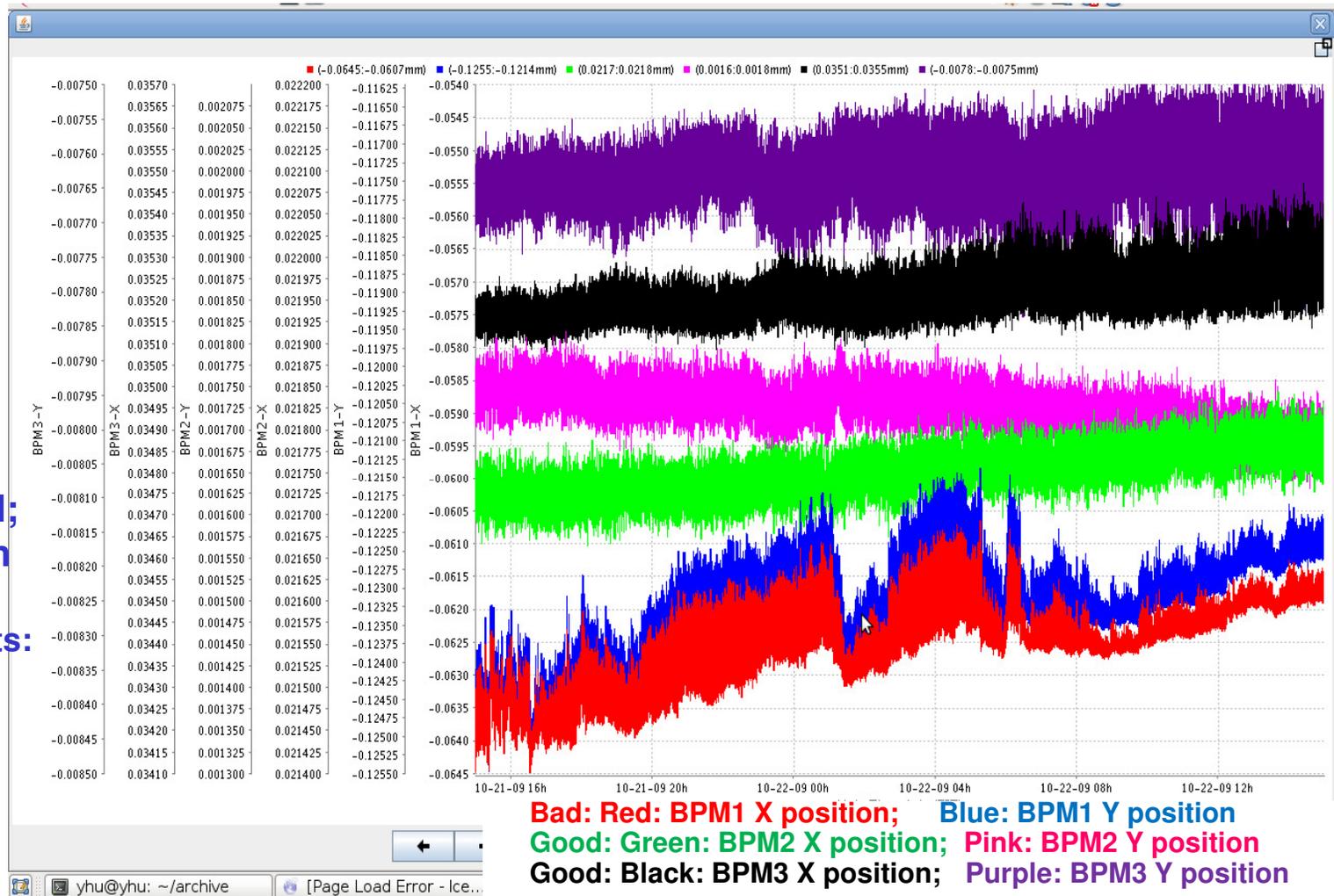
Overview of NSLS-2 BPM System (architecture)

**commercial BPM:
Libera Brilliance**

Test results:

- 1 is bad, 2 good;
- 0.2um drift / 24h

**NSLS-2 requirements:
0.2um / 8-hour**



Overview of NSLS-2 BPM System (architecture)

Motivation for Internal BPM Development

From Kurt Vetter

- Commercial Vendor FPGA technology at the end of its life cycle
 - Commercial vendor not willing to incorporate latest FPGA technology
 - Current hardware design completed in 2003 (*10 years old at NSLS-II commissioning*)
- Do not have access to commercial vendor FPGA or uP Source Code
 - NSLS-II completely dependent on commercial vendor for corrections, modifications, and upgrades
- High cost - \$13,500 per unit (NSLS-II quantity of 250 units)
 - Projected Internally developed BPM production cost ~ \$7,500 per unit (includes testing)
- Long-Term drift compensation (i.e. "RF Switching") introduces transients in signal path down to 3.9KHz
 - Compensation to mitigate transients may reduce phase margin of FOFB bandwidth

**In-house BPM
started in 09/2009**



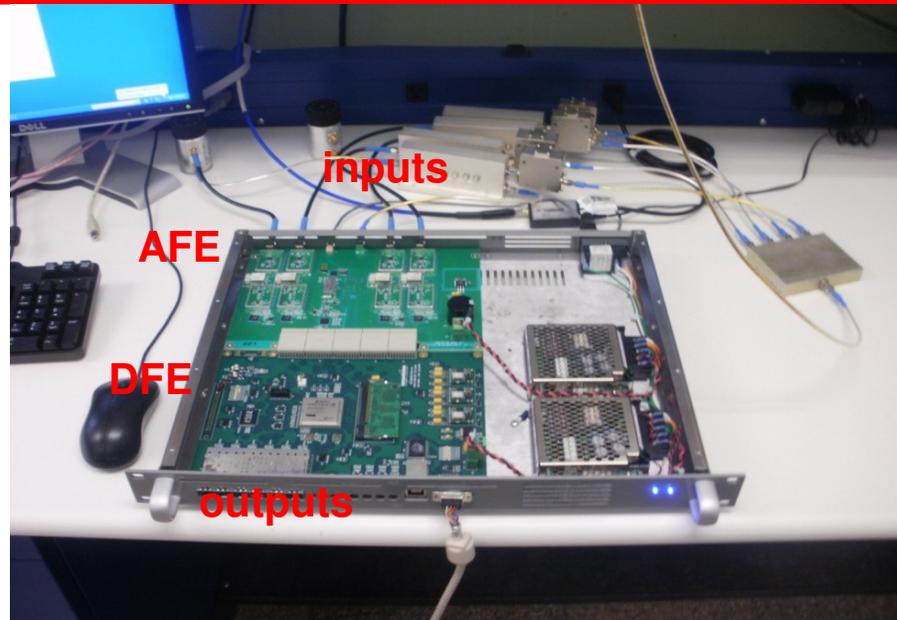
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Overview of NSLS-2 BPM System (architecture)



❑ In-house BPM receiver: 2 boards (AFE + DFE)

- Analog front-end: filters(LPF, BPF) + amplifiers + attenuators + ADCs;
- digital front-end: FPGA + DDR2 memory + SFPs/Ethernets;

❑ Outputs from BPM:

- **Output data flows: ADC, TBT, FA, SA (more details later);**
- Ethernet ports: ADC(117MHz), turn-by-turn(380KHz), slow acquisition(10Hz);
- SFPs/SDI: fast acquisition(~10KHz)

❑ BPM team (3 dedicated engineers, ~10 involved in total):

- Physicists + engineers(diagnostics, controls, mechanical) + technicians;



Overview of NSLS-2 BPM System (features)

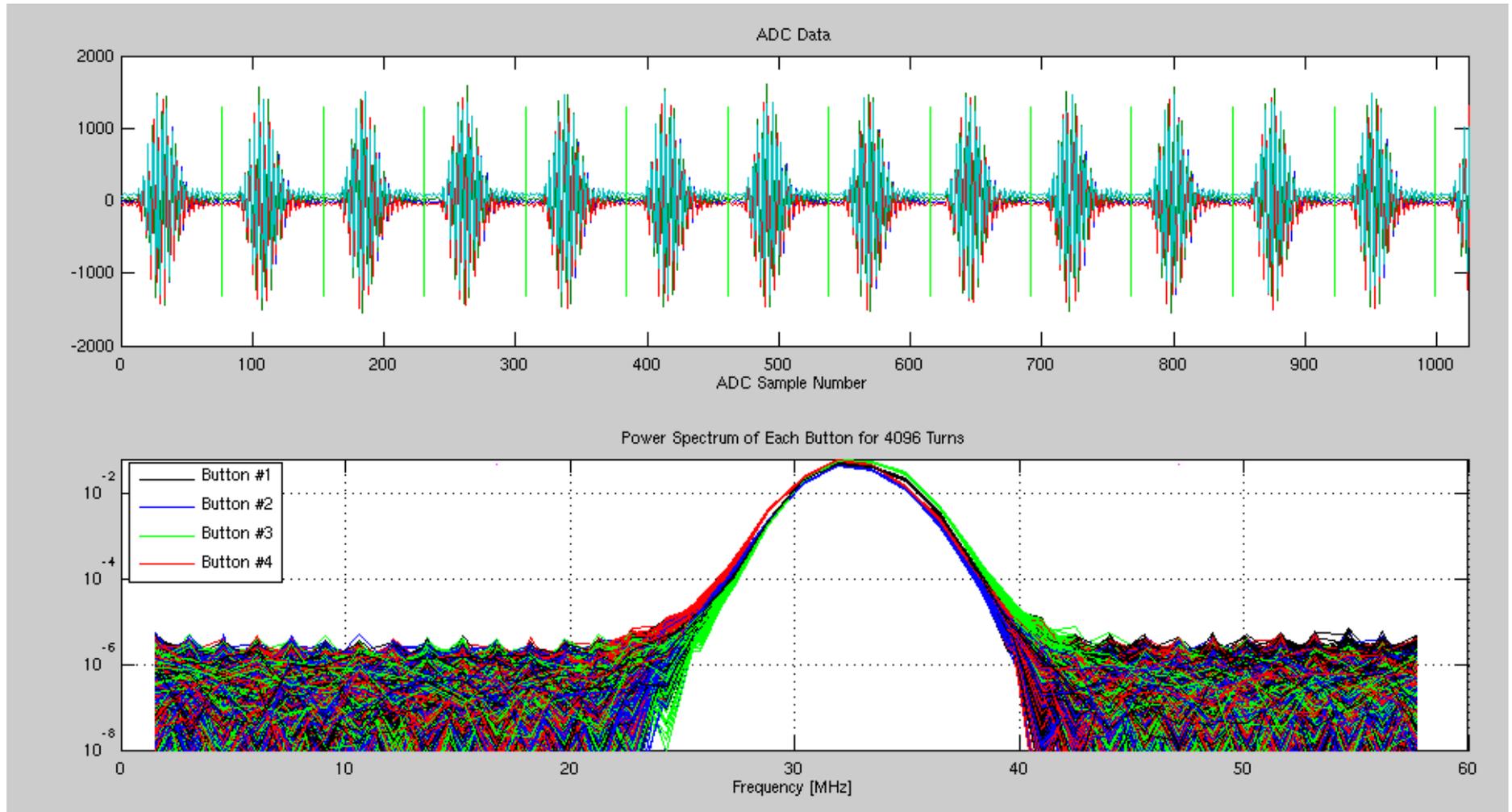
□ New features of NSLS-2 BPM (compared with Libera Brilliance)

- **Latest FPGA technology:** Vertex-5 / Vertex-6;
- **Deep DDR2 memory(256MB):** ADC data(~3.8K turns), TbT data(>1M turns);
- **Embedded FFTs:** spectrum of 10KHz FA data, TbT for tunes measuring, etc;
- **No crossbar switching noise:** use pilot tone for active calibration;
- **Easy programming:** Matlab/Simulink/System Generator for VHDL coding;
- **Embedded event receiver for timing:** better synchronization, global time-stamp;
- **Seamless FOFB integration:** Cell Controller shares the DFE board of BPM;
- **Open hardware & software:** the DFE with FPGA code will be open;
- **In-house expertise:**
 - big difference: jump from how to use DBPM to how to make it;
 - good for system maintenance, future upgrades, etc.

Overview of NSLS-2 BPM System (progress)

ADC raw data: tested at ALS, 77samples/turn

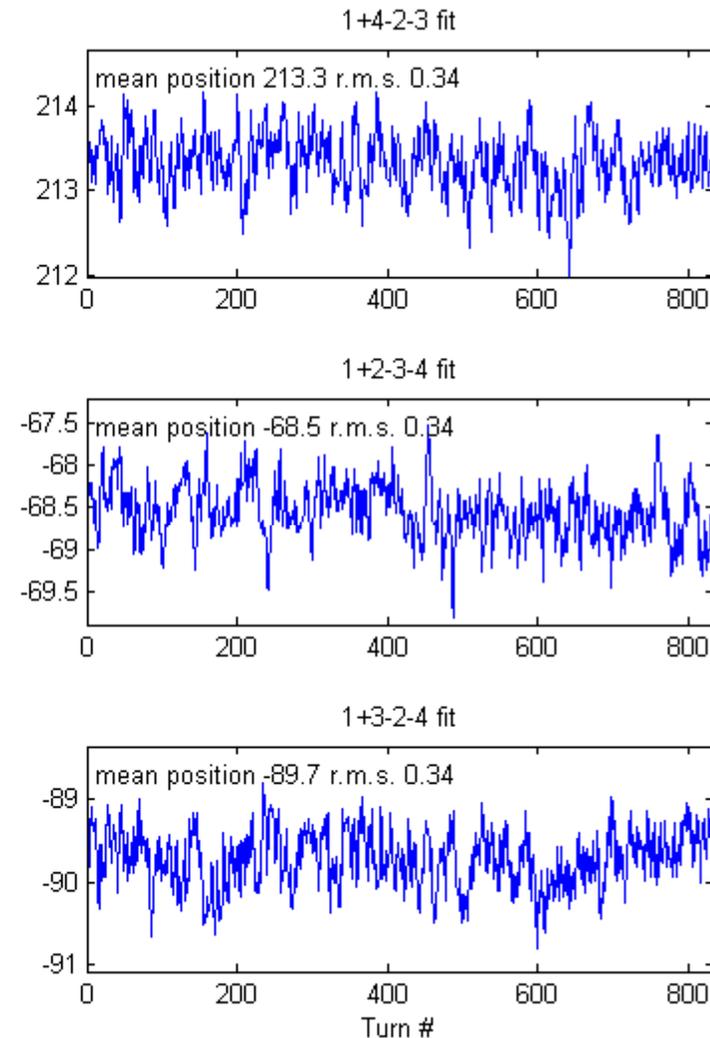
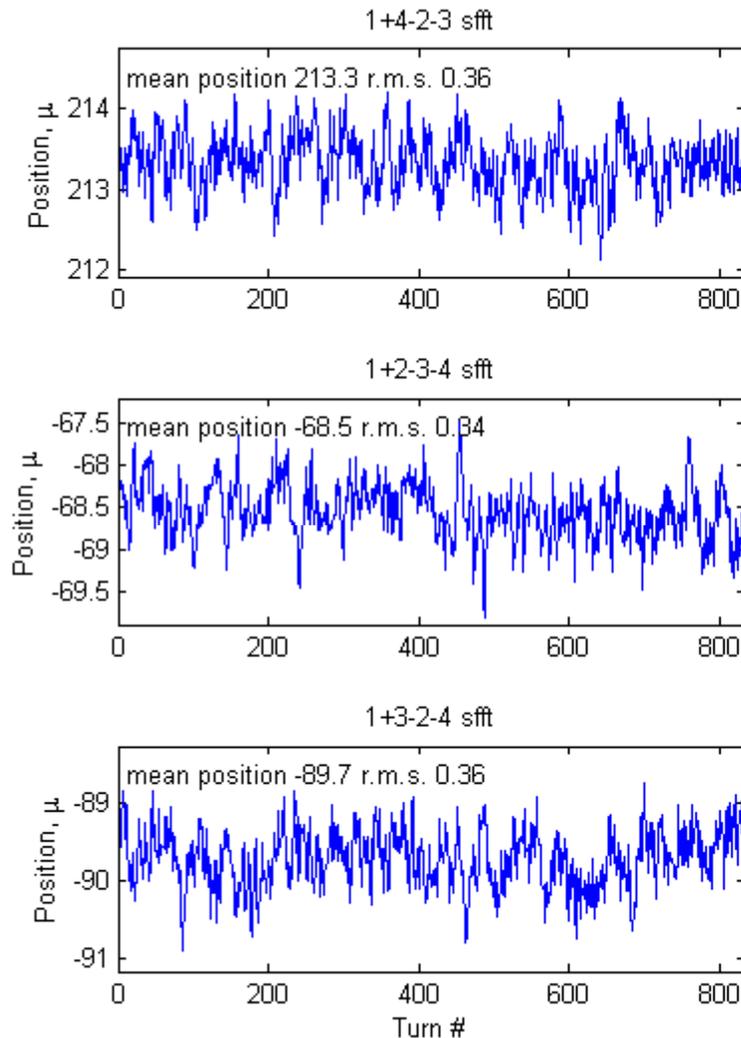
From Kurt Vetter



Overview of NSLS-2 BPM System (progress)

Turn-by-turn (~340nm RMS noise / resolution): tested at ALS

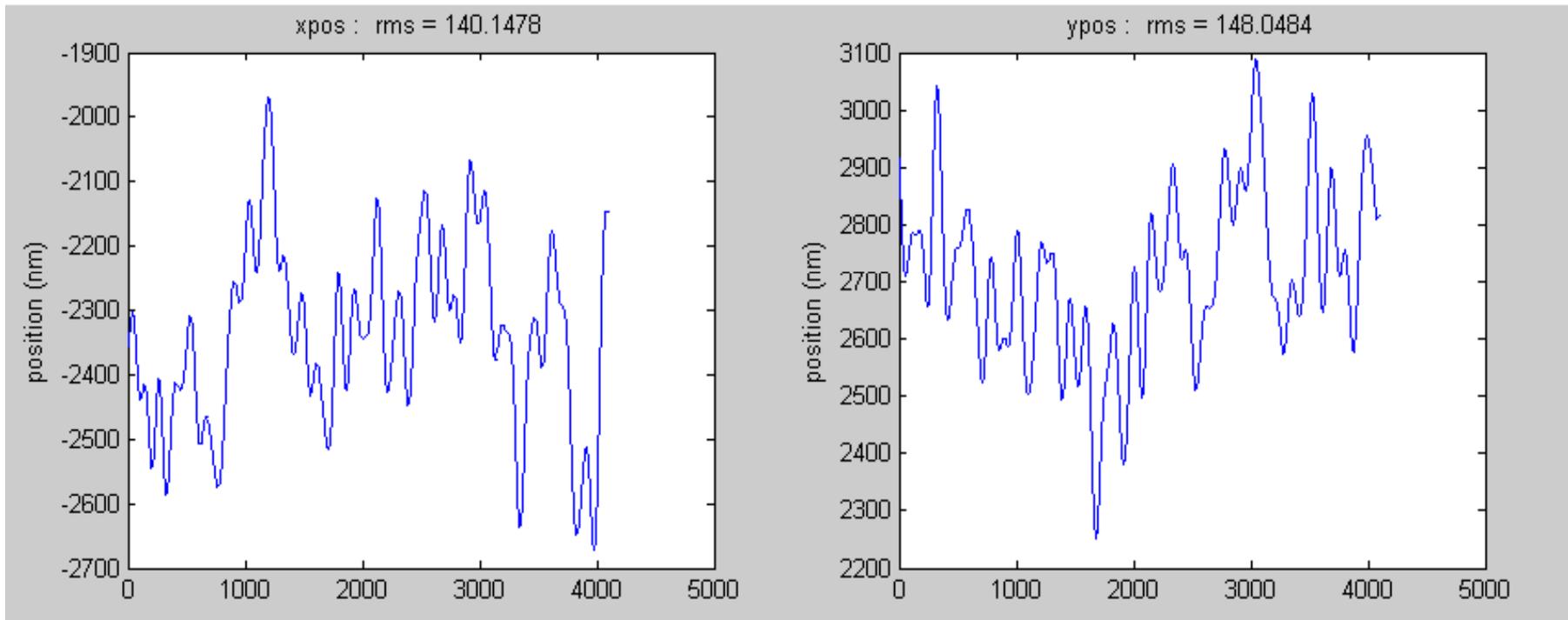
From Kurt Vetter



Overview of NSLS-2 BPM System (progress)

10KHz FA data: tested at Lab, <200nm RMS noise / resolution

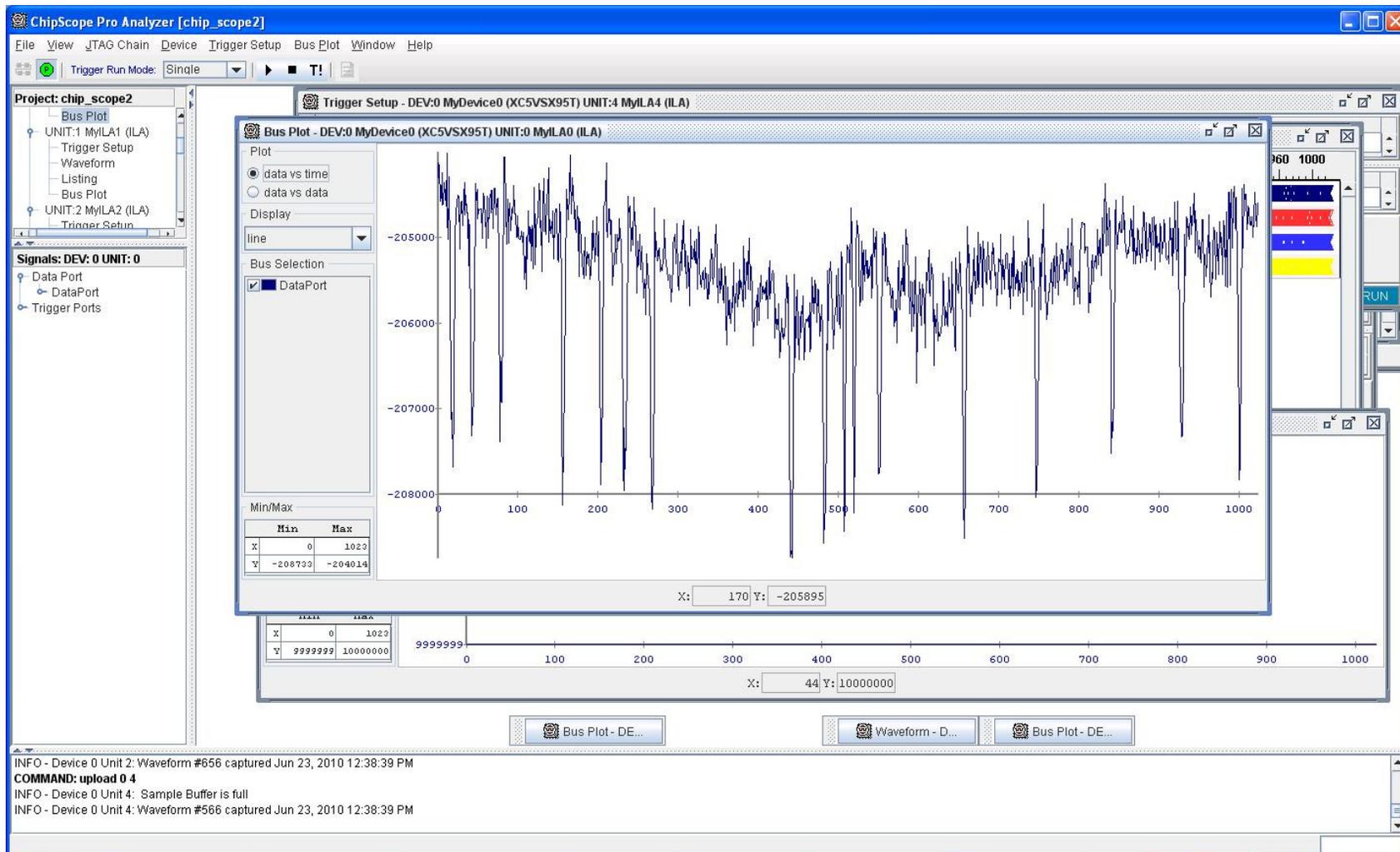
From Joe Mead



Overview of NSLS-2 BPM System (progress)

10Hz SA data: **glitch issue**;
the cause is found: unstable amplifier, second-version AFE started;

From Joe Mead

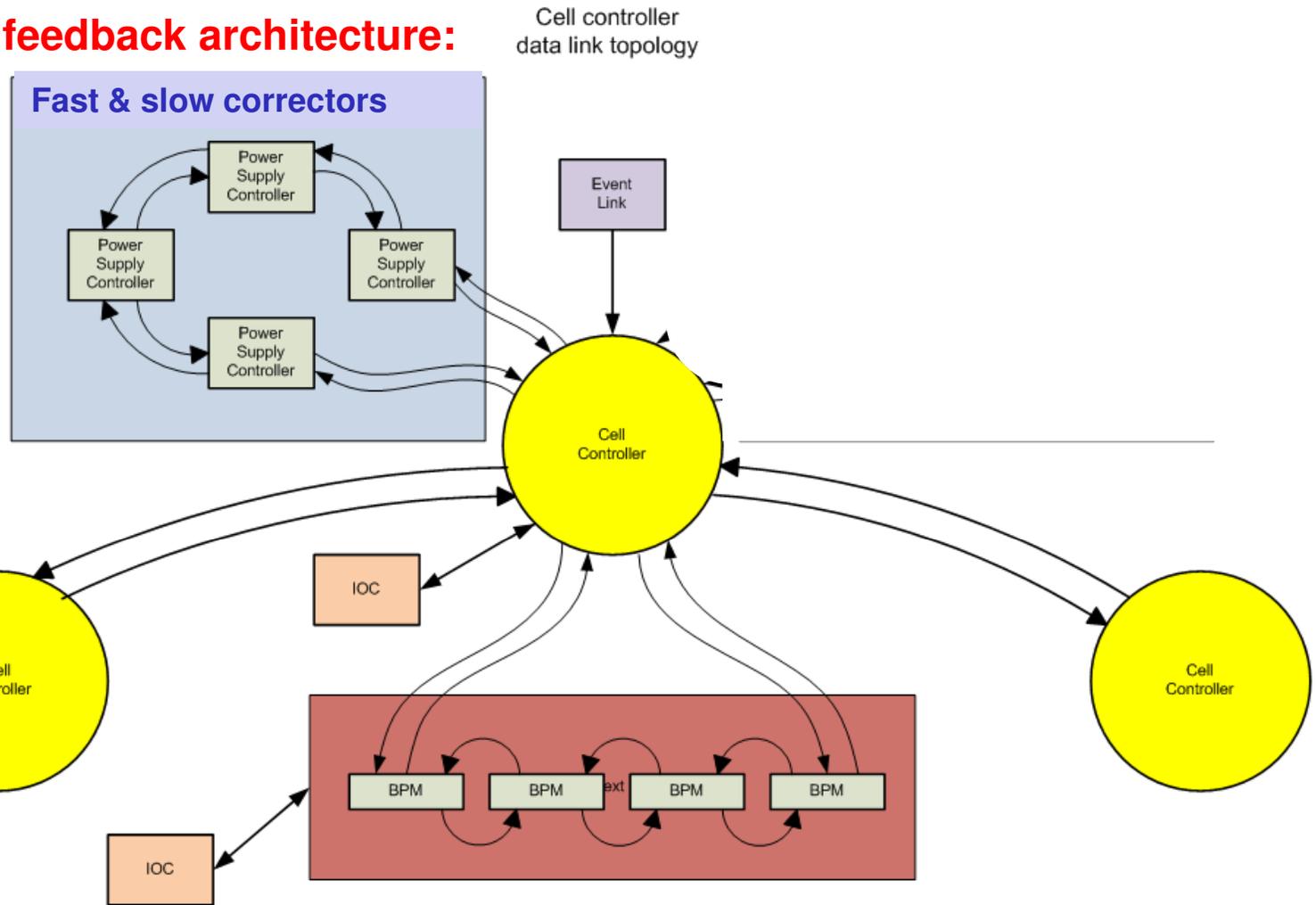


Procedure to use BPM for FOFB (architecture)

NSLS-II Fast orbit feedback architecture:

more details in Yuke's talk

By Joe DeLong

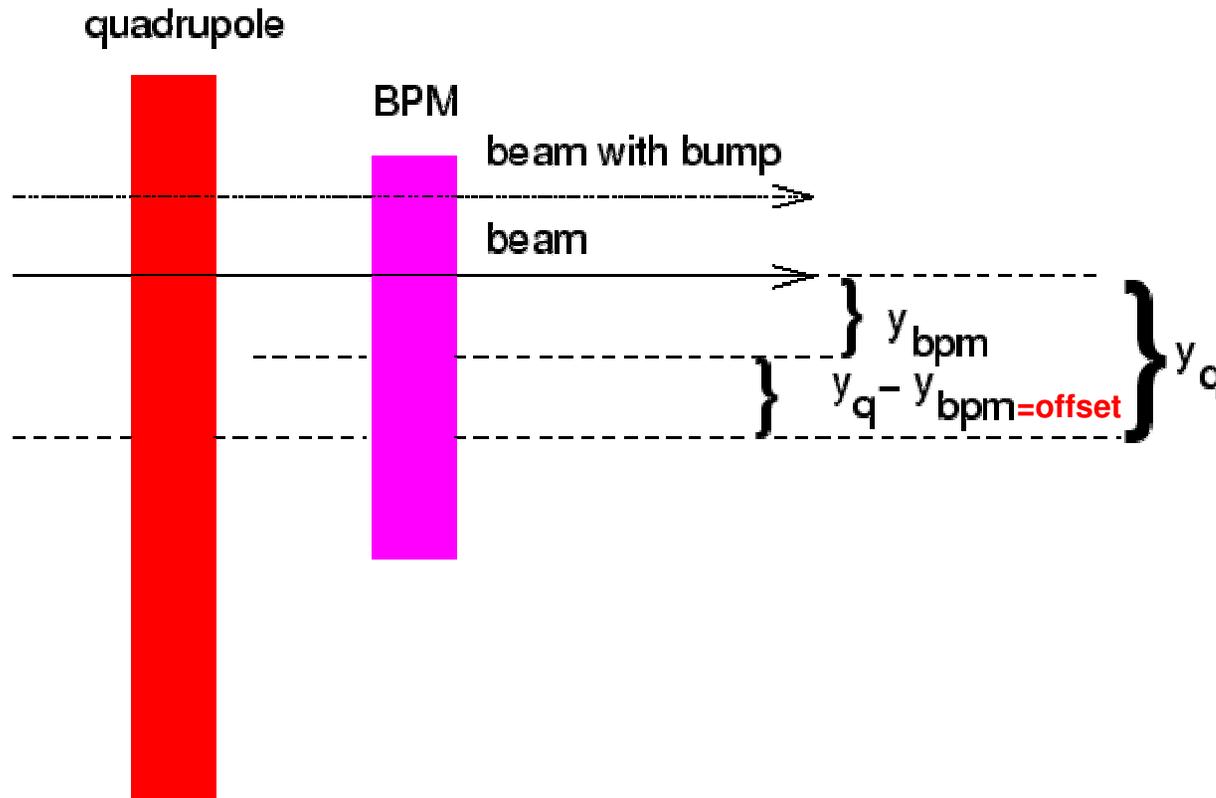


- Local BPMs 10KHz data at each cell → Cell Controller (data concentrator, algorithm computation, communication link / SDI) → neighboring CCs → global BPMs data for global orbit feedback

Procedure to use BPM (first step: beam based alignment)

□ Why do BBA: get BPM-to-Quad offsets and use them for position calculations

- $X/Y = Kx/y * ((Va+Vd)-(Vb+Vc))/(Va+Vb+Vc+Vd) - X/Y_{offset}$;
- **Golden orbit** is the offset in a sense;
- Golden orbit(offsets) will be integrated into NSLS-II IRMIS;



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□ What BPM data used: 10Hz SA

- 10Hz data will be averaged to lower rate (i.e. 1Hz) with higher resolution;
- Resolution requirement: the higher the better, 0.2um RMS noise is good;
- Since centering one Quad only takes short time(1-min), no position drift issue;

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- ❑ **Who/how do it: HLA, physics group, physicists know how;**
 - Physicists play with BPM SA data, slow correctors and quadrupoles, etc.;
 - Principle: steer beam to pass through the magnetic center of individual quad:

- ❑ **When do it: time consuming (several hours)**
 - not frequently, commissioning, start of each run

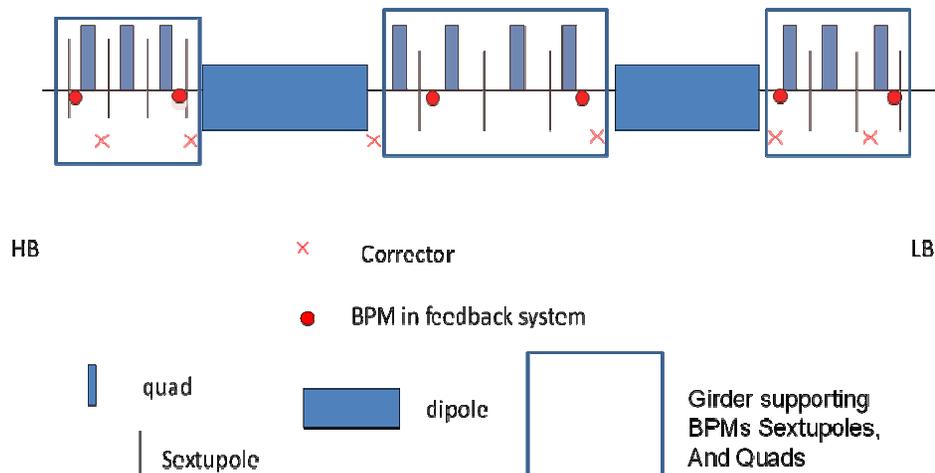
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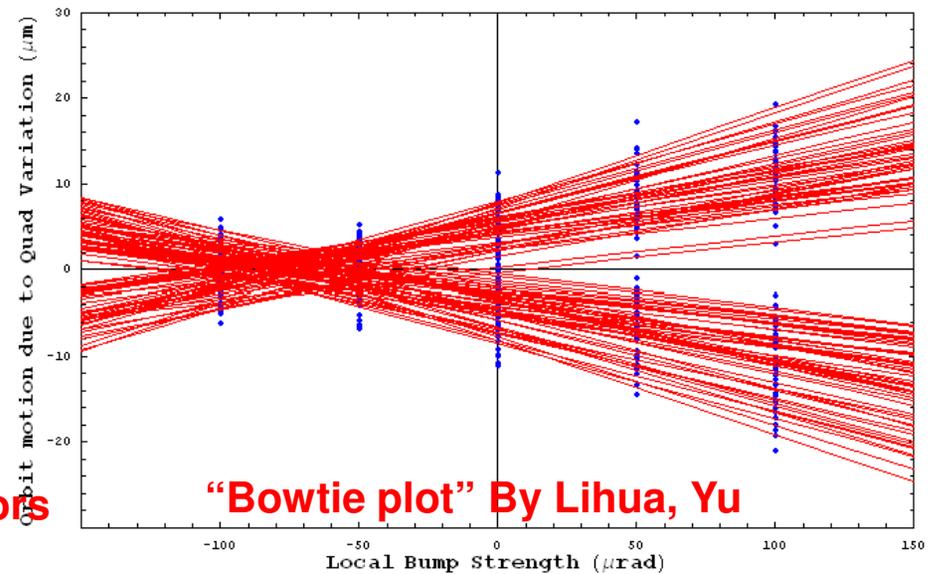
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Latest layout of BPMs, Quads, correctors for FOFB, By Lihua, Yu

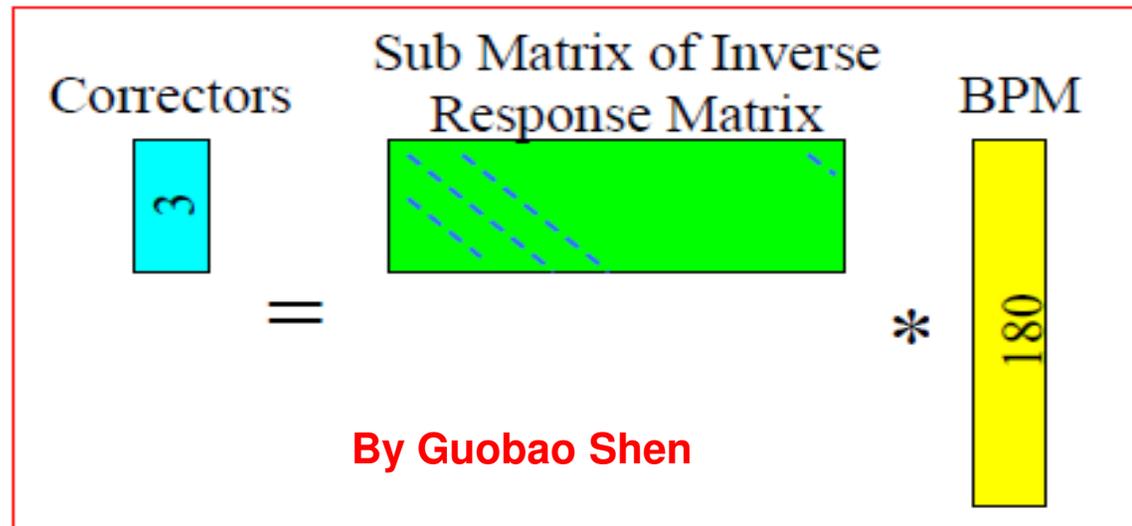
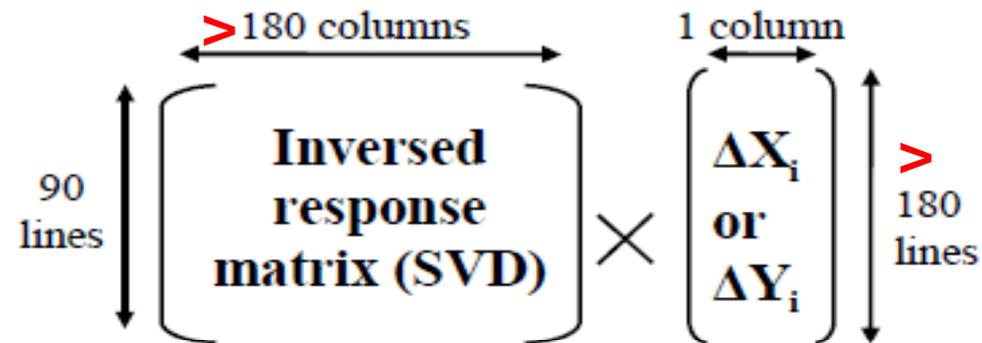


“Bowtie plot” By Lihua, Yu



Procedure to use BPM (second step: response matrix)

- Why need global RM (IRM/SVD): for FOFB algorithm which is implemented inside Cell Controller FPGA;



Procedure to use BPM (Response Matrix)

- ❑ **Why need global RM (IRM/SVD): for FOFB algorithm which is implemented inside Cell Controller FPGA;**

- ❑ **What BPM data used: still 10Hz SA**
 - 10Hz data will be averaged to lower rate (i.e. 1Hz);
 - Resolution: the higher the better, 0.2um RMS noise is good;
 - Again, no position drift issue;
 - **All BPMs' data should be globally synchronized;**

- ❑ **Who/how do it: HLA, physics group, physicists know how;**
 - Physicists play with BPM SA data, fast correctors, etc.;

- ❑ **When do it: time consuming (several hours)**
 - not frequently, commissioning, start of each run

Procedure to use BPM (enable FOFB)

When to turn on FOFB:

1) Load our measurement data into BPM & cell controller FPGAs:

- BPM coefficients(Kx/y) into BPMs: determined by BPM geometry;
- Beam-base Alignment data into BPMs: golden orbit (offsets);
- Response Matrix data into cell controller: for FOFB;
- All these data can be treated as constants;
- Loaded during FPGAs initialization;

2) All BPMs & cell controllers communicate well: no broken nodes;

3) Beam current (measured by Bergoz DCCT) \geq threshold (?mA);

4) During initial filling (injection from zero to full, 1Hz): FOFB is off;

5) It's the time: after initial filling, enable FOFB for top-off injection (1-min);

Procedure to use BPM (DC shift)

❑ No slow orbit feedback at NSLS-II:

- NSLS-II FOFB correction bandwidth goes from DC to 200Hz
- NSLS-2 orbit feedback is named **Fast Feedback with Slow Correctors**

❑ Why we still need slow correctors (SC)?

- The fast corrector(FC) might saturate after long-term drift;
- Shift DC components from FC to SC;
- Rate of DC shift is flexible, i.e.10 second;

Procedure to use BPM (disable FOFB)

❑ When to turn off FOFB (conditions):

- Initial filling;
- Machine physics study: BBA, RM, etc;
- BPM / Cell controller broken;
- Machine protection system (MPS) triggered;

❑ But don't dump the beam while disabling FOFB:

- The machine should be alive for a while without FOFB;
- BPM protection interlock signal can be used to dump the beam;
- Other diagnostic monitors might be used for MPS: DCCT, beam losses;

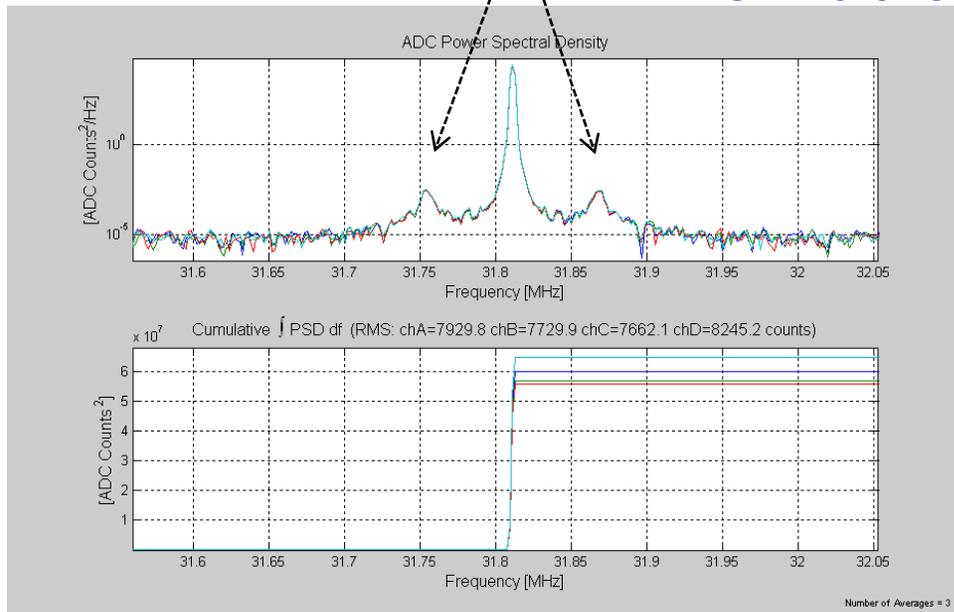
BPM data & applications/requirements

1) ADC raw data (~117MHz, ADC sampling frequency):

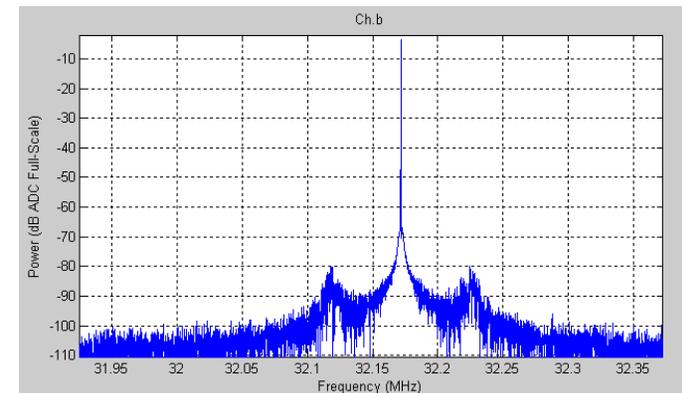
- Useful for diagnostics/debugging;
- Data length requirement: 10 ms (~3.8K turns, 3 turns in Libera) should be OK;

Noise investigation: Power supply /regulator

From Kurt Vetter



1M pt. FFT Using BPM SDRAM



BPM data & applications/requirements

2) Turn-by-turn data (~380KHz, revolution frequency):

- **Very useful and attractive to physicists;**
- **Many applications: tunes, phase advance, injection damping, etc.;**
- **Requirements:**
 - i. **Circular buffer: TBT data are continuously written into circular memory at revolution frequency. The arrival of a timing event stops the writing (freeze the buffer), then EPICS IOC reads out the buffered data;**
 - ii. **All BPMs' TBT data should be synchronized: a counter for each turn;**
 - iii. **Resolution: 1 um is good;**
 - iv. **1-second-length (~380K samples) TBT is enough for physics applications;**

TBT data for tunes measurement:

- a) **Traditional solution: spectrum analyzer-based (NSLS-2 has it in baseline)**
 - **More sensitivity: can detect small betatron oscillation**
- b) **Another solution: FFT TBT data inside our BPM / FPGA (not available from Libera)**
 - **0.01% frequency resolution requirement: $1/(2N) < 0.01\%$ → $N > 5 \cdot 10^4$ (samples)**

BPM data & applications/requirements

3) Fast acquisition (FA) data (~10KHz):

- FOFB;
- Machine protection: if the FA positions (X, Y) are out of range;
- **Spectral analysis by FFT inside our BPM / FPGA (not available from Libera);**
- Requirements:
 - i. Globally synchronized 10KHz data;
 - ii. Resolution: 0.4um RMS noise;

4) Slow acquisition (SA) data (~10Hz): very useful and attractive to physicists:

- BBA (beam-base alignment);
- RM (response matrix);
- Live orbit display;
- Beam life-time measurement (Bergoz DCCT will also be used for life-time);
- Requirements:
 - i. Globally synchronized and time-stamped;
 - ii. Resolution: 0.2 um RMS noise;

BPM data & applications/requirements

data flow \	Data Rate	Applications	Requirements
ADC Raw Data	117 MHz	diagnostics, debugging	on demand; ~ 3.8K samples
Turn-by-turn	378 kHz	tunes, phase advance, injection damping, etc.	on demand; 1 um resolution; ~ 380K samples; synchronization
Fast Acquisition	10 KHz	fast orbit feedback, machine protection	continuous; 0.4um resolution; synchronization
Slow Acquisition	10 Hz	beam-based alignment, response matrix, closed orbit, life-time	continuous; 0.2um resolution; synchronization

Controls Implementation for Physics apps

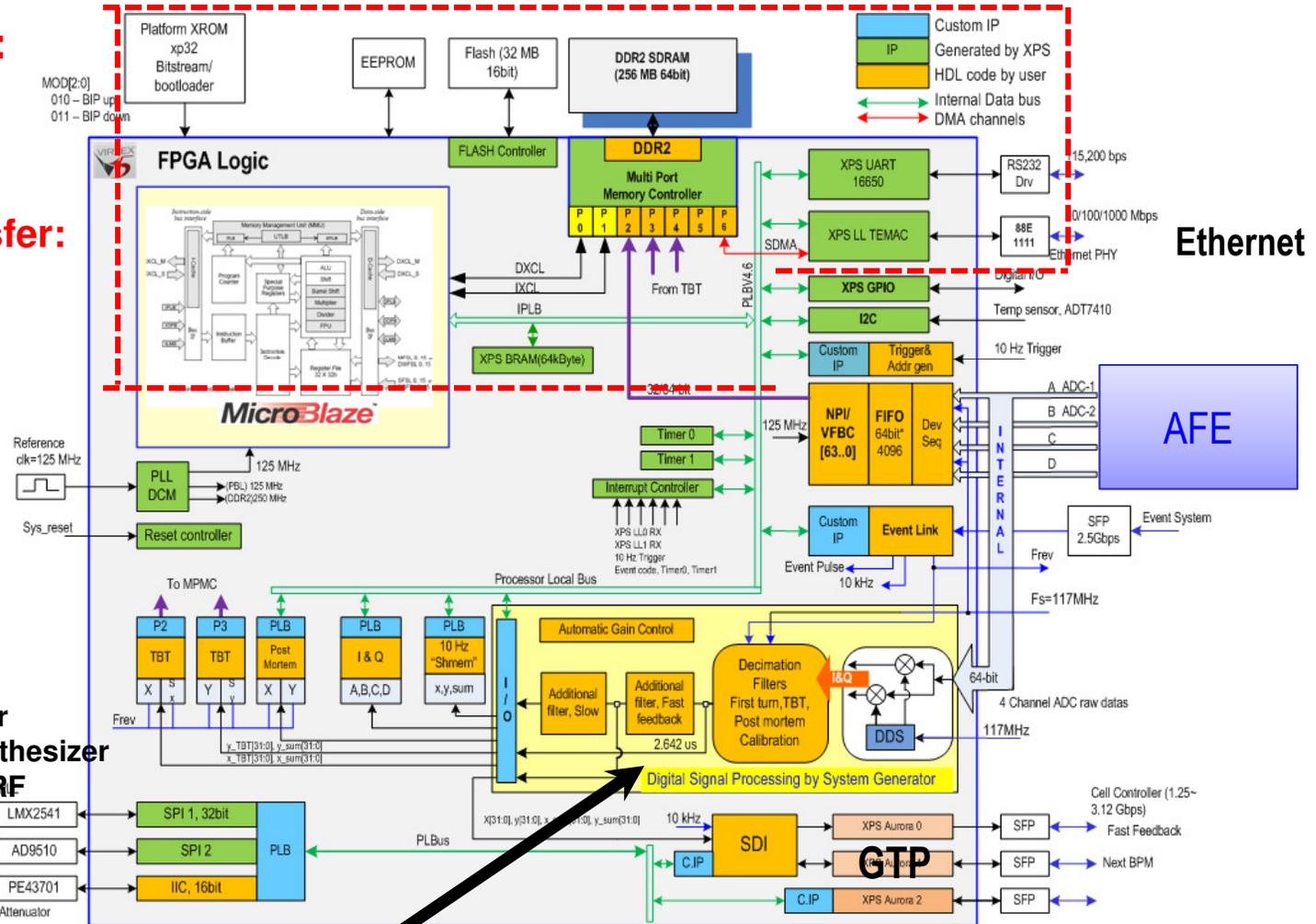
2-layer architecture for BPM data usages:

- Low-level controls(Kiman, Yong, etc.): make BPM data as EPICS PVs
- High-level applications (Guobao, Lingyun, etc): play with the EPICS PVs

Low-level controls:
MicroBlaze + MPMC
+ DDR2 + Ethernet

Large array data transfer:
(ADC, TBT)
 -- Modbus TCP/IP;
 -- TFTP;

- ✓ Attenuator
- ✓ Clock synthesizer
- ✓ Pilot ton RF



DSP module²⁷ By Kiman Ha



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 BROOKHAVEN SCIENCE ASSOCIATES

Controls Implementation for Physics apps

- ❑ **2-layer architecture for BPM data usages:**
 - Low-level controls(Kiman, Yong, etc.): make BPM data as EPICS PVs
 - High-level applications (Guobao, Lingyun, etc): play with the EPICS PVs

- ❑ **Basic implementations: external IOC (1 PC/Linux or VME/RTEMS for one Cell)**
 - 1) **ADC raw data:**
 - 4 EPICS waveform records with 1M (max.) elements each: 4-button(A,B,C,D);
 - Data on-demand / upon timing event;
 - 2) **TBT/PM data:**
 - 5 waveform records with 1M (max.) elements each: A,B,C,D, Counter;
 - Another 4 waveforms (X,Y,S,Q) are calculated in IOC from A,B,C,D;
 - Data on-demand / upon timing event;
 - 3) **FA 10KHz continuous data: currently not available from EPICS IOC;**
 - 4) **SA data:** 10Hz continuously, 5 longin for A,B,C,D,S and 3 ai records for X,Y,Q
 - 5) **Misc:** diagnostics, i.e. temperature, BPM/CC health, IOC CPU/memory usages, etc.

Conclusions

- ❑ **NSLS-II BPM receiver is in good progress;**
 - Digital board (DFE) 100% operational;
 - AFE 2nd version has started to solve glitch issue;
- ❑ **The data flows are enough for physics applications;**
 - BBA, RM. FOFB, tunes, phase advance, injection damping, lifetime, live orbit display, machine protection, post-mortem, etc.
- ❑ **If we beat Libera in terms of stability, we'll be good;**
 - Long-term drift: SA 10Hz data;
- ❑ **Special thanks to my colleagues: K. Vetter, K. Ha, J.DeLong, J.Mead, G-B. Shen, L-H.Yu, Y-K.Tian!**

Thanks ALL!

Backup

TBT: very useful and attractive to physicists:

- Too many applications, do whatever physicists want to do: tunes, phase advance, injection damping, etc.;
- Requirements:
 - i. **Data captured on trigger: receive a trigger, then acquire ~400K (1 second) samples to the DDR-2(buffer) and stop acquiring (freeze the buffer);**
 - ii. **All BPMs' TBT should be synchronized: a counter for each turn;**
 - iii. **Resolution: 1 um is good;**

Backup

Challenging:

- **AFE design;**
- **Stability,**
- **Calibration;**
- **Controls: transfer large array data (ADC raw data, TBT)**

BPM data & applications/requirements

2) Turn-by-turn data (~380KHz, revolution frequency):

- **Very useful and attractive to physicists;**
- **Many applications: tunes, phase advance, injection damping, etc.;**
- **Requirements:**
 - i. **Circular buffer: TBT data are continuously written into circular memory at revolution frequency. The arrival of a timing trigger stops the writing (freeze the buffer), then EPICS IOC reads out the buffered data;**
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TBT data for tunes measurement:

- a) **Traditional solution: spectrum analyzer-based (NSLS-2 has it in baseline)**
 - **More sensitivity: can detect small betatron oscillation**
- b) **Another solution: FFT of TBT data inside FPGA (not available from Libera)**
 - **0.01% frequency resolution requirement: $1/(2N) < 0.01\% \rightarrow N > 5K$ (samples)**

3) First turn (1 sample per injection trigger): like single-pass, **different from TBT**, directly calculated from ADC raw data;

BPM data & applications/requirements

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Post-mortem data:

- **the same buffer as the TBT data;**
- **Different from TBT: PM is acquired from history before PM trigger occurred;**
- **PM Source: global machine protection interlock (MPS);**