EPICS Application Developer's Guide

EPICS Base Release 3.14.10
2 October 2008

Martin R. Kraimer, Janet Anderson, Andrew Johnson, Eric Norum
(Argonne National Laboratory)
Jeff Hill (Los Alamos National Laboratory)
Ralph Lange, Benjamin Franksen (BESSY)
Peter Denison (Diamond)

Table of Contents

Table of Contents 1

Chapter 1: Introduction 7
1.1. Overview 7
1.2. Acknowledgments 9

Chapter 2: Getting Started 11
2.1. Introduction 11
2.2. Example IOC Application 11
2.3. Channel Access Host Example 13
2.4. iocsh 13
2.5. Building IOC components 14
2.6. makeBaseApp 17
2.7. vxWorks boot parameters 20
2.8. RTEMS boot procedure 21

Chapter 3: EPICS Overview 23
3.1. What is EPICS? 23
3.2. Basic Attributes 23
3.3. Hardware - Software Platforms (Vendor Supplied). 24
3.4. IOC Software Components 25
3.5. Channel Access 27
3.6. OPI Tools 29
3.7. EPICS Core Software. 30

Chapter 4: EPICS Build Facility 31
4.1. Overview 31
4.2. Build Requirements 33
4.3. Configuration Definitions 34
4.4. Makefiles 37
4.5. Make. 39
4.6. Makefile definitions 40
4.7. Table of Makefile definitions. 62
4.8. Configuration Files 73
4.9. Build Documentation Files 75
4.10.Startup Files. 76

Chapter 5: Database Locking, Scanning, And Processing 79
5.1. Overview 79
5.2. Record Links 79
5.3. Database Links 80
5.4. Database Locking. 80
5.5. Database Scanning 81
5.6. Record Processing 82
5.7. Guidelines for Creating Database Links 82
5.8. Guidelines for Synchronous Records. 84
5.9. Guidelines for Asynchronous Records 85
5.10.Cached Puts 87

5.11.putNotify 87
5.12.Channel Access Links 87

Chapter 6: Database Definition 91
6.1. Overview 91
6.2. Brief Summary of Database Definition Syntax. 91
6.3. General Rules for Database Definition 92
6.4. Menu 95
6.5. Record Type 95
6.6. Device 100
6.7. Driver 101
6.8. Registrar Declaration. 101
6.9. Variable Declaration 102
6.10.Function Declaration 102
6.11.Breakpoint Table 103
6.12.Record Instance 104
6.13.Record Information Item 107
6.14.Record Attribute 107
6.15.Breakpoint Tables - Discussion 107
6.16.Menu and Record Type Include File Generation. 109
6.17.dbExpand 112
6.18.dbLoadDatabase 112
6.19.dbLoadRecords 113
6.20.dbLoadTemplate 113
6.21.dbReadTest 115

Chapter 7: IOC Initialization 117
7.1. Overview - Environments requiring a main program 117
7.2. Overview - vxWorks 118
7.3. Overview - RTEMS 118
7.4. IOC Initialization. 119
7.5. IOC Pausing 121
7.6. Changing iocCore fixed limits 121
7.7. initHooks 122
7.8. Environment Variables 123
7.9. Initialize Logging 124

Chapter 8: Access Security 125
8.1. Overview 125
8.2. Quick Start. 125
8.3. User’s Guide 126
8.4. Design Summary 131
8.5. Access Security Application Programmer’s Interface 133
8.6. Database Access Security 138
8.7. Channel Access Security 140
8.8. Trapping Channel Access Writes 142
8.9. Access Control: Implementation Overview 142
8.10.Structures 144

Chapter 9: IOC Test Facilities. 145
9.1. Overview 145
9.2. Database List, Get, Put 145
9.3. Breakpoints 147
9.4. Error Logging 149

9.5. Hardware Reports 149
9.6. Scan Reports 150
9.7. General Time 150
9.8. Access Security Commands 152
9.9. Channel Access Reports 153
9.10.Interrupt Vectors 154
9.11.Miscellaneous 155
9.12.Database System Test Routines 155
9.13.Record Link Reports 156
9.14.Old Database Access Testing 157
9.15.Routines to dump database information 158

Chapter 10: IOC Error Logging 161
10.1.Overview 161
10.2.Error Message Routines 161
10.3.errlog Listeners 163
10.4.errlogThread 164
10.5.console output and message queue size 164
10.6.Status Codes 164
10.7.iocLog 165

Chapter 11: Record Support 167
11.1.Overview 167
11.2.Overview of Record Processing 167
11.3.Record Support and Device Support Entry Tables 168
11.4.Example Record Support Module 169
11.5.Record Support Routines 175
11.6.Global Record Support Routines 179

Chapter 12: Device Support 183
12.1.Overview 183
12.2.Example Synchronous Device Support Module 183
12.3.Example Asynchronous Device Support Module 185
12.4.Device Support Routines 186
12.5.Extended Device Support 188

Chapter 13: Driver Support 191
13.1.Overview 191
13.2.Device Drivers 191

Chapter 14: Static Database Access 195
14.1.Overview 195
14.2.Definitions 195
14.3.Allocating and Freeing DBBASE 196
14.4.DBENTRY Routines 197
14.5.Read and Write Database 198
14.6.Manipulating Record Types 199
14.7.Manipulating Field Descriptions 200
14.8.Manipulating Record Attributes 201
14.9.Manipulating Record Instances 202
14.10.Manipulating Menu Fields 204
14.11.Manipulating Link Fields 205
14.12.Manipulating MenuForm Fields 205
14.13.Manipulating Information Items 207

14.14.Find Breakpoint Table 208
14.15.Dump Routines 208
14.16.Examples 209

Chapter 15: Runtime Database Access 211
15.1.Overview 211
15.2.Database Include Files 211
15.3.Runtime Database Access Overview 213
15.4.Database Access Routines 216
15.5.Runtime Link Modification 224
15.6.Channel Access Monitors 225
15.7.Lock Set Routines 225
15.8.Channel Access Database Links 227

Chapter 16: EPICS General Purpose Tasks 231
16.1.Overview 231
16.2.General Purpose Callback Tasks 231
16.3.Task Watchdog 235

Chapter 17: Database Scanning 237
17.1.Overview 237
17.2.Scan Related Database Fields 237
17.3. Scan Related Software Components 238
17.4.Implementation Overview 241

Chapter 18: IOC Shell 247
18.1.Introduction 247
18.2.IOC Shell Operation 247
18.3.IOC Shell Programming 250

Chapter 19: libCom 255
19.1.bucketLib 255
19.2.calc 255
19.3.cppStd 259
19.4.epicsExit 259
19.5.cvtFast 260
19.6.cxxTemplates 260
19.7.dbmf 261
19.8.ellLib 262
19.9.epicsRingBytes 262
19.10.epicsRingPointer 263
19.11.epicsTimer 265
19.12. fdmgr 271
19.13.freeList 271
19.14.gpHash 271
19.15.logClient 272
19.16.macLib 273
19.17.misc 274

Chapter 20: libCom OSI libraries 281
20.1.Overview 281
20.2.epicsAssert 282
20.3.epicsEndian 282
20.4.epicsEvent 282

20.5.epicsFindSymbol 284
20.6.epicsGeneralTime 285
20.7.epicsInterrupt 287
20.8.epicsMath 288
20.9.epicsMessageQueue 288
20.10.epicsMutex 290
20.11.epicsStdlib 292
20.12.epicsStdio 292
20.13.epicsStdioRedirect 293
20.14.epicsThread 293
20.15.epicsTime 299
20.16.osiPoolStatus 306
20.17.osiProcess 307
20.18.osiSigPipeIgnore 307
20.19.osiSock.h 308
20.20. Device Support Library 308
20.21.vxWorks Specific routines 311

Chapter 21: Registry 313
21.1.Registry.h 313
21.2.registryRecordType.h 313
21.3.registryDeviceSupport.h 314
21.4.registryDriverSupport.h 314
21.5.registryFunction.h 314
21.6.registerRecordDeviceDriver.c 315
21.7.registerRecordDeviceDriver.pl 315

Chapter 22: Database Structures 317
22.1.Overview 317
22.2.Include Files 317
22.3.Structures 319

Chapter 23: INDEX 321

Chapter 1: Introduction

1.1 Overview

This document describes the core software that resides in an Input/Output Controller (IOC), one of the major components of EPICS. It is intended for anyone developing EPICS IOC databases and/or new record/device/driver support.

The plan of the book is:

Getting Started

A brief description of how to create EPICS support and ioc applications.

EPICS Overview

An overview of EPICS is presented, showing how the IOC software fits into EPICS.

EPICS Build Facility

This chapter, which was written by Janet Anderson, describes the EPICS build facility including directory structure, environment and system requirements, configuration files, Makefiles, and related build tools.

Database Locking, Scanning, and Processing

Overview of three closely related IOC concepts. These concepts are at the heart of what constitutes an EPICS IOC.

Database Definition

This chapter gives a complete description of the format of the files that describe IOC databases. This is the format used by Database Configuration Tools and is also the format used to load databases into an IOC.

IOC Initialization

A great deal happens at IOC initialization. This chapter removes some of the mystery about initialization.

Access Security

Channel Access Security is implemented in IOCs. This chapter explains how it is configured and also how it is implemented.

IOC Test Facilities

Epics supplied test routines that can be executed via the epics or vxWorks shell.

IOC Error Logging

IOC code can call routines that send messages to a system wide error logger.

Record Support

The concept of record support is discussed. This information is necessary for anyone who wishes to provide customized record and device support.

Device Support

The concept of device support is discussed. Device support takes care of the hardware specific details of record support, i.e. it is the interface between hardware and a record support module. Device support can directly access hardware or may interface to driver support.

Driver Support

The concepts of driver support is discussed. Drivers, which are not always needed, have no knowledge of records but just take care of interacting with hardware. Guidelines are given about when driver support, instead of just device support, should be provided.

Static Database Access

This is a library that works on both Host and IOC. For IOCs it works and on initialized or uninitialized EPICS databases.

Runtime Database Access

The heart of the IOC software is the memory resident database. This chapter describes the interface to this database.

Device Support Library

A set of routines are provided for device support modules that use shared resources such as VME address space.

EPICS General Purpose Tasks

General purpose callback tasks and task watchdog.

Database Scanning

Database scan tasks, i.e. the tasks that request records to process.

IOC Shell

The EPICS IOC shell is a simple command interpreter which provides a subset of the capabilities of the vxWorks shell.

libCom

EPICS base includes a subdirectory src/libCom, which contains a number of c and c++ libraries that are used by the other components of base. This chapter describes most of these libraries.

libCom OSI

This chapter describes the libraries in libCom that provide Operating System Independent (OSI) interrfaces used by the rest of EPICS base. LibCom also contains operating system dependent code that implements the OSI interfaces.

Registry

Under vxWorks osiFindGlobalSymbol can be used to dynamically bind to record, device, and driver support. Since on some systems this always returns failure, a registry facility is provided to implement the binding. The basic idea is that any storage meant to be "globally" accessable must be registered before it can be accessed

Database Structures

A description of the internal database structures.

Other than the overview chapter this document describes only core IOC software. Thus it does not describe other EPICS tools which run in an IOC such as the sequencer. It also does not describe Channel Access.

The reader of this manual should also have the following documents:

- *EPICS Record Reference Manual*, Philip Stanley, Janet Anderson and Marty Kraimer
  See the EPICS online wiki for latest version.

- EPICS IOC Software Configuration Management, Marty Kraimer, Andrew Johnson, Janet Anderson, Ralph Lange http://www.aps.anl.gov/asd/controls/epics/EpicsDocumentation/AppDevManuals/iocScm-3.13.2/index.html
- *vxWorks Programmer's Guide*, Wind River Systems
- *vxWorks Reference Manual*, Wind River Systems
- RTEMS C User's Guide, Online Applications Research

1.2 Acknowledgments

The basic model of what an IOC should do and how to do it was developed by Bob Dalesio at LANL/GTA. The principle ideas for Channel Access were developed by Jeff Hill at LANL/GTA. Bob and Jeff also were the principle implementers of the original IOC software. This software (called GTACS) was developed over a period of several years with feedback from LANL/GTA users. Without their ideas EPICS would not exist.

During 1990 and 1991, ANL/APS undertook a major revision of the IOC software with the major goal being to provide easily extendible record and device support. Marty Kraimer (ANL/APS) was primarily responsible for designing the data structures needed to support extendible record and device support and for making the changes needed to the IOC resident software. Bob Zieman (ANL/APS) designed and implemented the UNIX build tools and IOC modules necessary to support the new facilities. Frank Lenkszus (ANL/APS) made extensive changes to the Database Configuration Tool (DCT) necessary to support the new facilities. Janet Anderson developed methods to systematically test various features of the IOC software and is the principal implementer of changes to record support.

During 1993 and 1994, Matt Needes at LANL implemented and supplied the description of fast database links and the database debugging tools.

During 1993 and 1994 Jim Kowalkowski at ANL/APS developed GDCT and also developed the ASCII database instance format now used as the standard format. At that time he also created `dbLoadRecords` and `dbLoadTemplate`.

The `build` utility method resulted in the generation of binary files of UNIX that were loaded into IOCs. As new IOC architectures started being supported this caused problems. During 1995, after learning from an abandoned effort now referred to as `EpicsRX`, the build utilities and binary file (called `default.dctsdr`) were replaced by all ASCII files. The new method provides architecture independence and a more flexible environment for configuring the record/device/driver support. This principle implementer was Marty Kraimer with many ideas contributed by John Winans and Jeff Hill. Bob Dalesio made sure that we did not go too far, i.e. 1) make it difficult to upgrade existing applications and 2) lose performance.

In early 1996 Bob Dalesio tackled the problem of allowing runtime link modification. This turned into a cooperative development effort between Bob and Marty Kraimer. The effort included new code for database to Channel Access links, a new library for lock sets, and a cleaner interface for accessing database links.

In early 1999 the port of iocCore to non vxWorks operating systems was started. The principle developers were Marty Kraimer, Jeff Hill, and Janet Anderson. William Lupton converted the sequencer as well as helping with the posix threads implementation of osiSem and osiThread. Eric Norum provided the port to RTEMS and also contributed the shell that is used on non vxWorks environments. Ralph Lange provided the port to HPUX.

Many other people have been involved with EPICS development, including new record, device, and driver support modules.

Chapter 2: Getting Started

2.1 Introduction

This chapter provides a brief introduction to creating EPICS IOC applications. It contains:

- Instructions for creating, building, and running an example IOC application.
- Instructions for creating, building, and executing example Channel Access clients.
- Briefly describes iocsh, which is a base supplied command shell.
- Describes rules for building IOC components.
- Describes makeBaseApp.pl, which is a perl script that generates files for building applications.
- Briefly discusses vxWorks boot parameters

This chapter will be hard to understand unless you have some familarity with IOC concepts such as record/device/driver support and have had some experience with creating ioc databases. Once you have this experience, this chapter provides most of the information needed to build applications. The example that follows assumes that EPICS base has already been built.

2.2 Example IOC Application

This section explains how to create an example IOC application in a directory <top>, naming the application `myexampleApp` and the ioc directory `iocmyexample`.

2.2.1 Check that `EPICS_HOST_ARCH` is defined

Execute the command:

```
echo $EPICS_HOST_ARCH         (Unix/linux)
```

or

```
set EPICS_HOST_ARCH             (Windows)
```

This should display your workstation architecture, for example `linux-x86` or `win32-x86`. If you get an "Undefined variable" error, you should set EPICS_HOST_ARCH to your host operating system followed by a dash and then your host architecture, e.g. solaris-sparc. The perl script EpicsHostArch.pl in the base/startup directory has been provided to help set EPICS_HOST_ARCH.

2.2.2 Create the example application

The following commands create an example application.

```
mkdir <top>
```

```
cd <top>
<base>/bin/<arch>/makeBaseApp.pl -t example myexample
<base>/bin/<arch>/makeBaseApp.pl -i -t example myexample
```

Here, <arch> indicates the operating system architecture of your computer. For example, solaris-sparc. The last command will ask you to enter an architecture for the IOC. It provides a list of architectures for which base has been built.

The full path name to <base> (an already built copy of EPICS base) must be given. Check with your EPICS system administrator to see what the path to your <base> is. For example:

```
/home/phoebus/MRK/epics/base/bin/linux-x86/makeBaseApp.pl ...
```

Windows Users Note: Perl scripts are invoked with the command perl <scriptname> on win95/NT. Perl script names are case sensitive. For example to create an application on WIN95/NT:

```
perl C:\epics\base\bin\win32-x86\makeBaseApp.pl -t example myexample
```

2.2.3 Inspect files

Spend some time looking at the files that appear under <top>. Do this BEFORE building. This allows you to see typical files which are needed to build an application without seeing the files generated by make.

2.2.4 Sequencer Example

The sequencer is now supported as an unbundled product. The example includes an example state notation program; sncExample.stt. As created by makeBaseApp the example is not built or executed.

Before sncExample.st can be built, the sequencer must be built using the same version of base that the example uses.

To build sncExample edit the following files:

- configure/RELEASE - Set SNCSEQ to the location of the sequencer.
- iocBoot/iocmyexample/st.cmd - Remove the comment character # from
  #seq sncExample,"user=<user"

The Makefile contains commands for building sncExample as a component of the ioc application and as a standalone application, i.e. an application that does not use an epics database.

2.2.5 Build

In directory <top> execute the command

```
make
```

NOTE: On systems where GNU make is not the default another command is required, e.g. `gnumake`, `gmake`, etc. See you EPICS system administrator.

2.2.6 Inspect files

This time you will see the files generated by make as well as the original files.

2.2.7 Run the ioc example

The example can be run on vxWorks, RTEMS, or on a supported host.

- On a host, e.g. linux or solarius
  - `cd <top>/iocBoot/iocmyexample`
  - `../../bin/linux-x86/myexample st.cmd`
- vxWorks/RTERMS - Set your boot parameters as described at the end of this chapter and then boot the ioc.

After the ioc is started try some of the shell commands (e.g. `dbl` or `dbpr <recordname>`) described in chapter "IOC Test Facilities". In particular run `dbl` to get a list of the records.

The iocsh command interpreter used on non-vxWorks IOCs provides a help facility. Just type:

```
help
```

or

```
help <cmd>
```

where `<cmd>` is one of the commands displayed by help. The help command accepts wildcards, so

```
help db*
```

will provide information on all commands beginning with the characters db.

On vxWorks the help facility is available by first typing:

```
iocsh
```

2.3 Channel Access Host Example

An example host example can be generated by:

```
cd <mytop>
<base>/bin/<arch>/makeBaseApp.pl -t caClient caClient
make
```

(or gnumake, as required by your operating system)

Two channel access examples are provided.

- caExample - This example accepts a pvname, connects and reads the current value for pvname, displays the result and terminates. To run this example just type.
  `<mytop>/bin/<hostarch>/caExample <pvname>`
  where
  - `<mytop>` is the full path name to your application top directory.
  - `<hostarch>` is your host architecture.
  - `<pvname>` is one of the record names displayed by the `dbl` ioc shell command.
- caMonitor - This example accepts a filename, which contains a list of pvnames, each appearing on a separate line. It connects to each pv and issues monitor requests. It displays messages for all channel access events, connection events, etc.

2.4 iocsh

Because the vxWorks shell is only available on vxWorks, EPICS base provides iocsh. In the main program it can be invoked as follows:

```
iocsh("filename")
```

or

```
iocsh(0)
```

If the argument is a filename, the commands in the file are executed and iocsh returns. If the argument is 0 then iocsh goes into interactive mode, i.e. it prompts for and executes commands until an exit command is issued.

This shell is described in more detail in Chapter 18, “IOC Shell” on page 247

On vxWorks iocsh is not automatically started. It can be started by just giving the following command to the vxWorks shell.

```
iocsh
```

To get back to the vxWorks shell just say

```
exit
```

2.5 Building IOC components

Detailed build rules are given in chapter "Epics Build Facility". This section describes methods for building most components needed for IOC applications. It uses excerpts from the myexampleApp/src/Makefile that is generated by makeBaseApp.

The following two types of applications can be built:

- Support applications
  These are applications meant for use by ioc applications. The rules described here install things into one of the following directories that are created just below <top>:
  - include
    C include files are installed here. Either header files supplied by the application or header files generated from xxxRecord.dbd or xxxMenu.dbd files.
  - dbd
    Each file contains some combination of `include`, `recordtype`, `device`, `driver`, and `registrar` database definition commands. The following are installed:
    - xxxRecord.dbd, xxxMenu.dbd files
    - An arbitrary xxx.dbd file
    - ioc applications install a file yyy.dbd generated from file yyyInclude.dbd.
  - db
    Files containing record instance definitions.
  - lib/<arch>
    All source modules are compiled and placed in shared or static library (win32 dll)
- IOC applications
  These are applications loaded into actual IOCs.

2.5.1 Binding to IOC components

Because many IOC components are bound only during ioc initialization, some method of linking to the appropriate shared and/or static libraries must be provided. The method used for IOCs is to generate, from an xxxInclude.dbd file, a C++ program that forces a reference to the appropriate library modules. The following keywords for database definitions are used for this purpose:

```
recordtype
device
driver
```

```
registrar
variable
function
```

The method also requires that IOC components call an appropriate epicsExport function. Each such component must contain the statement: (NOTE: This must be the last include file in the source module.

```
#include <epicsExport.h>
```

Each record support module must contain a statement like:

```
epicsExportAddress(rset,xxxRSET);
```

Each device support module must contain a statement like:

```
epicsExportAddress(dset,devXxxSoft);
```

Each driver support module must contain a statement like:

```
epicsExportAddress(drvet,drvGpib);
```

The keyword `variable` provides access to integer or double variables, e.g. debugging variables. The xxxInclude.dbd file can contain definitions like:

```
variable(asCaDebug,int)
variable(myDefaultTimeout,double)
```

The code that defines the variables must include code like:

```
int asCaDebug = 0;
epicsExportAddress(int,asCaDebug);
```

The keyword `registrar` signifies that the epics component supplies a C function that has the prototype:

```
    typedef void (*REGISTRAR)(void);
```

This function normally registers things described in chapter "Registry". The myexampleApp provides an example set of functions for a subroutine record. It contains the statements:

```
static registryFunctionRef mySubRef[] = {
    {"mySubInit",(REGISTRYFUNCTION)mySubInit},
    {"mySubProcess",(REGISTRYFUNCTION)mySubProcess}
};

static void mySub(void)
{
    registryFunctionRefAdd(mySubRef,NELEMENTS(mySubRef));
}
epicsExportRegistrar(mySub);
```

`epicsExportRegistrar` can also be used to register iocsh commands, etc.

The registrar function in the preceding example does nothing but register functions. Functions can also be registered by using the `epicsRegisterFunction` macro in the C source file containing the function and the `function` statement in the application database description file. The example could thus be simplified to:

```
epicsRegisterFunction(mySubInit);

epicsRegisterFunction(mySubProcess);
```

NOTE: The epicsExport system requires that the `epicsExportAddress`, `epicsExportRegistrar` or `epicsRegisterFunction` statement appear in the same source module as whatever it exports.

2.5.2 Makefile rules

2.5.2.1 Building a support application.

```
# xxxRecord.h will be created from xxxRecord.dbd
DBDINC += xxxRecord
DBD += myexampleSupport.dbd

LIBRARY_IOC += myexampleSupport

myexampleSupport_SRCS += xxxRecord.c
myexampleSupport_SRCS += devXxxSoft.c
myexampleSupport_SRCS += dbSubExample.c

myexampleSupport_LIBS += $(EPICS_BASE_IOC_LIBS)
```

The DBDINC rule looks for a file xxxRecord.dbd. From this file a file xxxRecord.h is created and installed into <top>/include

The DBD rule finds myexampleSupport.dbd in the source directory and installs it into <top>/dbd

The LIBRARY_IOC statement states that a shared/static library should be created and installed into <top>/lib/<arch>.

The myexampleSupport_SRCS statements name all the source files that are compiled and put into the library.

The above statements are all that is needed for building many support applications.

2.5.2.2 Building the IOC application

The following statements build the IOC application:

```
PROD_IOC = myexample

DBD += myexample.dbd

# myexample.dbd will be made up from these files:
myexample_DBD += base.dbd
myexample_DBD += xxxSupport.dbd
myexample_DBD += dbSubExample.dbd

# <name>_registerRecordDeviceDriver.cpp will be created from <name>.dbd
myexample_SRCS += myexample_registerRecordDeviceDriver.cpp
myexample_SRCS_DEFAULT += myexampleMain.cpp
myexample_SRCS_vxWorks += -nil-

# Add locally compiled object code
myexample_SRCS += dbSubExample.c

#The following adds support from base/src/vxWorks
myexample_OBJS_vxWorks += $(EPICS_BASE_BIN)/vxComLibrary

myexample_LIBS += myexampleSupport
myexample_LIBS += $(EPICS_BASE_IOC_LIBS)
```

PROD_IOC gives that name of the ioc application, which is named `myexample`.

The DBD definition myexample.dbd will cause build rules to create the database definition include file myexampleInclude.dbd from files in the myexample_DBD definition. For each filename in the myexample_DBD definition, the created myexampleInclude.dbd will contain an include statement for that filename. The created myexampleInclude.dbd file will contain the following lines.

```
include "base.dbd"
include "xxxSupport.dbd"
include "dbSubExample.dbd"
```

When the DBD build rules find the created file `myexampleInclude.dbd`, the rules then call dbExpand which reads `myexampleInclude.dbd` to generate file `myexample.dbd`, and install it into `<top>/dbd.`

An arbitrary number of `myexample_SRCS` statements can be given. One, `myexample_registerRecordDeviceDriver.cpp,` is special. When this is seen the following happens:

- A perl script `registerRecordDeviceDriver.pl` is executed. Taking myexample.dbd as input it generates `myexample_registerRecordDeviceDriver.cpp`.

2.6 makeBaseApp

makeBaseApp is a perl script that creates application areas. It can create the following:

- <top>/Makefile
- <top>/configure - This directory contains the files needed by the EPICS build system.
- <top>/xxxApp - A set of directories and associated files for a major sub-module.
- <top>/iocBoot - A subdirectory and associated files.
- <top>/iocBoot/iocxxx - A subdirectory and files for a single ioc.

makeBaseApp creates directories and then copies template files into the newly created directories while expanding macros in the template files. EPICS base provides two sets of template files: simple and example. These are meant for simple applications. Each site, however, can create its own set of template files which may provide additional functionality. This section describes the functionality of makeBaseApp itself, the next section provides details about the simple and example templates.

2.6.1 Usage

makeBaseApp has four possible forms of command line:

```
<base>/bin/<arch>/makeBaseApp.pl -h
```

Provides help.

```
<base>/bin/<arch>/makeBaseApp.pl -l [options]
```

List the application templates available. This invocation does not alter the current directory.

```
<base>/bin/<arch>/makeBaseApp.pl [-t type] [options] app ...
```

Create application directories.

```
<base>/bin/<arch>/makeBaseApp.pl -i -t type [options] ioc ...
```

Create ioc boot directories.

Options for all command forms:

```
-b base
```

Provides the full path to EPICS base. If not specified, the value is taken from the EPICS_BASE entry in config/RELEASE. If the config directory does not exist, the path is taken from the command-line that was used to invoke makeBaseApp

`-T template`
: Set the template top directory (where the application templates are). If not specified, the template path is taken from the TEMPLATE_TOP entry in config/RELEASE. If the config directory does not exist the path is taken from the environment variable EPICS_MBA_TEMPLATE_TOP, or if this is not set the templates from EPICS base are used.

`-d`
: Verbose output (useful for debugging)

Arguments unique to `makeBaseApp.pl [-t type] [options] app ...`:

`app`
: One or more application names (the created directories will have " App" appended to this name)

`-t type`
: Set the template type (use the -l invocation to get a list of valid types). If this option is not used, type is taken from the environment variable EPICS_MBA_DEF_APP_TYPE, or if that is not set the values "default" and then "example " are tried.

Arguments unique to `makeBaseApp.pl -i [options] ioc ...`:

`ioc`

One or more IOC names (the created directories will have "ioc " prepended to this name).

`-a arch`
: Set the IOC architecture (e.g. vxWorks-68040). If `-a arch` is not specified, you will be prompted.

2.6.2 Environment Variables:

`EPICS_MBA_DEF_APP_TYPE`
: Application type you want to use as default

`EPICS_MBA_TEMPLATE_TOP`
: Template top directory

2.6.3 Description

To create a new <top> issue the commands:

```
mkdir <top>
cd <top>
<base>/bin/<arch>/makeBaseApp.pl -t <type> <app> ...
<base>/bin/<arch>/makeBaseApp.pl -i -t <type> <ioc> ...
```

makeBaseApp does the following:

- EPICS_BASE is located by checking the following in order:
  - If the -b option is specified it is used.
  - If a `<top>/config/RELEASE` file exists and defines a value for `EPICS_BASE` it is used.
  - It is obtained from the invocation of makeBaseApp. For this to work, the full path name to the makeBaseApp.pl script in the EPICS base release you are using must be given.
- TEMPLATE_TOP is located in a similar fashion:
  - If the -T option is specified it is used.
  - If a `<top>/config/RELEASE` file exists and defines a value for TEMPLATE_TOP it is used.

    - If EPICS_MBA_TEMPLATE_TOP is defined it is used.
    - It is set equal to `<epics_base>/templates/makeBaseApp/top`
- If -l is specified the list of application types is listed and makeBaseApp terminates.
- If -i is specified and -a is not then the user is prompted for the IOC architecture.
- The application type is determined by checking the following in order:
    - If -t is specified it is used.
    - If EPICS_MBA_DEF_APP_TYPE is defined it is used.
    - If a template `defaultApp` exists, the application type is set equal to default.
    - If a template `exampleApp` exists, the application type is set equal to example.
- If the application type is not found in TEMPLATE_TOP, makeBaseApp issues an error and terminates.
- If Makefile does not exist, it is created.
- If directory `configure` does not exist, it is created and populated with all the `configure` files.
- If -i is specified:
    - If directory `iocBoot` does not exist, it is created and the files from the template boot directory are copied into it.
    - For each `<ioc>` specified on the command line a directory iocBoot/ioc<ioc> is created and populated with the files from the template (with ReplaceLine() tag replacement, see below).
- If -i is NOT specified:
    - For each `<app>` specified on the command line a directory <app>App is created and populated with the directory tree from the template (with ReplaceLine() tag replacement, see below).

2.6.4 Tag Replacement within a Template

When copying certain files from the template to the new application structure, makeBaseApp replaces some predefined tags in the name or text of the files concerned with values that are known at the time. An application template can extend this functionality as follows:

- Two perl subroutines are defined within makeBaseApp:
    - ReplaceFilename - This substitutes for the following in names of any file taken from the templates.
        - _APPNAME_
        - _APPTYPE_
    - ReplaceLine - This substitutes for the following in each line of each file taken from the templates:
        - _USER_
        - _EPICS_BASE_
        - _ARCH_
        - _APPNAME_
        - _APPTYPE_
        - _TEMPLATE_TOP_
        - _IOC_
- If the application type directory has a file named `Replace.pl` , it can:
    - Replace one or both of the above subroutines with its own versions.
    - Addasubroutine `ReplaceFilenameHook($file)` which is called at the end of `ReplaceFilename`.
    - Add a subroutine `ReplaceLineHook($line)` which is called at the end of `ReplaceLine`.
    - Include other code which is run after the command line options are interpreted.

2.6.5 makeBaseApp templetes provided with base

2.6.5.1 support

This creates files appropriate for building a support application.

2.6.5.2 ioc

Without the -i option, this creates files appropriate for building an ioc application, With the -i option it creates an ioc boot directory.

2.6.5.3 example

Without the -i option it creates files for running an example. Both a support and an ioc application are built. With the -i option it creates an ioc boot directory that can be used to run the example.

2.6.5.4 caClient

This builds two Channel Access clients.

2.6.5.5 caServer

This builds an example Portable Access Server.

2.7 vxWorks boot parameters

The vxWorks boot parameters are set via the console serial port on your IOC. Life is much easier if you find out how to connect the serial port to a window on your workstation.

The vxWorks boot parameters look something like the following:

```
boot device            : xxx
processor number       : 0
host name              : xxx
file name              : <full path to board support>/vxWorks
inet on ethernet (e)   : xxx.xxx.xxx.xxx:<netmask>
host inet (h)          : xxx.xxx.xxx.xxx
user (u)               : xxx
ftp password (pw)      : xxx
flags (f)              : 0x0
target name (tn)       : <hostname for this inet address>
startup script (s)     : <top>/iocBoot/iocmyexample/st.cmd
```

The actual values for each field are site and IOC dependent. Two fields that you can change at will are the vxWorks boot image and the location of the startup script.

Note that the full path name for the correct board support boot image must be specified. If bootp is used the same information will need to be placed in the bootp host's configuration database instead.

When your boot parameters are set properly, just press the reset button on your IOC, or use the @ command to commence booting. You will find it VERY convenient to have the console port of the IOC attached to a scrolling window on your workstation.

2.8 RTEMS boot procedure

RTEMS uses the vendor-supplied bootstrap mechanism so the method for booting an IOC depends upon the hardware in use.

2.8.1 Booting from a BOOTP/DHCP/TFTP server

Many boards can use BOOTP/DHCP to read their network configuration and then use TFTP to read the applicaion program. RTEMS can then use TFTP or NFS to read startup scripts and configuration files. If you are using TFTP to read the startup scripts and configuration files you must install the EPICS application files on your TFTP server as follows:

- Copy all db/xxx files to <tftpbase>/epics/<target_hostname>/db/xxx.
- Copy all dbd/xxx files to <tftpbase>/epics/<target_hostname>/dbd/xxx.
- Copy the st.cmd script to <tftpbase>/epics/<target_hostname>/st.cmd.

Use DHCP site-specific option 129 to specify the path to the IOC startup script.

2.8.2 Motorola PPCBUG boot parameters

Motrola single-board computers which employ PPCBUG should have their 'NIOT' parameters set up like:

```
Controller LUN =00
Device LUN     =00
Node Control Memory Address =FFE10000
Client IP Address      ='Dotted-decimal' IP address of IOC
Server IP Address      ='Dotted-decimal' IP address of TFTP/NFS server
Subnet IP Address Mask ='Dotted-decimal' IP address of subnet mask (255.255.255.0 for class C subnet)
Broadcast IP Address   ='Dotted-decimal' IP address of subnet broadcast address
Gateway IP Address     ='Dotted-decimal' IP address of network gateway (0.0.0.0 if none)
Boot File Name         =Path to application bootable image (..../bin/RTEMS-mvme2100/test.boot)
Argument File Name     =Path to application startup script (..../iocBoot/ioctest/st.cmd)
Boot File Load Address         =001F0000 (actual value depends on BSP)
Boot File Execution Address    =001F0000 (actual value depends on BSP)
Boot File Execution Delay      =00000000
Boot File Length               =00000000
Boot File Byte Offset          =00000000
BOOTP/RARP Request Retry       =00
TFTP/ARP Request Retry         =00
Trace Character Buffer Address =00000000
```

2.8.3 Motorola MOTLOAD boot parameters

Motrola single-board computers which employ MOTLOAD should have their network 'Global Environment Variable' parameters set up like:

`mot-/dev/enet0-cipa=`'Dotted-decimal' IP address of IOC
`mot-/dev/enet0-sipa=`'Dotted-decimal' IP address of TFTP/NFS server
`mot-/dev/enet0-snma=`'Dotted-decimal' IP address of subnet mask (255.255.255.0 for class C subnet)
`mot-/dev/enet0-gipa=`'Dotted-decimal' IP address of network gateway (omit if none)
`mot-/dev/enet0-file=`Path to application bootable image (..../bin/RTEMS-mvme5500/test.boot)
`rtems-client-name=`IOC name (`mot-/dev/enet0-cipa` will be used if this parameter is missing)
`rtems-dns-server=`'Dotted-decimal' IP address of domain name server (omit if none)

`rtems-dns-domainname=`Domain name (if this parameter is omitted the compiled-in value will be used)
`epics-script=`Path to application startup script (..../iocBoot/ioctest/st.cmd)

The `mot-script-boot` parameter should be set up like:

```
tftpGet -a4000000 -cxxx -sxxx -mxxx -gxxx -d/dev/enet0 -f..../bin/RTEMS-mvme5500/test.boot
netShut
go -a4000000
```

where the -c, -s, -m and -g values should match the cipa, sipa, snma and gipa values, respectively and the -f value should match the file value.

2.8.4 RTEMS NFS access

For IOCs which use NFS for remote file access the EPICS initialization code uses the startup script pathname to determine the parameters for the initial NFS mount. If the startup script pathname begins with a '`/`' the first component of the pathname is used as both the server path and the local mount point. If the startup script pathname does not begin with a '`/`' the first component of the pathname is used as the local mount point and the server path is "`/tftpboot/`" followed by the first component of the pathname. This allows the NFS client used for EPICS file access and the TFTP client used for bootstrapping the application to have a similar view of the remote filesystem.

2.8.5 RTEMS 'Cexp'

The RTEMS 'Cexp' add-on package provides the ability to load object modules at application run-time. If your RTEMS build includes this package you can load RTEMS IOC applications in the same fashion as vxWorks IOC applications.

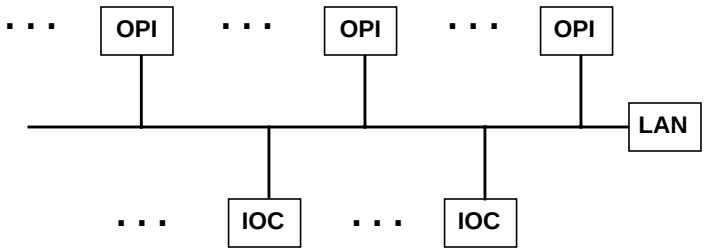
Chapter 3: EPICS Overview

3.1 What is EPICS?

EPICS consists of a set of software components and tools that Application Developers use to create a control system. The basic components are:

- **OPI**: Operator Interface. This is a workstation which can run various EPICS tools.
- **IOC**: Input/Output Controller. Any platform that can support EPICS run time databases together with the other software components described in the manual. One example is a workstation. Another example is a VME/VXI based system using vxWorks or RTEMS as the realtime operating system.
- **LAN**: Local Area Network. This is the communication network which allows the IOCs and OPIs to communicate. EPICS provides a software component, Channel Access, which provides network transparent communication between a Channel Access client and an arbitrary number of Channel Access servers.

A control system implemented via EPICS has the following physical structure.



The rest of this chapter gives a brief description of EPICS:

- **Basic Attributes**: A few basic attributes of EPICS.
- **Platforms**: The vendor supplied Hardware and Software platforms EPICS supports.
- **IOC Software**: EPICS supplied IOC software components.
- **Channel Access**: EPICS software that supports network independent access to IOC databases.
- **OPI Tools**: EPICS supplied OPI based tools.
- **EPICS Core**: A list of the EPICS core software, i.e. the software components without which EPICS will not work.

3.2 Basic Attributes

The basic attributes of EPICS are:

- **Tool Based**: EPICS provides a number of tools for creating a control system. This minimizes the need for custom coding and helps ensure uniform operator interfaces.
- **Distributed**: An arbitrary number of IOCs and OPIs can be supported. As long as the network is not saturated, no single bottle neck is present. A distributed system scales nicely. If a single IOC becomes saturated, its functions can be spread over several IOCs. Rather than running all applications on a single host, the applications can be spread over many OPIs.
- **Event Driven**: The EPICS software components are all designed to be event driven to the maximum extent possible. For example, rather than having to poll IOCs for changes, a Channel Access client can request that it be notified when a change occurs. This design leads to efficient use of resources, as well as, quick response times.
- **High Performance**: A SPARC based workstation can handle several thousand screen updates a second with each update resulting from a Channel Access event. A 68040 IOC can process more than 6,000 records per second, including generation of Channel Access events.

3.3 Hardware - Software Platforms (Vendor Supplied)

EPICS core components (including IOC components) run on a wide range of systems. Currently this includes the following platforms, but new operating system platforms can be easily supported if they have reasonable support for sockets and threads. Currently most 32 bit processors are supported. Some limited testing has been performed on 64 bit processors.

3.3.1 OPI

Platforms

- Unix based Workstations: Well supported platforms include SOLARIS, and HP-UX
- Linux
- Darwin, i.e. Mac OS 10
- Windows NT
- Limited support for VMS

3.3.2 LAN

Hardware

- Ethernet (most flavors)

Software

- TCP/IP protocols via sockets

3.3.3 IOC

Hardware

- VME/VXI bus and crates
    - Various VME modules (ADCs, DAC, Binary I/O, etc.)
    - Allen Bradley Scanner (Most AB I/O modules)
    - GPIB devices

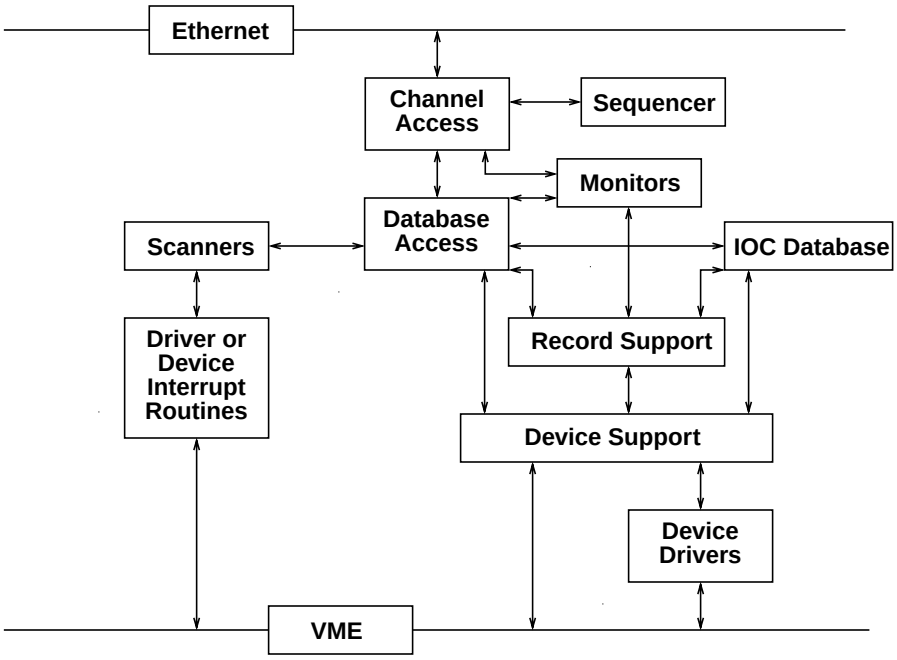
    - BITBUS devices
    - CAMAC
    - CANBUS
- Motorola 68K
- Intel
- AMD Athelon
- PowerPC
- Sun Sparc
- HP

Software

- vxWorks operating system
    - Real time kernel
    - Extensive “Unix like” libraries
- RTEMS
- Linux
- Unix
- Darwin
- win32

3.4 IOC Software Components

An IOC contains the following EPICS supplied software components.



- **IOC Database**: The memory resident database plus associated data structures.

- **Database Access**: Database access routines. With the exception of record and device support, all access to the database is via the database access routines.
- **Scanners**: The mechanism for deciding when records should be processed.
- **Record Support**: Each record type has an associated set of record support routines.
- **Device Support**: Each record type can have one or more sets of device support routines.
- **Device Drivers**: Device drivers access external devices. A driver may have an associated driver interrupt routine.
- **Channel Access**: The interface between the external world and the IOC. It provides a network independent interface to database access.
- **Monitors**: Database monitors are invoked when database field values change.
- **Sequencer**: A finite state machine.

Let's briefly describe the major components of the IOC and how they interact.

3.4.1 IOC Database

The heart of each IOC is a memory resident database together with various memory resident structures describing the contents of the database. EPICS supports a large and extensible set of record types, e.g. `ai` (Analog Input), `ao` (Analog Output), etc.

Each record type has a fixed set of fields. Some fields are common to all record types and others are specific to particular record types. Every record has a record name and every field has a field name. The first field of every database record holds the record name, which must be unique across all IOCs that are attached to the same TCP/IP subnet.

Data structures are provided so that the database can be accessed efficiently. Most software components, because they access the database via database access routines, do not need to be aware of these structures.

3.4.2 Database Access

With the exception of record and device support, all access to the database is via the channel or database access routines. See Chapter 15, "Runtime Database Access" on page 211 for details.

3.4.3 Database Scanning

Database scanning is the mechanism for deciding when to process a record. Five types of scanning are possible: Periodic, Event, I/O Event, Passive and Scan Once.

- **Periodic**: A request can be made to process a record periodically. A number of time intervals are supported.
- **Event**: Event scanning is based on the posting of an event by any IOC software component. The actual subroutine call is:
  ```
  post_event(event_num)
  ```
- **I/O Event**: The I/O event scanning system processes records based on external interrupts. An IOC device driver interrupt routine must be available to accept the external interrupts.
- **Passive**: Passive records are processed as a result of linked records being processed or as a result of external changes such as Channel Access puts.
- **Scan Once**: In order to provide for caching puts, The scanning system provides a routine `scanOnce` which arranges for a record to be processed one time.

3.4.4 Record Support, Device Support and Device Drivers

Database access needs no record-type specific knowledge, because each record-type has its associated record support module. Therefore, database access can support any number and type of records. Similarly, record support contains no device specific knowledge, giving each record type the ability to have any number of independent device support modules. If the method of accessing the piece of hardware is more complicated than what can be handled by device support, then a device driver can be developed.

Record types *not* associated with hardware do not have device support or device drivers.

The IOC software is designed so that the database access layer knows nothing about the record support layer other than how to call it. The record support layer in turn knows nothing about its device support layer other than how to call it. Similarly the only thing a device support layer knows about its associated driver is how to call it. This design allows a particular installation and even a particular IOC within an installation to choose a unique set of record types, device types, and drivers. The remainder of the IOC system software is unaffected.

Because an Application Developer can develop record support, device support, and device drivers, these topics are discussed in greater detail in later chapters.

Every record support module must provide a record processing routine to be called by the database scanners. Record processing consists of some combination of the following functions (particular records types may not need all functions):

- **Input**: Read inputs. Inputs can be obtained, via device support routines, from hardware, from other database records via database links, or from other IOCs via Channel Access links.
- **Conversion**: Conversion of raw input to engineering units or engineering units to raw output values.
- **Output**: Write outputs. Output can be directed, via device support routines, to hardware, to other database records via database links, or to other IOCs via Channel Access links.
- **Raise Alarms**: Check for and raise alarms.
- **Monitor**: Trigger monitors related to Channel Access callbacks.
- **Link**: Trigger processing of linked records.

3.4.5 Channel Access

Channel Access is discussed in the next section.

3.4.6 Database Monitors

Database monitors provide a callback mechanism for database value changes. This allows the caller to be notified when database values change without constantly polling the database. A mask can be set to specify value changes, alarm changes, and/or archival changes.

At the present time only Channel Access uses database monitors. No other software should use the database monitors. The monitor routines will not be described because they are of interest only to Channel Access.

3.5 Channel Access

Channel Access provides network transparent access to IOC databases. It is based on a client/ server model. Each IOC provides a Channel Access server which is willing to establish communication with an arbitrary number of clients. Channel Access client services are available on both OPIs and IOCs. A client can communicate with an arbitrary number of servers.

3.5.1 Client Services

The basic Channel Access client services are:

- **Search**: Locate the IOCs containing selected process variables and establish communication with each one.
- **Get**: Get value plus additional optional information for a selected set of process variables.
- **Put**: Change the values of selected process variables.
- **Add Event**: Add a change of state callback. This is a request to have the server send information only when the associated process variable changes state. Any combination of the following state changes can be requested: change of value, change of alarm status and/or severity, and change of archival value. Many record types provide hysteresis factors for value changes.

In addition to requesting process variable values, any combination of the following additional information may be requested:

- **Status**: Alarm status and severity.
- **Units**: Engineering units for this process variable.
- **Precision**: Precision with which to display floating point numbers.
- **Time**: Time when the record was last processed.
- **Enumerated**: A set of ASCII strings defining the meaning of enumerated values.
- **Graphics**: High and low limits for producing graphs.
- **Control**: High and low control limits.
- **Alarm**: The alarm `HIHI`, `HIGH`, `LOW`, and `LOLO` values for the process variable.

It should be noted that Channel Access does ***not*** provide access to database records as records. This is a deliberate design decision. This allows new record types to be added without impacting any software that accesses the database via Channel Access, and it allows a Channel Access client to communicate with multiple IOCs having differing sets of record types.

3.5.2 Search Server

Channel Access provides an IOC resident server which waits for Channel Access search messages. These are generated when a Channel Access client (for example when an Operator Interface task starts) searches for the IOCs containing process variables the client uses. This server accepts all search messages, checks to see if any of the process variables are located in this IOC, and, if any are found, replies to the sender with and “I have it” message.

3.5.3 Connection Request Server

Once the process variables have been located, the Channel Access client issues connection requests for each IOC containing process variables the client uses. The connection request server, in the IOC, accepts the request and establishes a connection to the client. Each connection is managed by two separate tasks: `ca_get` and `ca_put`. The `ca_get` and `ca_put` requests map to `dbGetField` and `dbPutField` database access requests. `ca_add_event` requests result in database monitors being established. Database access and/or record support routines trigger the monitors via a call to `db_post_event`.

3.5.4 Connection Management

Each IOC provides a connection management service. When a Channel Access server fails (e.g. its IOC crashes) the client is notified and when a client fails (e.g. its task crashes) the server is notified. When a client fails, the server breaks the connection. When a server crashes, the client automatically re-establishes communication when the server restarts.

3.6 OPI Tools

EPICS provides a number of OPI based tools. These can be divided into two groups based on whether or not they use Channel Access. Channel Access tools are real time tools, i.e. they are used to monitor and control IOCs.

3.6.1 Examples of channel Access Tools

A large number of Channel Access tools have been developed. The following are some representative examples.

- **EDM -** Extensible Display Manager. The newest display manager/editor for EPICS.
- **MEDM**: Motif version of combined display manager and display editor.
- **DM**: Display Manager. Reads one or more display list files created by EDD, establishes communication with all necessary IOCs, establishes monitors on process variables, accepts operator control requests, and updates the display to reflect all changes.
- **stripTool -** General purpose stripchart tool.
- **ALH**: Alarm Handler. General purpose alarm handler driven by an alarm configuration file.
- **AR**: Archiver. General purpose tool to acquire and save data from IOCs.
- **Sequencer**: Runs in an IOC and emulates a finite state machine.
- **BURT**: Backup and Restore Tool. General purpose tool to save and restore Channel Access channels. The tool can be run via Unix commands or via a Graphical User Interface.
- **KM**: Knob Manager - Channel Access interface for the sun dials (a set of 8 knobs)
- **PROBE**: Allows the user to monitor and/or change a single process variable specified at run time.
- **CAMATH**: Channel Access interface for Mathematica.
- **CAWINGZ**: Channel Access interface for Wingz.
- **IDL/PVWAVE** Channel Access Interfaces exist for these products.
- **TCL/TK** Channel Access Interface for these products.
- **CDEV -** A library designed to provide a standard API to one or more underlying packages, typically control system interfaces. CDEV provides a Channel Access service.

3.6.2 Examples of other OPI Tools

- **VDCT** - A Java based database configuration tool which is quickly becoming the recommended database configuration tool.
- **JDCT:** Java Database Configuration Tool. A JAVA based tool for creating run time databases.
- **GDCT**: Graphical Database Configuration Tool. Used to create a run time database for an IOC. This is no longer being developed since it is based on an open source software system called unidraw, which is no longer being supported.
- **EDD**: Display Editor. This tool is used to create a display list file for the Display Manager. A display list file contains a list of static, monitor, and control elements. Each monitor and control element has an associated process variable.
- **SNC**: State Notation Compiler. It generates a C program that represents the states for the IOC Sequencer tool.
- **Database Tools -** Tools are provided which generate C include files from menu and record type database definition files.
- **Source/Release**: EPICS provides a Source/Release mechanism for managing EPICS.

3.7 EPICS Core Software

EPICS consists of a set of core software and a set of optional components. The core software, i.e. the components of EPICS without which EPICS would not function, are:

- Channel Access - Client and Server software
- IOC Database
- Scanners
- Monitors
- Database Definition Tools
- Source/Release

All other software components are optional. Of course, any application developer would be crazy to ignore tools such as MEDM (or EDD/DM). Likewise an application developer would not start from scratch developing record and device support. Most OPI tools do not, however, have to be used. Likewise any given record support module, device support module, or driver could be deleted from a particular IOC and EPICS will still function.

Chapter 4: EPICS Build Facility

Janet Anderson is the author of this chapter.

4.1 Overview

This chapter describes the EPICS build facility including directory structure, environment and system requirements, configuration files, Makefiles, and related build tools.

4.1.1 <top> Directory structure

EPICS software can be divided into multiple <top> areas. Examples of <top> areas are EPICS base itself, EPICS extensions, and simple or complicated IOC applications. Each <top> may be maintained separately. Different <top> areas can be on different releases of external software such as EPICS base releases.

A <top> directory has the following directory structure:

```
<top>/
    Makefile
    configure/
    dir1/
    dir2/
    ...
```

where configure is a directory containing build configuration files and a Makefile and where dir1, dir2, ... are user created subdirectory trees with Makefiles and source files to be built. Because the build rules allow make commands like "make install.vxWorks-68040", subdirectory names within a <top> directory structure may not contain a period"." character.

4.1.2 Install Directories

Files installed during the build are installed into subdirectories of an installation directory which defaults to $(TOP), the <top> directory. For base the default value can be changed in the configure/CONFIG_SITE file. For extensions and applications the default value can be overridden in the configure/CONFIG file. The installation directories for the EPICS components are:

- **INSTALL_LOCATION** - base.
- **INSTALL_LOCATION_EXTENSIONS** - extensions
- **INSTALL_LOCATION_APP** - applications

The following subdirectories may also exist in the installation directory. They are created by the build and contain the installed build components.

- **dbd** - Directory into which Database Definition files are installed.
- **include** - The directory into which C header files are installed. These header files may be generated from menu and record type definitions.

- **bin** - This directory contains a subdirectory for each host architecture and for each target architecture. These are the directories into which executables, binaries, etc. are installed.
- **lib** - This directory contains a subdirectory for each host architecture. These are the directories into which libraries are installed.
- **db** - This is the directory into which database record instance, template, and substitution files are installed.
- **html** - This is the directory into which html documentation is installed.
- **templates** - This is the directory into which template files are installed.
- **javalib** - This is the directory into which java class files and jar files are installed.
- **configure** - The directory into which configure files are installed (if INSTALL_LOCATION not equal TOP).

4.1.3 Elements of build system

The main ingredients of the build system are:

- A set of configuration files and tools provided in the EPICS base/configure directory
- A corresponding set of configuration files in the <top>/configure directory of a non-base <top> directory structure to be built. The makeBaseApp.pl and makeBaseExt.pl scripts create these configuration files. Many of these files just include a file of the same name from the base/configure directory.
- Makefiles in each directory of the <top> directory structure to be built

4.1.4 Features

The principal features of the build system are:

- Requires a single Makefile in each directory of a <top> directory structure
- Supports both host os vendor's native compiler and GNU compiler
- Supports building multiple types of software (libraries, executables, databases, java class files, etc.) stored in a single directory tree.
- Supports building EPICS base, extensions, and IOC applications.
- Supports multiple host and target operating system - architecture combinations.
- Allows builds for all hosts and targets within a single <top> source directory tree.
- Allows sharing of components such as special record/device/drivers across <top> areas.
- gnumake is the only command used to build a <top> area.

4.1.5 Multiple host and target systems

You can build on multiple host systems and for multiple cross target systems using a single EPICS directory structure. The intermediate and binary files generated by the build will be created in separate O.* subdirectories and installed into the appropriate separate host or target install directories. EPICS executables and scripts are installed into the $(INSTALL_LOCATION)/bin/<arch> directories. Libraries are installed into $(INSTALL_LOCATION)/lib/<arch>. The default definition for $(INSTALL_LOCATION) is $(TOP) which is the root directory in the directory structure. Architecture dependant created files (e.g. object files) are stored in O.<arch> source subdirectories, and architecture independent created files are stored in O.Common source subdirectories. This allows objects for multiple cross target architectures to be maintained at the same time.

To build EPICS base for a specific host/target combination you must have the proper host/target c/c++ cross compiler and target header files, CROSS_COMPILER_HOST_ARCHS must empty or include the host architecture in its list value, the CROSS_COMPILER_TARGET_ARCHS variable must include the target to be cross-compiled, and the base/configure/os directory must have the appropriate configure files.

4.2 Build Requirements

4.2.1 Host Environment Variable

Only one environment variable, `EPICS_HOST_ARCH`, is required to build EPICS <top> areas. This variable should be set to be your workstation's operating system - architecture combination to use the os vendor’s c/c++ compiler for native builds or set to the operating system - architecture - alternate compiler combination to use an alternate compiler for native builds if an alternate compiler is supported on your system. The filenames of the `CONFIG.*.Common` files in base/configure/os show the currently supported EPICS_HOST_ARCH values. Examples are `solaris-sparc`, `solaris-sparc-gnu`, `linux-x86`, `win32-x86`, and `win32-x86-borland`.

4.2.2 Software Prerequisites

Before you can build EPICS components your host system must have the following software installed:

- Perl version 5.6 or greater
- GNU make, version 3.81 or greater
- C++ compiler (host operating system vendor's compiler or GNU compiler)

If you will be building EPICS components for vxWorks targets you will also need:

- Tornado II and one or more board support packages. Consult the vxWorks documentation for details.

If you will be building EPICS components for RTEMS targets you will also need:

- RTEMS development tools and libraries required to run EPICS IOC applications.

4.2.3 Path requirements

You must have the perl executable in your path and you may need C and C++ compilers in your search path. Check definitions of CC and CCC in base/configure/os/CONFIG.<host>.<host> or the definitions for GCC and G++ if ANSI=GCC and CPLUSPLUS=GCC are specified in CONFIG_SITE. For building base you also must have echo in your search path.

4.2.3.1 Unix path

For Unix host builds you also need touch, cpp, cp, rm, mv, and mkdir in your search path and /bin/chmod must exist. On some Unix systems you may also need ar and ranlib in your path, and the c compiler may require ld in your path.

4.2.3.2 Win32 PATH

On WIN32 systems, building shared libraries is the default setting and you will need to add fullpathname to $(INSTALL_LOCATION)/bin/$(EPICS_HOST_ARCH) to your path. Building shared libraries is determined by the value of the macro SHARED_LIBRARIES in CONFIG_SITE or os/CONFIG.Common.<host> (either YES or NO).

4.2.4 Directory names

Because the build rules allow make commands like "make <dir>.<action>,<arch>", subdirectory names within a <top> directory structure may not contain a period"." character.

4.2.5 Startup files

The startup directory in EPICS base contains a perl script, `EpicsHostArch.pl`, which can be used to define EPICS_HOST_ARCH. This script can be invoked with a command line parameter defining the alternate compiler (e.g. if invoking "`EpicsHostArch.pl`" yields solaris-sparc, then invoking "`EpicsHostArch.pl gnu`" will yield solaris-sparc-gnu).

The startup directory also contains scripts to help users set the path and other environment variables

4.3 Configuration Definitions

4.3.1 Site-specific EPICS Base Configuration

4.3.1.1 Site configuration

To configure EPICS base for your site, you may want to modify the default definitions in the following files:

configure/CONFIG_SITE Build choices. Specify target archs.
configure/CONFIG_SITE_ENV Environment variable defaults

4.3.1.2 Host configuration

To configure each host system for your site, you may override the default definitions in the configure/os directory by adding a new file with override definitions. The new file should have the same name as the distribution file to be overridden except CONFIG in the name is changed to CONFIG_SITE.

configure/os/CONFIG_SITE.<host>.<host> - Host build settings
configure/os/CONFIG_SITE.<host>.Common - Host build settings for all target systems

4.3.1.3 Target configuration

To configure each target system, you may override the default definitions in the configure/os directory by adding a new file with override definitions . The new file should have the same name as the distribution file to be overridden except CONFIG in the name is replaced by CONFIG_SITE.

configure/os/CONFIG_SITE.Common.<target> - Target cross settings
configure/os/CONFIG_SITE.<host>.<target> - Host-target settings
configure/os/CONFIG_SITE.Common.vxWorksCommon - vxWorks full paths

4.3.1.4 R3.13 compatibility configuration

To configure EPICS base for building with R3.13 extensions and ioc applications, you must modify the default definitions in the base/config/CONFIG_SITE* files to agree with site definitions you made in base/configure and base/configure/os files.

4.3.2 Directory definitions

The configure files contain definitions for locations in which to install various components. These are all relative to `INSTALL_LOCATION`. The default value for `INSTALL_LOCATION` is $(TOP), and $(T_A) is the current build's target architecture. The default value for INSTALL_LOCATION can be overridden at the bottom of an ioc application's configure/CONFIG file. For base set INSTALL_LOCATION in the CONFIG_SITE file.

```
INSTALL_LOCATION_LIB      = $(INSTALL_LOCATION)/lib
INSTALL_LOCATION_BIN      = $(INSTALL_LOCATION)/bin

INSTALL_HOST_BIN            = $(INSTALL_LOCATION_BIN)/$(EPICS_HOST_ARCH)
INSTALL_HOST_LIB            = $(INSTALL_LOCATION_LIB)/$(EPICS_HOST_ARCH)

INSTALL_INCLUDE           = $(INSTALL_LOCATION)/include
INSTALL_DOC               = $(INSTALL_LOCATION)/doc
INSTALL_HTML              = $(INSTALL_LOCATION)/html
INSTALL_TEMPLATES         = $(INSTALL_LOCATION)/templates
INSTALL_DBD               = $(INSTALL_LOCATION)/dbd
INSTALL_DB                = $(INSTALL_LOCATION)/db
INSTALL_CONFIG            = $(INSTALL_LOCATION)/configure
INSTALL_JAVA              = $(INSTALL_LOCATION)/javalib

INSTALL_LIB               = $(INSTALL_LOCATION_LIB)/$(T_A)
INSTALL_SHRLIB            = $(INSTALL_LOCATION_LIB)/$(T_A)
INSTALL_TCLLIB            = $(INSTALL_LOCATION_LIB)/$(T_A)
INSTALL_BIN               = $(INSTALL_LOCATION_BIN)/$(T_A)
```

4.3.3 Extension and Application Specific Configuration

The base/configure directory contains files with the default build definitions and site specific build definitions. The extensions/configure directory contains extension specific build definitions (e.g. location of X11 and Motif libraries) and "include <filename>" lines for the base/configure files. Likewise, the <application>/configure directory contains application specific build definitions and includes for the base/configure files. Build definitions such a CROSS_COMPILER_TARGET_ARCHS can be overridden in an extension or application by placing an override definition in the <top>/configure/CONFIG_SITE file.

4.3.4 RELEASE file

Every <top>/configure directory contains a RELEASE file. RELEASE contains a user specified list of other <top> directory structures containing files needed by the current <top>. When make is executed in configure, a perl script, `convertRelease.pl,` generates CONFIG_APP_INCLUDE in the O.<arch> subdirectories which contains include, bin, and library directory definitions for each external <top> definition in the RELEASE file. CONFIG_APP_INCLUDE is included into the CONFIG file so its definitions are available for use by Makefiles. The `convertRelease.pl` script also generates a RULES_INCLUDE file which contains an include statement for any existing RULES_BUILD files from each external <top> listed in the RELEASE file. RULES_INCLUDE is included by the RULES_BUILD file in EPICS base so all make rules in the external <top> RULES_BUILD files are available for use by Makefiles.

For example, if configure/RELEASE contains the following definition:

```
CAMAC = /home/epics/modules/bus/camac
```

then the created CONFIG_APP_INCLUDE will contain the following lines

```
CAMAC_BIN = /home/epics/modules/bus/camac/bin/solaris-sparc
CAMAC_LIB = /home/epics/modules/bus/camac/lib/solaris-sparc
RELEASE_INCLUDES += -I/home/epics/modules/bus/camac/include
RELEASE_DBDFLAGS += -I /home/epics/modules/bus/camac/dbd
```

and the created RULES_INCLUDE will contain the following line

```
-include /home/epics/modules/bus/camac/configure/RULES_BUILD
```

RELEASE_DBDFLAGS will appear on the command lines for the dbToRecordTypeH, mkmf.pl, and dbExpand tools, and RELEASE_INCLUDES will appear on compiler command lines. CAMAC_LIB and CAMAC_BIN can be used in a Makefile to define the location of needed scripts, executables, object files, libraries or other files.

Definitions in configure/RELEASE can be overridden for a specific EPICS_HOST_ARCH architecture by providing a configure/RELEASE.<epics_host_arch> file containing overriding definitions.

4.3.5 Modifying configure/RELEASE* files

You should always do a "`gnumake clean uninstall`" in the <top> level directory BEFORE adding, changing, or removing any definitions in the configure/RELEASE* files and then a "`gnumake`" at the top level AFTER making the changes.

The file <top>/config/RELEASE contains definitions for components obtained from outside <top>. If you want to link to a new release of anything defined in the file do the following:

```
cd <top>
gnumake clean uninstall
edit configure/RELEASE
      change the relevant line(s) to point to the new release
gnumake
```

All definitions in <top>/config/RELEASE must result in complete path definitions, i.e. relative path names are not permitted. If your site could have multiple releases of base and other <supporttop> components installed at once, these path definitions should contain a release number as one of the components. However as the RELEASE file is read by gnumake, it is permissible to use macro substitutions to define these pathnames, for example:

```
SUPPORT = /usr/local/iocapps/R3.13.1
EPICS_BASE = $(SUPPORT)/base/3-13-1-asd2
```

4.3.6 Specifying osclass specific definitions

Definitions in a Makefile will apply to the host system (the platform on which make is executed) and each system defined by CROSS_COMPILER_TARGET_ARCHS.

It is possible to limit the systems for which a particular definition applies. Most Makefile definitions can be specified with an appended underscore "_" followed by an osclass specification. If an _<osclass> is not specified, then the definition applies to the host and all CROSS_COMPILER_TARGET_ARCHS systems. If an _<osclass> is specified, then the definition applies only to systems with the specified os class. A Makefile definition can also have an appended _DEFAULT specification. If _DEFAULT is appended, then the Makefile definition will apply to all systems that do not have an _<osclass> specification for that definition. If a _DEFAULT is appended on a definition but the definition should not apply to a particular system <osclass>, the value "-nil-" should be specified in the relevant Makefile definition.

Each system has an OS_CLASS definition in its configure/os/CONFIG.Common.<arch> file. A few examples are:

For vxWorks-* targets <osclass> is vxWorks.
For RTEMS-* targets <osclass> is RTEMS.
For solaris-* targets <osclass> is solaris.
For win32-* targets <osclass> is WIN32.
For linux-* targets <osclass> is Linux.
For hpux-* targets <osclass> is hpux.
For darwin-* targets <osclass> is Darwin.
For aix-* targets <osclass> is AIX.

For example the following Makefile lines specify that product aaa should be created for all systems. Product bbb should be created for systems that do not have OS_CLASS defined as solaris.

```
PROD = aaa
PROD_solaris = -nil-
PROD_DEFAULT = bbb
```

4.3.7 Specifying T_A specific definitions

It is possible for the user to limit the systems for which a particular definition applies to specific target systems.

For example the following Makefile lines specify that product aaa should be created for all target architecture which allow IOC type products and product bbb should be created only for the vxWorks-68040 and vxWorks-ppc603 targets. Remember T_A is the build's current target architecture. so PROD_IOC has the bbb value only when the current built target architecture is vwWorks-68040 or vxWorks-ppc603

```
PROD_IOC = aaa
VX_PROD_vxWorks-68040 = bbb
VX_PROD_vxWorks-ppc603 = bbb
PROD_IOC += VX_PROD_$(T_A)
```

4.3.8 Host and Ioc targets

Build creates two type of makefile targets: Host and Ioc. Host targets are executables, object files, libraries, and scripts which are not part of iocCore. Ioc targets are components of ioc libraries, executables, object files, or iocsh scripts which will be run on an ioc.

Each supported target system has a VALID_BUILDS definition which specifies the type of makefile targets it can support. This definition appears in configure/os/CONFIG.Common.<arch> or configure/os/CONFIG.<arch>.<arch> files.

For vxWorks systems VALID_BUILDS is set to "Ioc".

For Unix type systems, VALID_BUILDS is set to "Host Ioc".

For RTEMS systems, VALID_BUILDS is set to "Ioc".

For WIN32 systems, VALID_BUILDS is set to "Host Ioc".

In a Makefile it is possible to limit the systems for which a particular PROD, TESTPROD, LIBRARY, SCRIPTS, and OBJS is built. For example the following Makefile lines specify that product aaa should be created for systems that support Host type builds. Product bbb should be created for systems that support Ioc type builds. Product ccc should be created for all target systems.

```
PROD_HOST = aaa
PROD_IOC = bbb
PROD = ccc
```

These definitions can be further limited by specifying an appended underscore "_" followed by an osclass or DEFAULT specification.

4.4 Makefiles

4.4.1 Name

The name of the makefile in each directory must be Makefile.

4.4.2 Included Files

Makefiles normally include files from <top>/configure. Thus the makefile "inherits" rules and definitions from configure. The files in <top>/configure may in turn include files from another <top>/configure. This technique makes it possible to share make variables and even rules across <top> directories.

4.4.3 Contents of Makefiles

4.4.3.1 Makefiles in directories containing subdirectories

A Makefile in this type of directory must define where <top> is relative to this directory, include <top>/configure files, and specify the subdirectories in the desired order of make execution. Running gnumake in a directory with the following Makefile lines will cause gnumake to be executed in <dir1> first and then <dir2>. The build rules do not allow a Makefile to specify both subdirectories and components to be built.

```
TOP=../..
include $(TOP)/configure/CONFIG
DIRS += <dir1> <dir2>
include $(TOP)/configure/RULES_DIRS
```

4.4.3.2 Makefiles in directories where components are to be built

A Makefile in this type of directory must define where <top> is relative to this directory, include <top> configure files, and specify the target component definitions. Optionally it may contain user defined rules. Running gnumake in a directory with this type of Makefile will cause gnumake to create an O.<arch> subdirectory and then execute gnumake to build the defined components in this subdirectory. It contains the following lines:

```
TOP=../../..
include $(TOP)/configure/CONFIG
   <component definition lines>
include $(TOP)/configure/RULES
   <optional rules definitions>
```

4.4.4 Simple Makefile examples

Create an IOC type library named asIoc from the source file asDbLib.c and install it into the `$(INSTALL_LOCATION)/lib/<arch>` directory.

```
TOP=../../..
include $(TOP)/configure/CONFIG
LIBRARY_IOC += asIoc
asIoc_SRCS += asDbLib.c
include $(TOP)/configure/RULES
```

For each Host type target architecture, create an executable named catest from the catest1.c and catest2.c source files linking with the existing EPICS base ca and Com libraries, and then install the catest executable into the `$(INSTALL_LOCATION)/bin/<arch>` directory.

```
TOP=../../..
include $(TOP)/configure/CONFIG
PROD_HOST = catest
catest_SRCS += catest1.c catest2.c
catest_LIBS = ca Com
```

```
include $(TOP)/configure/RULES
```

4.5 Make

4.5.1 Make vs. gnumake

EPICS provides an extensive set of make rules. These rules only work with the GNU version of make, gnumake, which is supplied by the Free Software Foundation. Thus, on most Unix systems, the native make will not work. On some systems, e.g. Linux, GNU make may be the default. This manual always uses gnumake in the examples.

4.5.2 Frequently used Make commands

NOTE: It is possible to invoke the following commands for a single target architecture by appending .<arch> to the target in the command.

The most frequently used make commands are:

`gnumake`
: This rebuilds and installs everything that is not up to date.
NOTE: Executing gnumake without arguments is the same as "gnumake install"

`gnumake <arch>`
: This rebuilds and installs everything that is not up to date for a single specified target arch.
NOTE: This is the same as "gnumake install.<arch>"

`gnumake clean`
: This can be used to save disk space by deleting the O.<arch> directories that gnumake will create, but does not remove any installed files from the bin, db, dbd etc. directories. "gnumake clean.<arch>" can be invoked to clean a single architecture.

`gnumake realclean`
: This command can be executed from the <top> directory only. It will remove ALL the O.<arch> subdirectories (even those created by a gnumake from another EPICS_HOST_ARCH).

`gnumake rebuild`
: This is the same as "gnumake clean install". If you are unsure about the state of the generated files in an application, just execute "gnumake rebuild".

`gnumake uninstall`
: This command can be executed from the <top> directory only. It will remove everything installed by gnumake in the include, lib, bin, db, dbd, etc. directories.

`gnumake realuninstall`
: This command can be executed from the <top> directory only. It will remove all the install directories, include, lib, bin, db, dbd, etc..

`gnumake distclean`
: This command can be executed from the <top> directory only. It is the same as issuing both the realclean and realuninstall commmands

`gnumake archclean`
This command will remove O.<arch> dirs but not O.Common dir.

`gnumake cvsclean`
This command can be executed from the <top> directory only. It removes cvs .#* files in all dirs of directory tree.

4.5.3 Make targets

The following is a summary of targets that can be specified for gnumake:

- <action>
- <arch>
- <action>.<arch>
- <dir>
- <dir>.<action>
- <dir>.<arch>
- <dir>.<action>.<arch>

where:

<arch> is EPICS_HOST_ARCH, solaris-sparc, vxWorks-68040, win32-x86, etc. - builds named architecture only.
<action> is help, clean, realclean, distclean, inc, install, build, rebuild, buildInstall, realuninstall, or uninstall
NOTE: help, uninstall, distclean, and realuninstall can only be specified at <top>.
NOTE: realclean cannot be specified in an *.<arch> subdirectory.
<dir> is subdirectory name

Note: You can build using your os vendors' native compiler and also build using a supported alternate compiler in the same directory structure because the executables and libraries will be created and installed into separate directories (e.g bin/solaris-sparc and bin/solaris-sparc-gnu). You can do this by changing your `EPICS_HOST_ARCH`, environment variable between builds or by setting `EPICS_HOST_ARCH` on the gnumake command line.

4.5.4 Header file dependencies

All product, test product, and library source files which appear in one of the source file definitions (e.g. SRCS, PROD_SRCS, LIB_SRCS, <prodname>_SRCS) will have their header file dependencies automatically generated and included as part of the Makefile if HDEPENDS is set to YES in the Makefile and/or in base/configure/CONFIG_SITE.

4.6 Makefile definitions

The following components can be defined in a Makefile:

4.6.1 Source file directories

Normally all product, test product, and library source files reside in the same directory as the Makefile. OS specific source files are allowed and should reside in subdirectories os/<os_class> or os/posix or os/default.

The build rules also allow source files to reside in subdirectories of the current Makefile directory (src directory). For each subdirectory <dir> containing source files add the SRC_DIRS definition.

```
SRC_DIRS += <dir>
```

where <dir> is a relative path definition. An example of SRC_DIRS is

```
SRC_DIRS += ../dir1 ../dir2
```

The directory search order for the above definition is

```
.
../os/$(OS_CLASS) ../os/posix ../os/default
../dir1/os/$(OS_CLASS) ../dir1/os/posix ../dir1/os/default
../dir2/os/$(OS_CLASS) ../dir2/os/posix ../dir2/os/default
..
../dir1 ../dir2
```

where the build directory O.<os_class> is . and the src directory is ...

4.6.2 Posix C source code

The epics base config files assume posix source code and define POSIX to be YES as the default. Individual Makefiles can override this by setting POSIX to NO.

4.6.3 Breakpoint Tables

For each breakpoint table dbd file, bpt<table name>.dbd, to be created from an existing bpt<table name>.data file, add the definition

```
DBD += bpt<table name>.dbd
```

to the Makefile. The following Makefile will create a bptTypeJdegC.dbd file from an existing bptTypeJdegC.data file and install the new dbd file into the $(INSTALL_LOCATION)/dbd directory.

```
TOP=../../..
include $(TOP)/configure/CONFIG
DBD += bptTypeJdegC.dbd
include $(TOP)/configure/RULES
```

4.6.4 Record Type Definitions

For each new record type, the following definition should be added to the makefile:

```
DBDINC += <rectype>Record
```

A <rectype>Record.h header file will be created from an existing <rectype>Record.dbd file. This header will be installed into the $(INSTALL_LOCATION)/include directory and the dbd file will be installed into the $(INSTALL_LOCATION)/dbd directory.

The following Makefile will create xxxRecord.h from an existing xxxRecord.dbd file, install xxxRecord.h into $(INSTALL_LOCATION)/include, and install xxxRecord.dbd into $(INSTALL_LOCATION)/dbd.

```
TOP=../../..
include $(TOP)/configure/CONFIG
DBDINC += xxxRecord
include $(TOP)/configure/RULES
```

4.6.5 Menus

If a menu menu<name>.dbd file is present, then add the following definition:

```
DBDINC += menu<name>.h
```

The header file, menu<name>.h will be created from the existing menu<name>.dbd file and installed into the $(INSTALL_LOCATION)/include directory and the menu dbd file will be installed into $(INSTALL_LOCATION)/dbd.

The following Makefile will create a menuConvert.h file from an existing menuConvert.dbd file and install menuConvert.h into $(INSTALL_LOCATION)/include and menuConvert.dbd into $(INSTALL_LOCATION)/dbd.

```
TOP=../../..
include $(TOP)/configure/CONFIG
DBDINC = menuConvert.h
include $(TOP)/configure/RULES
```

4.6.6 Expanded Database Definition Files

Database definition include files named <name>Include.dbd containing includes for other database definition files can be expanded by the utility program `dbExpand` into a created <name>.dbd file and the <name>.dbd file installed into $(INSTALL_LOCATION)/dbd. The following variables control the process:

```
DBD += <name>.dbd
USR_DBDFLAGS += -I <include path>
USR_DBDFLAGS += -S <macro substitutions>
<name>_DBD += <file1>.dbd <file2>.dbd ...
```

where

```
DBD += <name>.dbd
```

is the name of the output dbd file to contain the expanded definitions. It is created by expanding an existing or build created <name>Include.dbd file and then copied into $(INSTALL_LOCATION)/dbd.

An example of a file to be expanded is exampleInclude.dbd containing the following lines

```
include "base.dbd"
include "xxxRecord.dbd"
device(xxx,CONSTANT,devXxxSoft,"SoftChannel")
```

`USR_DBDFLAGS` defines optional flags for dbExpand. Currently only an include path (-I <path>) and macro substitution (-S <substitution>) are supported. The include paths for EPICS base/dbd, and other <top>/dbd directories will automatically be added during the build if the <top> names are specified in the configure/RELEASE file.

A database definition include file named <name>Include.dbd containing includes for other database definition files can be created from a <name>_DBD definition. The lines

```
DBD += <name>.dbd
<name>_DBD += <file1>.dbd <file2>.dbd ...
```

will create an expanded dbd file <name>.dbd by first creating a <name>Include.dbd. For each filename in the <name>_DBD definition, the created <name>Include.dbd will contain an include statement for that filename. Then the expanded DBD file is generated from the created <name>Include.dbd file and installed into $(INSTALL_LOCATION)/dbd.

The following Makefile will create an expanded dbd file named example.dbd from an existing exampleInclude.dbd file and then install example.dbd into the $(INSTALL_LOCATION)/dbd directory.

```
TOP=../../..
```

```
include $(TOP)/configure/CONFIG
DBD += exampleApp.dbd
include $(TOP)/configure/RULES
```

The following Makefile will create an exampleInclude.dbd file from the example_DBD definition then expand it to create an expanded dbd file, example.dbd, and install example.dbd into the $(INSTALL_LOCATION)/dbd directory.

```
TOP=../../..
include $(TOP)/configure/CONFIG
DBD += example.dbd
example_DBD += base.dbd xxxRecord.dbd xxxSupport.dbd
include $(TOP)/configure/RULES
```

The created exampleInclude.dbd file will contain the following lines

```
include "base.dbd"
include "xxxRecord.dbd"
include "xxxSupport.dbd"
```

4.6.7 Registering Support Routines for Expanded Database Definition Files

A source file which registers simple static variables and record/device/driver support routines with iocsh can be created. The list of variables and routines to register is obtained from lines in an existing `dbd` file.

The following line in a Makefile will result in `<name>_registerRecordDeviceDriver.cpp` being created, compiled, and linked into `<prodname>`. It requires that the file `<name>.dbd` exist.

```
<prodname>_SRCS += <name>_registerRecordDeviceDriver.cpp
```

An example of registering the variable mySubDebug and the routines mySubInit and mySubProcess is <name>.dbd containg the following lines

```
variable(mySubDebug)
function(mySubInit)
function(mySubProcess)
```

4.6.8 Database Definition Files

The following line installs the existing named dbd files into $(INSTALL_LOCATION)/dbd without expansion.

```
DBD += <name>.dbd
```

4.6.9 DBD install files

Definitions of the form:

```
DBD_INSTALLS += <name>
```

result in files being installed to the $(INSTALL_LOCATION/dbd directory. The file <name> can appear with or without a directory prefix. If the file has a directory prefix e.g. $(APPNAME)/dbd/, it is copied from the specified location. If a directory prefix is not present, make will look in the current source directory for the file.

4.6.10 Database Files

For most databases just the name of the database has to be specified. Make will figure out how to generate the file:

```
DB += xxx.db
```

generates xxx.db depending on which source files exist and installs it into $(INSTALL_LOCATION)/db.

A <name>.db database file will be created from an optional <name>.template file and/or an optional <name>.substitutions file, If the substitution file exists but the template file is not named <name>.template, the template file name can be specified as

```
<name>_TEMPLATE = <template file name>
```

A *<nn>.db database file will be created from a *.template and a *<nn>.substitutions file, (where nn is an optional index number).

If a <name> substitutions file contains "file" references to other input files, these referenced files should be made dependencies of the created <name>.db by adding a dependency definition line:

```
<name>_DEPENDS = <filename1> <filename2> ...
```

The Macro Substitutions and Include tool, msi, will be used to generate the database, and msi must either be in your path or you must redefine MSI as the full path name to the msi binary in a RELEASE file or Makefile. An example MSI definition is

```
MSI = /usr/local/epics/extensions/bin/${EPICS_HOST_ARCH}/msi
```

Template files <name>.template, and db files, <name>.db, will be created from an edf file <name>.edf and an <name>.edf file will be created from a <name>.sch file.

Template and substitution files can be installed.

```
DB += xxx.template xxx.substitutions
```

generates and installs these files. If one or more xxx.substitutions files are to be created by script, the script name must be placed in the CREATESUBSTITUTIONS variable (e.g. CREATESUBSTITUTIONS=mySubst.pl). This script will be executed by gnumake with the prefix of the substitution file name to be generated as its argument. If (and only if) there are script generated substitutions files, the prefix of any inflated database's name may not equal the prefix of the name of any template used within the directory.

4.6.11 DB install files

Definitions of the form:

```
DB_INSTALLS += <name>
```

result in files being installed to the $(INSTALL_LOCATION/db directory. The file <name> can appear with or without a directory prefix. If the file has a directory prefix e.g. $(APPNAME)/db/, it is copied from the specified location. If a directory prefix is not present, make will look in the current source directory for the file.

4.6.12 Compile and link command options

Any of the following can be specified:

4.6.12.1 Options for all compile/link commands.

These definitions will apply to all compiler and linker targets.

`USR_INCLUDES += -I<name>`
: header file directories each prefixed by a "-I".

`USR_INCLUDES_<osclass> += -I<name>`
: os specific header file directories each prefixed by a "-I".

`USR_INCLUDES_DEFAULT += -I<name>`
: header file directories each prefixed by a "-I" for any arch that does not have a USR_INCLUDE_<osclass> definition

`USR_CFLAGS += <c flags>`
: c compiler options.

`USR_CFLAGS_<osclass> += <c flags>`
: os specific c compiler options.

`USR_CFLAGS_<T_A> += <c flags>`
: target architecture specific c compiler options.

`USR_CFLAGS_DEFAULT += <c flags>`
: c compiler options for any arch that does not have a USR_CFLAGS_<osclass> definition

`USR_CXXFLAGS += <c++ flags>`
: c++ compiler options.

`USR_CXXFLAGS_<osclass> += <c++ flags>`
: c++ compiler options for the specified osclass.

`USR_CXXFLAGS_<T_A> += <c++ flags>`
: c++ compiler options for the specified target architecture.

`USR_CXXFLAGS_DEFAULT += <c++ flags>`
: c++ compiler options for any arch that does not have a USR_CXXFLAGS_<osclass> definition

`USR_CPPFLAGS += <preprocessor flags>`
: c preprocessor options.

`USR_CPPFLAGS_<osclass> += <preprocessor flags>`
: os specific c preprocessor options.

`USR_CPPFLAGS_<T_A> += <preprocessor flags>`
: target architecture specific c preprocessor options.

`USR_CPPFLAGS_DEFAULT += <preprocessor flags>`
: c preprocessor options for any arch that does not have a USR_CPPFLAGS_<osclass> definition

`USR_LDFLAGS += <linker flags>`
: linker options.

`USR_LDFLAGS_<osclass> += <linker flags>`
: os specific linker options.

`USR_LDFLAGS_DEFAULT += <linker flags>`
: linker options for any arch that does not have a USR_LDFLAGS_<osclass> definition

4.6.12.2 Options for a target specific compile/link command.

`<name>_INCLUDES += -I<name>`
: header file directories each prefixed by a "-I".

`<name>_INCLUDES_<osclass> += -I<name>`
: os specific header file directories each prefixed by a "-I".

`<name>_INCLUDES_<T_A> += -I<name>`
: target architecture specific header file directories each prefixed by a "-I".

`<name>_CFLAGS += <c flags>`
: c compiler options.

`<name>_CFLAGS_<osclass> += <c flags>`
: os specific c compiler options.

`<name>_CFLAGS_<T_A> += <c flags>`
: target architecture specific c compiler options.

`<name>_CXXFLAGS += <c++ flags>`
: c++ compiler options.

`<name>_CXXFLAGS_<osclass> += <c++ flags>`
: c++ compiler options for the specified osclass.

`<name>_CXXFLAGS_<T_A> += <c++ flags>`

c++ compiler options for the specified target architecture.

`<name>_CPPFLAGS += <preprocessor flags>`
: c preprocessor options.

`<name>_CPPFLAGS_<osclass> += <preprocessor flags>`
: os specific c preprocessor options.

`<name>_CPPFLAGS_<T_A> += <preprocessor flags>`
: target architecture specific c preprocessor options.

`<name>_LDFLAGS += <linker flags>`
: linker options.

`<name>_LDFLAGS_<osclass> += <linker flags>`
: os specific linker options.

4.6.13 Libraries

A library is created and installed into $(INSTALL_LOCATION)/lib/<arch> by specifying its name and the name of the object and/or source files containing code for the library. An object or source file name can appear with or without a directory prefix. If the file name has a directory prefix e.g. $(EPICS_BASE_BIN), it is taken from the specified location. If a directory prefix is not present, make will first look in the source directories for a file with the specified name and next try to create the file using existing configure rules. A library filename prefix may be prepended to the library name when the file is created. For Unix type systems and vxWorks the library prefix is lib and there is no prefix for WIN32. Also a library suffix appropriate for the library type and target arch (e.g. .a, .so, .lib, .dll) will be appended to the filename when the file is created.

vxWorks and RTEMS Note: Only archive libraries are created.

Shared libraries Note: Shared libraries can be built for any or all HOST type architectures. The definition of SHARED_LIBRARIES (YES/NO) in base/configure/CONFIG_SITE determines whether shared or archive libraries will be built. When SHARED_LIBRARIES is YES, both archive and shared libraries are built. This definition can be overridden for a specific arch in an configure/os/CONFIG_SITE.<arch>.Common file.,The default definition for SHARED_LIBRARIES in the EPICS base distribution file is YES for all host systems.

win32 Note: An object library file is created when SHARED_LIBRARIES=NO, <name>.lib which is installed into $(INSTALL_LOCATION)/lib/<arch>. Two library files are created when SHARED_LIBRARIES=YES, <name>.lib which is installed into $(INSTALL_LOCATION)/lib/<arch>, and <name>.dll which is installed into $(INSTALL_LOCATION)/bin/<arch>. (Warning: The file <name>.lib will only be created by the build if there are exported symbols from the library.) If SHARED_LIBRARIES=YES, the directory $(INSTALL_LOCATION)/bin/<arch> must be in the user's path during builds to allow invoking executables which were linked with shared libraries.

4.6.13.1 Specifying the library name.

Any of the following can be specified:

`LIBRARY += <name>`
: A library will be created for every target arch.

`LIBRARY_<osclass> += <name>`
: Library <name> will be created for all archs of the specified osclass.

`LIBRARY_DEFAULT += <name>`
: Library <name> will be created for any arch that does not have a LIBRARY_<osclass> definition

`LIBRARY_IOC += <name>`
: Library <name> will be created for IOC type archs.

`LIBRARY_IOC_<osclass> += <name>`
: Library <name> will be created for all IOC type archs of the specified osclass.

`LIBRARY_IOC_DEFAULT += <name>`

Library <name> will be created for any IOC type arch that does not have a LIBRARY_IOC_<osclass> definition

`LIBRARY_HOST += <name>`
: Library <name> will be created for HOST type archs.

`LIBRARY_HOST_<osclass> += <name>`
: Library <name> will be created for all HOST type archs of the specified osclass.

`LIBRARY_HOST_DEFAULT += <name>`
: Library <name> will be created for any HOST type arch that does not have a LIBRARY_HOST_<osclass> definition

4.6.13.2 Specifying library source file names

Source file names, which must have a suffix, are defined as follows:

`SRCS += <name>`
: Source files will be used for all defined libraries and products.

`SRCS_<osclass> += <name>`
: Source files will be used for all defined libraries and products for all archs of the specified osclass.

`SRCS_DEFAULT += <name>`
: Source files will be used for all defined libraries and products for any arch that does not have a SRCS_<osclass> definition

LIBSRCS and LIB_SRCS have the same meaning. LIBSRCS is deprecated, but retained for R3.13 compatibility.

`LIBSRCS += <name>`
: Source files will be used for all defined libraries.

`LIBSRCS_<osclass> += <name>`
: Source files will be used for all defined libraries for all archs of the specified osclass.

`LIBSRCS_DEFAULT += <name>`
: Source files will be used for all defined libraries for any arch that does not have a LIBSRCS_<osclass> definition

`USR_SRCS += <name>`
: Source files will be used for all defined products and libraries.

`USR_SRCS_<osclass> += <name>`
: Source files will be used for all defined products and libraries for all archs of the specified osclass.

`USR_SRCS_DEFAULT += <name>`
: Source files will be used for all defined products and libraries for any arch that does not have a USR_SRCS_<osclass> definition

`LIB_SRCS += <name>`
: Source files will be used for all libraries.

`LIB_SRCS_<osclass> += <name>`
: Source files will be used for all defined libraries for all archs of the specified osclass.

`LIB_SRCS_DEFAULT += <name>`
: Source files will be used for all defined libraries for any arch that does not have a LIB_SRCS_<osclass> definition

`<libname>_SRCS += <name>`
: Source files will be used for the named library.

`<libname>_SRCS_<osclass> += <name>`
: Source files will be used for named library for all archs of the specified osclass.

`<libname>_SRCS_DEFAULT += <name>`
: Source files will be used for named library for any arch that does not have a <libname>_SRCS_<osclass> definition

4.6.13.3 Specifying library object file names

Library object file names should only be specified for object files which will not be built in the current directory. For object files built in the current directory, library source file names should be specified. See Specifying Library Source File Names above.

Object files which have filename with a ".o" or ".obj" suffix are defined as follows and can be specified without the suffix but should have the directory prefix

`USR_OBJS += <name>`
: Object files will be used in builds of all products and libraries

`USR_OBJS_<osclass> += <name>`
: Object files will be used in builds of all products and libraries for archs with the specified osclass.

`USR_OBJS_DEFAULT` += <name>
: Object files will be used in builds of all products and libraries for archs without a USR_OBJS_<osclass> definition specified.

`LIB_OBJS += <name>`
: Object files will be used in builds of all libraries.

`LIB_OBJS_<osclass> += <name>`
: Object files will be used in builds of all libraries for archs of the specified osclass.

`LIB_OBJS_DEFAULT` += <name>
: Object files will be used in builds of all libraries for archs without a LIB_OBJS_<osclass> definition specified.

`<libname>_OBJS += <name>`
: Object files will be used for all builds of the named library)

`<libname>_OBJS_<osclass> += <name>`
: Object files will be used in builds of the library for archs with the specified osclass.

`<libname>_OBJS_DEFAULT += <name>`
: Object files will be used in builds of the library for archs without a <libname>_OBJS_<osclass> definition specified.

Combined object files, from R3.13 built modules and applications which have file names that do not include a ".o" or ".obj" suffix (e.g. xyzLib) are defined as follows:

`USR_OBJLIBS += <name>`
: Combined object files will be used in builds of all libraries and products.

`USR_OBJLIBS_<osclass> += <name>`
: Combined object files will be used in builds of all libraries and products for archs of the specified osclass.

`USR_OBJLIBS_DEFAULT` += <name>
: Combined object files will be used in builds of all libraries and products for archs without a USR_OBJLIBS_<osclass> definition specified.

`LIB_OBJLIBS += <name>`
: Combined object files will be used in builds of all libraries.

`LIB_OBJLIBS_<osclass> += <name>`
: Combined object files will be used in builds of all libraries for archs of the specified osclass.

`LIB_OBJLIBS_DEFAULT` += <name>
: Combined object files will be used in builds of all libraries for archs without a LIB_OBJLIBS_<osclass> definition specified.

`<libname>_OBJLIBS += <name>`
: Combined object files will be used for all builds of the named library.

`<libname>_OBJLIBS_<osclass> += <name>`
: Combined object files will be used in builds of the library for archs with the specified osclass.

`<libname>_OBJLIBS_DEFAULT += <name>`
: Combined object files will be used in builds of the library for archs without a <libname>_OBJLIBS_<osclass> definition specified.

`<libname>_LDOBJS += <name>`
: Combined object files will be used for all builds of the named library. (deprecated)

`<libname>_LDOBJS_<osclass> += <name>`
: Combined object files will be used in builds of the library for archs with the specified osclass. (deprecated)

`<libname>_LDOBJS_DEFAULT += <name>`
: Combined object files will be used in builds of the library for archs without a <libname>_OBJS_<osclass> definition specified. (deprecated)

4.6.13.4 LIBOBJS definitions

Previous versions of epics (3.13 and before) accepted definitions like:

```
LIBOBJS += $(<support>_BIN)/xxx.o
```

These are gathered together in files such as baseLIBOBJS. To use such definitions include the lines:

```
-include ../baseLIBOBJS
<libname>_OBJS += $(LIBOBJS)
```

Note: vxWorks applications created by makeBaseApp.pl from base release R3.14.0alpha3 and later no longer have a file named baseLIBOBJS. Base record and device support now exists in archive libraries.

4.6.13.5 Specifying dependant libraries to be linked when creating a library

For each library name specified which is not a system library nor a library from an EPICS top defined in the confiugre/RELEASE file, a <name>_DIR definition must be present in the Makefile to specify the location of the library.

Library names, which must not have a directory and "lib" prefix nor a suffix, are defined as follows:

`LIB_LIBS += <name>`
: Libraries to be used when linking all defined libraries.

`LIB_LIBS_<osclass> += <name>`
: Libraries to be used or all archs of the specified osclass when linking all defined libraries.

`LIB_LIBS_DEFAULT += <name>`
: Libraries to be used for any arch that does not have a LIB_LIBS_<osclass> definition when linking all defined libraries.

`USR_LIBS += <name>`
: Libraries to be used when linking all defined products and libraries.

`USR_LIBS_<osclass> += <name>`
: Libraries to be used or all archs of the specified osclasswhen linking all defined products and libraries.

`USR_LIBS_DEFAULT += <name>`
: Libraries to be used for any arch that does not have a USR_LIBS_<osclass> definition when linking all defined products and libraries.

`<libname>_LIBS += <name>`
: Libraries to be used for linking the named library.

`<libname>_LIBS_<osclass> += <name>`
: Libraries will be used for all archs of the specified osclass for linking named library.

<libname>_LIBS_DEFAULT += <name>
: Libraries to be used for any arch that does not have a <libname>_LIBS_<osclass> definition when linking named library.

`<libname>_SYS_LIBS += <name>`
: System libraries to be used for linking the named library.

`<libname>_SYS_LIBS_<osclass> += <name>`
: System libraries will be used for all archs of the specified osclass for linking named library.

`<libname>_SYS_LIBS_DEFAULT += <name>`
: System libraries to be used for any arch that does not have a <libname>_LIBS_<osclass> definition when linking named library.

4.6.13.6 The order of dependant libraries

Dependant library names appear in the following order on a library link line:

1. <libname>_LIBS
2. <libname>_LIBS_<osclass> or <libname>_LIBS_DEFAULT
3. LIB_LIBS
4. LIB_LIBS_<osclass> or LIB_LIBS_DEFAULT
5. USR_LIBS
6. USR_LIBS_<osclass> or USR_LIBS_DEFAULT
7. <libname>_SYS_LIBS
8. <libname>_SYS_LIBS_<osclass> or <libname>_SYS_LIBS_DEFAULT
9. LIB_SYS_LIBS
10. LIB_SYS_LIBS_<osclass> or LIB_SYS_LIBS_DEFAULT
11. USR_SYS_LIBS
12. USR_SYS_LIBS_<osclass> or USR_SYS_LIBS_DEFAULT

4.6.13.7 Specifying library DLL file names (deprecated)

WIN32 libraries require all external references to be resolved, so if a library contains references to items in other DLL libraries, these DLL library names must be specified (without directory prefix and without ".dll" suffix) as follows:

`DLL_LIBS += <name>`
: These DLLs will be used for all libraries.

`<libname>_DLL_LIBS += <name>`
: These DLLs will be used for the named library.

Each <name> must have a corresponding <name>_DIR definition specifying its directory location.

4.6.13.8 Specifying shared library version number

A library version number can be specified when creating a shared library as follows:

```
SHRLIB_VERSION += <version>
```

On WIN32 this results in "/version:$(SHRLIB_VERSION)" link option. On Unix type hosts ".$(SHRLIB_VERSION)" is appended to the shared library name and a symbolic link is created for the unversioned library name. $(EPICS_VERSION).$(EPICS_REVISION) is the default value for SHRLIB_VERSION.

4.6.13.9 Library example:

```
LIBRARY_vxWorks += vxWorksOnly
LIBRARY_IOC += iocOnly
LIBRARY_HOST += hostOnly
LIBRARY += all
```

```
vxWorksOnly_OBJS += $(LINAC_BIN)/vxOnly1
vxWorksOnly_SRCS += vxOnly2.c
iocOnly_OBJS += $(LINAC_BIN)/iocOnly1
iocOnly_SRCS += iocOnly2.cpp
hostOnly_OBJS +=  $(LINAC_BIN)/host1
all_OBJS += $(LINAC_BIN)/all1
all_SRCS += all2.cpp
```

If the architectures defined in <top>/configure are solaris-sparc and vxWorks-68040 and LINAC is defined in the <top>/CONFIGURE/RELEASE file, then the following libraries will be created:

- $(INSTALL_LOCATION)/bin/vxWork-68040/libvxWorksOnly.a : $(LINAC_BIN)/vxOnly1.o vxOnly2.o
- $(INSTALL_LOCATION)/bin/vxWork-68040/libiocOnly.a : $(LINAC_BIN/iocOnly1.o iocOnly2.o
- $(INSTALL_LOCATION)/lib/solaris-sparc/libiocOnly.a : $(LINAC_BIN)/iocOnly1.o iocOnly2.o
- $(INSTALL_LOCATION)/lib/solaris-sparc/libhostOnly.a : $(LINAC_BIN)/host1.o
- $(INSTALL_LOCATION)/bin/vxWork-68040/liball.a : $(LINAC_BIN)/all1.o all2.o
- $(INSTALL_LOCATION)/lib/solaris-sparc/liball.a : $(LINAC_BIN)/all1.o all2.o

4.6.14 Loadable libraries

Loadable libraries are regular libraries which are not required to have all symbols resolved during the build. The intent is to create dynamic plugins so no archive library is created. Source file, object files, and dependant libraries are specified in exactly the same way as for regular libraries.

Any of the following can be specified:

`LOADABLE_LIBRARY += <name>`
: The <name> loadable library will be created for every target arch.

`LOADABLE_LIBRARY_<osclass> += <name>`
: Loadable library <name> will be created for all archs of the specified osclass.

`LOADABLE_LIBRARY_DEFAULT += <name>`
: Loadable library <name> will be created for any arch that does not have a LOADABLE_LIBRARY_<osclass> definition

`LOADABLE_LIBRARY_HOST += <name>`
: Loadable library <name> will be created for HOST type archs.

`LOADABLE_LIBRARY_HOST_<osclass> += <name>`
: Loadable library <name> will be created for all HOST type archs of the specified osclass.

`LOADABLE_LIBRARY_HOST_DEFAULT += <name>`
: Loadable library <name> will be created for any HOST type arch that does not have a LOADABLE_LIBRARY_HOST_<osclass> definition

4.6.15 Combined object libraries (VxWorks only)

Combined object libraries are regular combined object files which have been created by linking together multiple object files. OBJLIB specifications in the Makefile create a combined object file and a corresponding munch file for vxWorks target architectures only. Combined object libraries have a Library.o suffix. It is possible to generate and install combined object libraries by using definitions:

```
OBJLIB += <name>
OBJLIB_vxWorks += <name>
OBJLIB_SRCS += <srcname1> <srcname2> ...
OBJLIB_OBJS += <objname1> <objname2> ...
```

These definitions result in the combined object file <name>Library.o and its corresponding <name>Library.munch munch file being built for each vxWorks architecture from source/object files in the OBJLIB_SRCS/OBJLIB_OBJS definitions. The combined object file and the munch file are installed into the $(INSTALL_LOCATION)/bin/<arch> directory.

4.6.16 Object Files

It is possible to generate and install object files by using definitions:

```
OBJS += <name>
OBJS_<osclass> += <name>
OBJS_DEFAULT += <name>
OBJS_IOC += <name>
OBJS_IOC_<osclass> += <name>
OBJS_IOC_DEFAULT += <name>
OBJS_HOST += <name>
OBJS_HOST_<osclass> += <name>
OBJS_HOST_DEFAULT += <name>
```

These will cause the specified file to be generated from an existing source file for the appropriate target arch and installed into $(INSTALL_LOCATION)/bin/<target_arch>.

The following Makefile will create the abc object file for all target architectures, the def object file for all target archs except vxWorks, and the xyz object file only for the vxWorks target architecture and install them into the appropriate $(INSTALL_LOCATION)/bin/<arch> directory.

```
TOP=../../..
include $(TOP)/configure/CONFIG
OBJS += abc
OBJS_vxWorks += xyz
OBJS_DEFAULT += def
include $(TOP)/configure/RULES
```

4.6.17 State Notation Programs

A state notation program file can be specified as a source file in any SRC definition. For example:

```
<prodname>_SRCS += <name>.stt
```

The state notation compiler `snc` will generate the file `<name>.c` from the state notation program file `<name>.stt`. This C file is compiled and the resulting object file is linked into the `<prodname>` product.

A state notation source file must have the extension `.st` or `.stt`. The `.st` file is passed through the C preprocessor before it is processed by `snc`.

If you have state notation language source files (`.stt` and `.st` files), the module seq must be built and SNCSEQ defined in the RELEASE file. If the state notation language source files require c preprocessing before conversion to c source (`.st` files), gcc must be in your path.

4.6.18 Scripts, etc.

Any of the following can be specified:

```
SCRIPTS += <name>
```

A script will be installed from the src directory to the $(INSTALL_LOCATION)/bin/<arch> directories.

```
SCRIPTS_<osclass> += <name>
```

Script <name> will be installed for all archs of the specified osclass.

`SCRIPTS_DEFAULT += <name>`
: Script <name> will be installed for any arch that does not have a SCRIPTS_<osclass> definition

`SCRIPTS_IOC += <name>`
: Script <name> will be installed for IOC type archs.

`SCRIPTS_IOC_<osclass> += <name>`
: Script <name> will be installed for all IOC type archs of the specified osclass.

`SCRIPTS_IOC_DEFAULT += <name>`
: Script <name> will be installed for any IOC type arch that does not have a SCRIPTS_IOC_<osclass> definition

`SCRIPTS_HOST += <name>`
: Script <name> will be installed for HOST type archs.

`SCRIPTS_HOST_<osclass> += <name>`
: Script <name> will be installed for all HOST type archs of the specified osclass.

`SCRIPTS_HOST_DEFAULT += <name>`
: Script <name> will be installed for any HOST type arch that does not have a SCRIPTS_HOST_<osclass> definition

Definitions of the form:

```
SCRIPTS_<osclass> += <name1>
SCRIPTS_DEFAULT += <name2>
```

results in the <name1> script being installed from the src directory to the $(INSTALL_LOCATION)/bin/<arch> directories for all target archs of the specified os class <osclass> and the <name2> script installed into the $(INSTALL_LOCATION)/bin/<arch> directories of all other target archs.

4.6.19 Include files

A definition of the form:

```
INC += <name>.h
```

results in file <name>.h being installed or created and installed to the $(INSTALL_LOCATION)/include directory.

Definitions of the form:

```
INC_DEFAULT += <name>.h
INC_<osclass> += <name>.h
```

results in file <name>.h being installed or created and installed into the appropriate $(INSTALL_LOCATION)/include/os/<osclass> directory..

4.6.20 Html and Doc files

A definition of the form:

```
HTMLS_DIR = <dirname>
HTMLS += <name>
```

results in file <name> being installed from the src directory to the $(INSTALL_LOCATION)/html/<dirname> directory.

A definition of the form:

```
DOCS += <name>
```

results in file <name> being installed from the src directory to the $(INSTALL_LOCATION)/doc directory.

4.6.21 Templates

Adding definitions of the form

```
TEMPLATES_DIR = <dirname>
TEMPLATES += <name>
```

results in the file <name> being installed from the src directory to the $(INSTALL_LOCATION)/templates/<dirname> directory. If a directory structure of template files is to be installed, the template file names may include a directory prefix.

4.6.22 Lex and yac

If a <name>.c source file specified in a Makefile definition is not found in the source directory, gnumake will try to build it from <name>.y and <name>_lex.l files in the source directory.

4.6.23 Products

A product executable is created for each <arch> and installed into $(INSTALL_LOCATION)/bin/<arch> by specifying its name and the name of either the object or source files containing code for the product. An object or source file name can appear with or without a directory prefix. Object files should contain a directory prefix. If the file has a directory prefix e.g. $(EPICS_BASE_BIN), the file is taken from the specified location. If a directory prefix is not present, make will look in the source directories for a file with the specified name or try build it using existing rules. An executable filename suffix appropriate for the target arch (e.g. .exe) may be appended to the filename when the file is created.

PROD specifications in the Makefile for vxWorks target architectures create a combined object file with library references resolved and a corresponding .munch file.

```
PROD_HOST += <name>
<name>_SRC += <srcname>.c
```

results in the executable <name> being built for each HOST architecture, <arch>, from a <srcname>.c file. Then <name> is installed into the $(INSTALL_LOCATION)/bin/<arch> directory.

4.6.23.1 Specifying the product name.

Any of the following can be specified:

`PROD += <name>`
: Product <name> will be created for every target arch.

`PROD_<osclass> += <name>`
: Product <name> will be created for all archs of the specified osclass.

`PROD_DEFAULT += <name>`
: Product <name> will be created for any arch that does not have a PROD_<osclass> definition

`PROD_IOC += <name>`
: Product <name> will be created for IOC type archs.

`PROD_IOC_<osclass> += <name>`
: Product <name> will be created for all IOC type archs of the specified osclass.

`PROD_IOC_DEFAULT += <name>`
: Product <name> will be created for any IOC type arch that does not have a PROD_IOC_<osclass> definition

`PROD_HOST += <name>`
: Product <name> will be created for HOST type archs.

`PROD_HOST_<osclass> += <name>`

Product <name> will be created for all HOST type archs of the specified osclass.

`PROD_HOST_DEFAULT += <name>`
: Product <name> will be created for any HOST type arch that does not have a PROD_HOST_<osclass> definition

4.6.23.2 Specifying product object file names

Object files which have filenames with a ".o" or ".obj" suffix are defined as follows and can be specified without the suffix but should have the directory prefix

`USR_OBJS += <name>`
: Object files will be used in builds of all products and libraries

`USR_OBJS_<osclass> += <name>`
: Object files will be used in builds of all products and libraries for archs with the specified osclass.

`USR_OBJS_DEFAULT` += <name>
: Object files will be used in builds of all products and libraries for archs without a USR_OBJS_<osclass> definition specified.

`PROD_OBJS += <name>`
: Object files will be used in builds of all products

`PROD_OBJS_<osclass> += <name>`
: Object files will be used in builds of all products for archs with the specified osclass.

`PROD_OBJS_DEFAULT` += <name>
: Object files will be used in builds of all products for archs without a PROD_OBJS_<osclass> definition specified.

`<prodname>_OBJS += <name>`
: Object files will be used for all builds of the named product

`<prodname>_OBJS_<osclass> += <name>`
: Object files will be used in builds of the named product for archs with the specified osclass.

`<prodname>_OBJS_DEFAULT += <name>`
: Object files will be used in builds of the named product for archs without a <prodname>_OBJS_<osclass> definition specified.

Combined object files, from R3.13 built modules and applications which have file names that do not include a ".o" or ".obj" suffix (e.g. xyzLib) are defined as follows:

`USR_OBJLIBS += <name>`
: Combined object files will be used in builds of all libraries and products.

`USR_OBJLIBS_<osclass> += <name>`
: Combined object files will be used in builds of all libraries and products for archs of the specified osclass.

`USR_OBJLIBS_DEFAULT` += <name>
: Combined object files will be used in builds of all libraries and products for archs without a USR_OBJLIBS_<osclass> definition specified.

`PROD_OBJLIBS += <name>`
: Combined object files will be used in builds of all products.

`PROD_OBJLIBS_<osclass> += <name>`
: Combined object files will be used in builds of all products for archs of the specified osclass.

`PROD_OBJLIBS_DEFAULT` += <name>
: Combined object files will be used in builds of all products for archs without a PROD_OBJLIBS_<osclass> definition specified.

`<prodname>_OBJLIBS += <name>`
: Combined object files will be used for all builds of the named product.

`<prodname>_OBJLIBS_<osclass> += <name>`
: Combined object files will be used in builds of the named product for archs with the specified osclass.

`<prodname>_OBJLIBS_DEFAULT += <name>`
: Combined object files will be used in builds of the named product for archs without a <prodname>_OBJLIBS_<osclass> definition specified.

`<prodname>_LDOBJS += <name>`
: Object files will be used for all builds of the named product. (deprecated)

`<prodname>_LDOBJS_<osclass> += <name>`
: Object files will be used in builds of the name product for archs with the specified osclass. (deprecated)

`<prodname>_LDOBJS_DEFAULT += <name>`
: Object files will be used in builds of the product for archs without a <prodname>_LDOBJS_<osclass> definition specified. (deprecated)

4.6.23.3 Specifying product source file names

Source file names, which must have a suffix, are defined as follows:

`SRCS += <name>`
: Source files will be used for all defined libraries and products.

`SRCS_<osclass> += <name>`
: Source files will be used for all defined libraries and products for all archs of the specified osclass.

`SRCS_DEFAULT += <name>`
: Source files will be used for all defined libraries and products for any arch that does not have a SRCS_<osclass> definition

`USR_SRCS += <name>`
: Source files will be used for all products and libraries.

`USR_SRCS_<osclass> += <name>`
: Source files will be used for all defined products and libraries for all archs of the specified osclass.

`USR_SRCS_DEFAULT += <name>`
: Source files will be used for all defined products and libraries for any arch that does not have a USR_SRCS_<osclass> definition

`PROD_SRCS += <name>`
: Source files will be used for all products.

`PROD_SRCS_<osclass> += <name>`
: Source files will be used for all defined products for all archs of the specified osclass.

`PROD_SRCS_DEFAULT += <name>`
: Source files will be used for all defined products for any arch that does not have a PROD_SRCS_<osclass> definition

`<prodname>_SRCS += <name>`
: Source file will be used for the named product.

`<prodname>_SRCS_<osclass> += <name>`
: Source files will be used for named product for all archs of the specified osclass.

<prodname>_SRCS_DEFAULT += <name>
: Source files will be used for named product for any arch that does not have a <prodname>_SRCS_<osclass> definition

4.6.23.4 Specifying libraries to be linked when creating the product

For each library name specified which is not a system library nor a library from EPICS_BASE, a <name>_DIR definition must be present in the Makefile to specify the location of the library.

Library names, which must not have a directory and "lib" prefix nor a suffix, are defined as follows:

`PROD_LIBS += <name>`
: Libraries to be used when linking all defined products.

`PROD_LIBS_<osclass> += <name>`
: Libraries to be used or all archs of the specified osclass when linking all defined products.

`PROD_LIBS_DEFAULT += <name>`
: Libraries to be used for any arch that does not have a PROD_LIBS_<osclass> definition when linking all defined products.

`USR_LIBS += <name>`
: Libraries to be used when linking all defined products.

`USR_LIBS_<osclass> += <name>`
: Libraries to be used or all archs of the specified osclasswhen linking all defined products.

`USR_LIBS_DEFAULT += <name>`
: Libraries to be used for any arch that does not have a USR_LIBS_<osclass> definition when linking all defined products.

`<prodname>_LIBS += <name>`
: Libraries to be used for linking the named product.

`<prodname>_LIBS_<osclass> += <name>`
: Libraries will be used for all archs of the specified osclass for linking named product.

`<prodname>`_LIBS_DEFAULT += <name>
: Libraries to be used for any arch that does not have a <prodname>_LIBS_<osclass> definition when linking named product.

`SYS_PROD_LIBS += <name>`
: System libraries to be used when linking all defined products.

`SYS_PROD_LIBS_<osclass> += <name>`
: System libraries to be used for all archs of the specified osclass when linking all defined products.

`SYS_PROD_LIBS_DEFAULT += <name>`
: System libraries to be used for any arch that does not have a PROD_LIBS_<osclass> definition when linking all defined products.

`<prodname>_SYS_LIBS += <name>`
: System libraries to be used for linking the named product.

`<prodname>_SYS_LIBS_<osclass> += <name>`
: System libraries will be used for all archs of the specified osclass for linking named product.

`<prodname>_SYS_LIBS_DEFAULT += <name>`
: System libraries to be used for any arch that does not have a <prodname>_LIBS_<osclass> definition when linking named product.

4.6.23.5 The order of dependant libraries

Dependant library names appear in the following order on a product link line:

1. <prodname>_LIBS
2. <prodname>_LIBS_<osclass> or <prodname>_LIBS_DEFAULT
3. PROD_LIBS
4. PROD_LIBS_<osclass> or PROD_LIBS_DEFAULT
5. USR_LIBS
6. USR_LIBS_<osclass> or USR_LIBS_DEFAULT
7. <prodname>_SYS_LIBS
8. <prodname>_SYS_LIBS_<osclass> or <prodname>_SYS_LIBS_DEFAULT

9. PROD_SYS_LIBS
10. PROD_SYS_LIBS_<osclass> or PROD_SYS_LIBS_DEFAULT
11. USR_SYS_LIBS
12. USR_SYS_LIBS_<osclass> or USR_SYS_LIBS_DEFAULT

4.6.23.6 Specifying product version number

On WIN32 only a product version number can be specified as follows:

```
PROD_VERSION += <version>
```

This results in "/version:$(PROD_VERSION)" link option.

4.6.23.7 Product static builds

Product executables can be linked with either archive versions or shared versions of EPICS libraries. Shared versions of system libraries will always be used in product linking. The definition of STATIC_BUILD (YES/NO) in base/configure/CONFIG_SITE determines which EPICS libraries to use. When STATIC_BUILD is NO, shared libraries will be used. (SHARED_LIBRARIES must be set to YES.) The default definition for STATIC_BUILD in the EPICS base CONFIG_SITE distribution file is NO. A STATIC_BUILD definition in a Makefile will override the definition in CONFIG_SITE.

4.6.24 Test Products

Test products are product executables that are created but not installed into $(INSTALL_LOCATION)/bin/<arch> directories. Test product libraries, source, and object files are specified in exactly the same way as regular products.

Any of the following can be specified:

`TESTPROD += <name>`
: Test product <name> will be created for every target arch.

`TESTPROD_<osclass> += <name>`
: Test product <name> will be created for all archs of the specified osclass.

`TESTPROD_DEFAULT += <name>`
: Test product <name> will be created for any arch that does not have a TESTPROD_<osclass> definition

`TESTPROD_IOC += <name>`
: Test product <name> will be created for IOC type archs.

`TESTPROD_IOC_<osclass> += <name>`
: Test product <name> will be created for all IOC type archs of the specified osclass.

`TESTPROD_IOC_DEFAULT += <name>`
: Test product <name> will be created for any IOC type arch that does not have a TESTPROD_IOC_<osclass> definition

`TESTPROD_HOST += <name>`
: Test product <name> will be created for HOST type archs.

`TESTPROD_HOST_<osclass> += <name>`
: Test product <name> will be created for all HOST type archs of the specified osclass.

`TESTPROD_HOST_DEFAULT += <name>`
: Test product <name> will be created for any HOST type arch that does not have a TESTPROD_HOST_<osclass> definition

4.6.25 Test Scripts

Test scripts are perl scripts whose names end in `.t` that get executed to satisfy the `runtests` make target. They are run by the perl Test::Harness library, and should send output to stdout following the Test Anything Protocol. Any of the following can be specified, although only TESTSCRIPTS_HOST is currently useful:

`TESTSCRIPTS += <name>`
: Test script <name> will be created for every target arch.

`TESTSCRIPTS_<osclass> += <name>`
: Test script <name> will be created for all archs of the specified osclass.

`TESTSCRIPTS_DEFAULT += <name>`
: Test script <name> will be created for any arch that does not have a TESTSCRIPTS_<osclass> definition

`TESTSCRIPTS_IOC += <name>`
: Test script <name> will be created for IOC type archs.

`TESTSCRIPTS_IOC_<osclass> += <name>`
: Test script <name> will be created for all IOC type archs of the specified osclass.

`TESTSCRIPTS_IOC_DEFAULT += <name>`
: Test script <name> will be created for any IOC type arch that does not have a TESTSCRIPTS_IOC_<osclass> definition

`TESTSCRIPTS_HOST += <name>`
: Test script <name> will be created for HOST type archs.

`TESTSCRIPTS_HOST_<osclass> += <name>`
: Test script <name> will be created for all HOST type archs of the specified osclass.

`TESTSCRIPTS_HOST_DEFAULT += <name>`
: Test script <name> will be created for any HOST type arch that does not have a TESTSCRIPTS_HOST_<osclass> definition.

If a name in one of the above variables matches a regular executable program name (normally generated as a test product) with "`.t`" appended, a suitable perl script will be generated that will execute that program directly; this makes it simple to run programs that use the epicsUnitTest routines in libCom. A test script written in Perl with a name ending `.plt` will be copied into the O.<arch> directory with the ending changed to `.t`; such scripts will usually use the perl Test::Simple or Test::More libraries.

4.6.26 Miscellaneous Targets

A definition of the form:

```
TARGETS += <name>
```

results in the file <name> being built in the O.<arch> directory from existing rules and files in the source directory. These target files are not installed.

4.6.27 Installing Other Binaries

Definitions of the form:

```
BIN_INSTALLS += <name>
BIN_INSTALLS += <dir>/<name>
BIN_INSTALLS_DEFAULT += <name>
BIN_INSTALLS_<osclass> += <name>
```

will result in the named files being installed to the appropriate $(INSTALL_LOCATION)/bin/<arch> directory. The file <name> can appear with or without a directory prefix. If the file has a directory prefix e.g. $(EPICS_BASE_BIN), it is copied from the specified location. If a directory prefix is not present, make will look in the source directory for the file.

4.6.28 Installing Other Libraries

Definitions of the form:

```
LIB_INSTALLS += <name>
LIB_INSTALLS += <dir>/<name>
LIB_INSTALLS_DEFAULT += <name>
LIB_INSTALLS_<osclass> += <name>
```

result in files being installed to the appropriate $(INSTALL_LOCATION)/lib/<arch> directory. The file <name> can appear with or without a directory prefix. If the file has a directory prefix e.g. $(EPICS_BASE_LIB), it is copied from the specified location. If a directory prefix is not present, make will look in the source directory for the file.

4.6.29 Win32 resource files

Definitions of the form:

```
RCS += <name>      Resource files for all products and libraries.
RCS_<osclass> += <name>

PROD_RCS += <name>  Resource files for all products.
PROD_RCS_<osclass> += <name>
PROD_RCS_DEFAULT += <name>

LIB_RCS += <name>  Resource files for all libraries.
LIB_RCS_<osclass> += <name>
LIB_RCS_DEFAULT += <name>

<name>_RCS += <name>  Resource files for specified product or library.
<name>_RCS_<osclass> += <name>
<name>_RCS_DEFAULT += <name>
```

result in resource files (*.res files) being created from the specified *.rc files and linked into the prods and/or libraries.

4.6.30 TCL libraries

Definitions of the form:

```
TCLLIBNAME += <name>
TCLINDEX += <name>
```

result in the specified tcl files being installed to the $(INSTALL_LOCATION)/lib/<arch> directory.

4.6.31 Java class files

Java class files can be created by the javac tool into $(INSTALL_JAVA) or into the O.Common subdirectory, by specifying the name of the java class file in the Makefile. Command line options for the javac tool can be specified. The configuration files set the java c option "-sourcepath .:..:../..".

Any of the following can be specified:

JAVA += <name>.java
: The <name>.java file will be used to create the <name>.class file in the $(INSTALL_JAVA) directory.

TESTJAVA += <name>.java
: The <name>.java files will be used to create the <name>.class file in the O.Common subdirectory.

USR_JAVACFLAGS += <name>
: The javac option <name> will be used on the javac command lines.

4.6.31.1 Example 1

In this example, three class files are created in $(INSTALL_LOCATION)/javalib/mytest. The javac depreciation flag is used to list the description of each use or override of a deprecated member or class.

```
JAVA = mytest/one.java
JAVA = mytest/two.java
JAVA = mytest/three.java
USR_JAVACFLAGS = -deprecation
```

4.6.31.2 Example 2

In this example, the test.class file is created in the O.Common subdirectory.

```
TESTJAVA = test.java
```

4.6.32 Java jar file

A single java jar file can be created using the java jar tool and installed into $(INSTALL_JAVA) (i.e. $(INSTALL_LOCATION)/javalib) by specifying its name, and the names of its input files to be included in the created jar file. The jar input file names must appear with a directory prefix.

Any of the following can be specified:

JAR += <name>
: The <name> jar file will be created and installed into the $(INSTALL_JAVA) directory.

JAR_INPUT += <name>
: Names of images, audio files and classes files to be included in the jar file.

JAR_MANIFEST += <name>
: The preexisting manifest file will be used for the created jar file.

4.6.32.1 Example 1

In this example, all the class files created by the current Makefile's "JAVA+=" definitions, are placed into a file named mytest1.jar. A manifest file will be automatically generated for the jar.

Note: $(INSTALL_CLASSES) is set to $(addprefix $(INSTALL_JAVA)/,$(CLASSES)) in the EPICS base configure files.

```
JAR = mytest1.jar
JAR_INPUT = $(INSTALL_CLASSES)
```

4.6.32.2 Example 2

In this example, three class files are created and placed into a new jar archive file named mytest2.jar. An existing manifest file, mytest2.mf is put into the new jar file.

```
JAR = mytest2.jar
```

```
JAR_INPUT = $(INSTALL_JAVA)/mytest/one.class
JAR_INPUT = $(INSTALL_JAVA)/mytest/two.class
JAR_INPUT = $(INSTALL_JAVA)/mytest/three.class
JAR_MANIFEST = mytest2.mf
```

4.6.33 Java native method C header files

A C header files for use with java native methods will be created by the javah tool in the O.Common subdirectory by specifying the name of the header file to be created. The name of the java class file used to generate the header is derived from the name of the header file. Underscores (_) are used as a header file name delimiter. Command line options for the javah tool can be specified.

Any of the following can be specified:

JAVAINC += <name>.h
: The <name>.h header file will be created in the O.Common subdirectory.

USR_JAVAHFLAGS += <name>
: The javah option <name> will be used on the javah tool command line.

4.6.33.1 Example

In this example, the C header xx_yy_zz.h will be created in the $(COMMON_DIR) subdirectory from the class xx.yy.zz (i.e. the java class file $(INSTALL_JAVA)/xx/yy/zz.class)). The option "-old" will tell javah to create old JDK1.0 style header files.

```
JAVAINC = xx_yy_zz.h
USR_JAVAHFLAGS = -old
```

4.7 Table of Makefile definitions

Definitions given below containing <osclass> are used when building for target archs of a specific osclass, and the <osclass> part of the name should be replaced by the desired osclass, e.g. solaris, vxWorks, etc. If a _DEFAULT setting is given but a particular <osclass> requires that the default not apply and there are no items in the definition that apply for that <osclass>, the value "-nil-" should be specified in the relevant Makefile definition.

Build Option	Description
Products to be built (host type archs only)	
`PROD`	products (names without execution suffix) to build and install. Specify xyz to build executable xyz on Unix and xyz.exe on WIN32
`PROD_<osclass>`	os class specific products to build and install for <osclass> archs only
`PROD_DEFAULT`	products to build and install for archs with no PROD_<osclass> specified
`PROD_IOC`	products to build and install for ioc type archs
`PROD_IOC_<osclass>`	os specific products to build and install for ioc type archs
`PROD_IOC_DEFAULT`	products to build and install for ioc type arch systems with no PROD_IOC_<osclass> specified

Build Option	Description
PROD_HOST	products to build and install for host type archs.
PROD_HOST_<osclass>	os class specific products to build and install for <osclass> type archs
PROD_HOST_DEFAULT	products to build and install for arch with no PROD_HOST_<osclass> specified
Test products to be built	
TESTPROD	test products (names without execution suffix) to build but not install
TESTPROD_<osclass>	os class specific test products to build but not install
TESTPROD_DEFAULT	test products to build but not install for archs with no TESTPROD_<osclass> specified
TESTPROD_IOC	test products to build and install for ioc type archs
TESTPROD_IOC_<osclass>	os specific test products to build and install for ioc type archs
TESTPROD_IOC_DEFAULT	test products to build and install for ioc type arch systems with no TESTPROD_IOC_<osclass> specified
TESTPROD_HOST	testproducts to build and install for host type archs.
TESTPROD_HOST_<osclass>	os class specific testproducts to build and install for <osclass> type archs
TESTPROD_HOST_DEFAULT	test products to build and install for arch with no TESTPROD_HOST_<osclass> specified
TESTSCRIPTS	test scripts (names with .t suffix) to build but not install
TESTSCRIPTS_<osclass>	os class specific test scripts to build but not install
TESTSCRIPTS_DEFAULT	test scripts to build but not install for archs with no TESTSCRIPTS_<osclass> specified
TESTSCRIPTS_IOC	test scripts to build and install for ioc type archs
TESTSCRIPTS_IOC_<osclass>	os specific test scripts to build and install for ioc type archs
TESTSCRIPTS_IOC_DEFAULT	test scripts to build and install for ioc type arch systems with no TESTSCRIPTS_IOC_<osclass> specified
TESTSCRIPTS_HOST	test scripts to build and install for host type archs.
TESTSCRIPTS_HOST_<osclass>	os class specific testscripts to build and install for <osclass> type archs
TESTSCRIPTS_HOST_DEFAULT	test scripts to build and install for arch with no TESTSCRIPTS_HOST_<osclass> specified
Libraries to be built	
LIBRARY	name of library to build and install. The name should NOT include a prefix or extension e.g. specify Ca to build libCa.a on Unix, Ca.lib, CaObj.lib, or Ca.dll on WIN32
LIBRARY_<osclass>	os specific libraries to build and install

Build Option	Description
LIBRARY_DEFAULT	libraries to build and install for archs with no LIBRARY_<osclass> specified
LIBRARY_IOC	name of library to build and install for ioc type archs. The name should NOT include a prefix or extension e.g. specify Ca to build libCa.a on Unix, Ca.lib,CaObj.lib, or Ca.dll on WIN32
LIBRARY_IOC_<osclass>	os specific libraries to build and install for ioc type archs
LIBRARY_IOC_DEFAULT	libraries to build and install for ioc type arch systems with no LIBRARY_IOC_<osclass> specified
LIBRARY_HOST	name of library to build and install for host type archs. The name should NOT include a prefix or extension, e.g. specify Ca to build libCa.a on Unix, Ca.lib, CaObj.lib, or Ca.dll on WIN32
LIBRARY_HOST_<osclass>	os class specific libraries to build and install for host type archs
LIBRARY_HOST_DEFAULT	libraries to build and install for host type arch systems with no LIBRARY_HOST_<osclass> specified
SHARED_LIBRARIES	build shared libraries? Must be YES or NO
SHRLIB_VERSION	shared library version number
Loadable libraries to be built	
LOADABLE_LIBRARY	name of loadable library to build and install. The name should NOT include a prefix or extension e.g. specify Ca to build libCa.so on Unix and Ca.dll on WIN32
LOADABLE_LIBRARY_<osclass>	os specific loadable libraries to build and install
LOADABLE_LIBRARY_DEFAULT	loadable libraries to build and install for archs with no LOADABLE_LIBRARY_<osclass> specified
LOADABLE_LIBRARY_HOST	name of loadable library to build and install for host type archs. The name should NOT include a prefix or extension, e.g. specify test to build libtest.so on Unix and test.dll on WIN32
LOADABLE_LIBRARY_HOST_<osclass>	os class specific loadable libraries to build and install for host type archs
LOADABLE_LIBRARY_HOST_DEFAULT	loadable libraries to build and install for host type arch systems with no LOADABLE_LIBRARY_HOST_<osclass> specified
Combined object files (vxWorks only)	
OBJLIB	name of a combined object file library and corresponding munch file to build and install. The name will have a Library suffix appended
OBJLIB_vxWorks	same as OBJLIB
OBJLIB_SRCS	source files to build the OBJLIB
OBJLIB_OBJS	object files to include in OBJLIB
Product and library source files	
SRCS	source files to build all PRODs and LIBRARYs

Build Option	Description
SRCS_<osclass>	osclass specific source files to build all PRODs and LIBRARYs
SRCS_DEFAULT	source file to build all PRODs and LIBRARYs for archs with no SRCS_<osclass> specified
USR_SRCS	source files to build all PRODs and LIBRARYs
USR_SRCS_<osclass>	osclass specific source files to build all PRODs and LIBRARYs
USR_SRCS_DEFAULT	source file to build all PRODs and LIBRARYs for archs with no SRCS_<osclass> specified
PROD_SRCS	source files to build all PRODs
PROD_SRCS_<osclass>	osclass specific source files to build all PRODs
PROD_SRCS_DEFAULT	source files needed to build PRODs for archs with no SRCS_<osclass> specified
LIB_SRCS	source files for building LIBRARY (e.g. LIB_SRCS=la.c lb.c lc.c)
LIB_SRCS_<osclass>	os-specific library source files
LIB_SRCS_DEFAULT	library source files for archs with no LIB_SRCS_<osclass> specified
LIBSRCS	source files for building LIBRARY (deprecated)
LIBSRCS_<osclass>	os-specific library source files (deprecated)
LIBSRCS_DEFAULT	library source files for archs with no LIBSRCS_<osclass> specified (deprecated)
<name>_SRCS	source files to build a specific PROD or LIBRARY
<name>_SRCS_<osclass>	os specific source files to build a specific PROD or LIBRARY
<name>_SRCS_DEFAULT	source files needed to build a specific PROD or LIBRARY for archs with no <prod>_SRCS_<osclass> specified
Product and library object files	
USR_OBJS	object files, specified without suffix, to build all PRODs and LIBRARYs
USR_OBJS_<osclass>	osclass specific object files, specified without suffix, to build all PRODs and LIBRARYs
USR_OBJS_DEFAULT	object files, specified without suffix, needed to build PRODs and LIBRARYs for archs with no OBJS_<osclass> specified
PROD_OBJS	object files, specified without suffix, to build all PRODs
PROD_OBJS_<osclass>	osclass specific object files, specified without suffix, to build all PRODs
PROD_OBJS_DEFAULT	object files, specified without suffix, needed to build PRODs for archs with no OBJS_<osclass> specified
LIB_OBJS	object files, specified without suffix, for building all LIBRARYs (e.g. LIB_OBJS+=$(AB_BIN)/la $(AB_BIN)/lb)
LIB_OBJS_<osclass>	os-specific library object files, specify without suffix,

Build Option	Description
LIB_OBJS_DEFAULT	library object files, specified without suffix, for archs with no LIB_OBJS_<osclass> specified
<name>_OBJS	object files, specified without suffix, to build a specific PROD or LIBRARY
<name>_OBJS_<osclass>	os specific object files, specified without suffix, to build a specific PROD or LI|BRARY
<name>_OBJS_DEFAULT	object files, without suffix, needed to build a specific PROD or LIBRARY for archs with no <prod>_OBJS_<osclass> specified
Product and library R3.13 combined object files	
USR_OBJLIBS	combined object files with filenames that do not have a suffix, needed for building all PRODs and LIBRARYs (e.g. USR_OBJLIBS+=$(XYZ_BIN)/xyzLib)
USR_OBJLIBS_<osclass>	os-specific combined object files with filenames that do not have a suffix for building all PRODs and LIBRARYs
USR_OBJLIBS_DEFAULT	combined object files with filenames that do not have a suffix, for archs with no USR_OBJLIBS_<osclass> specified for building all PRODs and LIBRARYs
PROD_OBJLIBS	combined object files with filenames that do not have a suffix, needed for building all PRODs (e.g. PROD_OBJLIBS+=$(XYZ_BIN)/xyzLib)
PROD_OBJLIBS_<osclass>	os-specific combined object files with filenames that do not have a suffix for building all PRODs
PROD_OBJLIBS_DEFAULT	combined object files with filenames that do not have a suffix, for archs with no PROD_OBJLIBS_<osclass> specified for building all PRODs
LIB_OBJLIBS	combined object files with filenames that do not have a suffix, needed for building all LIBRARYs (e.g. LIB_OBJLIBS+=$(XYZ_BIN)/xyzLib)
LIB_OBJLIBS_<osclass>	os-specific combined object files with filenames that do not have a suffix for building all LIBRARYs
LIB_OBJLIBS_DEFAULT	combined object files with filenames that do not have a suffix, for archs with no LIB_OBJLIBS_<osclass> specified for building all LIBRARYs
<name>_OBJLIBS	combined object files with filenames that do not have a suffix, needed to build a specific PROD or LIBRARY
<name>_OBJLIBS_<osclass>	os specific combined object files with filenames that do not have a suffix, to build a specific PROD or LI|BRARY
<name>_OBJLIBS_DEFAULT	combined object files with filenames that do not have a suffix, needed to build a specific PROD or LIBRARY for archs with no <name>_OBJLIBS_<osclass> specified
<name>_LDOBJS	combined object files with filenames that do not have a suffix, needed to build a specific PROD or LIBRARY (deprecated)

Build Option	Description
`<name>_LDOBJS_<osclass>`	os specific combined object files with filenames that do not have a suffix, to build a specific PROD or LI|BRARY (deprecated)
`<name>_LDOBJS_DEFAULT`	combined object files with filenames that do not have a suffix, needed to build a specific PROD or LIBRARY for archs with no <name>_LDOBJS_<osclass> specified (deprecated)
Product and library dependant libraries	
`<name>_DIR`	directory to search for the specified lib. (For libs listed in all PROD_LIBS, LIB_LIBS, <name>_LIBS and USR_LIBS listed below)
`USR_LIBS`	load libraries (e.g. Xt X11) for all products and libraries
`USR_LIBS_<osclass>`	os specific load libraries for all makefile links
`USR_LIBS_DEFAULT`	load libraries for systems with no USR_LIBS_<osclass> specified libs
`<name>_LIBS`	named prod or library specific ld libraries (e.g. probe_LIBS=X11 Xt)
`<name>_LIBS_<osclass>`	os-specific libs needed to link named prod or library
`<name>_LIBS_DEFAULT`	libs needed to link named prod or library for systems with no <name>_LIBS_<osclass> specified
`PROD_LIBS`	libs needed to link every PROD
`PROD_LIBS_<osclass>`	os-specific libs needed to link every PROD
`PROD_LIBS_DEFAULT`	libs needed to link every PROD for archs with no PROD_LIBS_<osclass> specified
`LIB_LIBS`	libraries to be linked with every library being created
`LIB_LIBS_<osclass>`	os class specific libraries to be linked with every library being created
`LIB_LIBS_DEFAULT`	libraries to be linked with every library being created for archs with no LIB_LIBS_<osclass> specified
`USR_SYS_LIBS`	system libraries (e.g. Xt X11) for all products and libraries
`USR_SYS_LIBS_<osclass>`	os class specific system libraries for all makefile links
`USR_SYS_LIBS_DEFAULT`	system libraries for archs with no `USR_SYS_LIBS_<osclass>` specified
`<name>_SYS_LIBS`	named prod or library specific system ld libraries
`<name>_SYS_LIBS_<osclass>`	os class specific system libs needed to link named prod or library
`<name>_SYS_LIBS_DEFAULT`	system libs needed to link named prod or library for systems with no `<name>_SYS_LIBS_<osclass>` specified
`PROD_SYS_LIBS`	system libs needed to link every PROD
`PROD_SYS_LIBS_<osclass>`	os class specific system libs needed to link every PROD
`PROD_SYS_LIBS_DEFAULT`	system libs needed to link every PROD for archs with no PROD_SYS_LIBS_<osclass> specified
`LIB_SYS_LIBS`	system libraries to be linked with every library being created

Build Option	Description
LIB_SYS_LIBS_<osclass>	os class specific system libraries to be linked with every library being created
LIB_SYS_LIBS_DEFAULT	system libraries to be linked with every library being created for archs with no LIB_SYS_LIBS_<osclass> specified
SYS_PROD_LIBS	system libs needed to link every PROD for all systems (deprecated)
SYS_PROD_LIBS_<osclass>	os class specific system libs needed to link every PROD (deprecated)
SYS_PROD_LIBS_DEFAULT	system libs needed to link every PROD for systems with no SYS_PROD_LIBS_<osclass> specified (deprecated)
Compiler flags	
USR_CFLAGS	C compiler flags for all systems
USR_CFLAGS_<T_A>	target architecture specific C compiler flags
USR_CFLAGS_<osclass>	os class specific C compiler flags
USR_CFLAGS_DEFAULT	C compiler flags for archs with no USR_CFLAGS_<osclass> specified
<name>_CFLAGS	file specific C compiler flags (e.g. xxxRecord_CFLAGS=-g)
<name>_CFLAGS_<T_A>	file specific C compiler flags for a specific target architecture
<name>_CFLAGS_<osclass>	file specific C compiler flags for a specific os class
USR_CXXFLAGS	C++ compiler flags for all systems (e.g. xyxMain_CFLAGS=-DSDDS)
USR_CXXFLAGS_<T_A>	otarget architecture specific C++ compiler flags
USR_CXXFLAGS_<osclass>	os-specific C++ compiler flags
USR_CXXFLAGS_DEFAULT	C++ compiler flags for systems with no USR_CXXFLAGS_<osclass> specified
<name>_CXXFLAGS	file specific C++ compiler flags
<name>_CXXFLAGS_<T_A>	file specific C++ compiler flags for a specific target architecture
<name>_CXXFLAGS_<osclass>	file specific C++ compiler flags for a specific osclass
USR_CPPFLAGS	C pre-processor flags (for all makefile compiles)
USR_CPPFLAGS_<T_A>	target architecture specific cpp flags
USR_CPPFLAGS_<osclass>	os specific cpp flags
USR_CPPFLAGS_DEFAULT	cpp flags for systems with no USR_CPPFLAGS_<osclass> specified
<name>_CPPFLAGS	file specific C pre-processor flags (e.g. xxxRecord_CPPFLAGS=-DDEBUG)
<name>_CPPFLAGS_<T_A>	file specific cpp flags for a specific target architecture
<name>_CPPFLAGS_<osclass>	file specific cpp flags for a specific os class
USR_INCLUDES	directories, with -I prefix, to search for include files (e.g. -I$(EPICS_EXTENSIONS_INCLUDE))

Build Option	Description
USR_INCLUDES_<osclass>	directories, with -I prefix, to search for include files for a specific os class
USR_INCLUDES_DEFAULT	directories, with -I prefix, to search for include files for systems with no <name>_INCLUDES_<osclass> specified
<name>_INCLUDES	directories, with -I prefix, to search for include files when building a specific object file (e.g. -I$(MOTIF_INC))
<name>_INCLUDES_<T_A>	file specific directories, with -I prefix, to search for include files for a specific target architecture
<name>_INCLUDES_<osclass>	file specific directories, with -I prefix, to search for include files for a specific os class
HOST_WARN	Are compiler warning messages desired for host type builds? (YES or NO) (default is YES)
CROSS_WARN	C cross-compiler warning messages desired (YES or NO) (default YES)
HOST_OPT	Is host build compiler optimization desired (default is NO optimization)
CROSS_OPT	Is cross-compiler optimization desired (YES or NO) (default is NO optimization)
CMPLR	C compiler selection, TRAD, ANSI or STRICT (default is STRICT)
CXXCMPLR	C++ compiler selection, NORMAL or STRICT (default is STRICT)
Linker options	
USR_LDFLAGS	linker options (for all makefile links)
USR_LDFLAGS_<osclass>	os specific linker options (for all makefile links)
USR_LDFLAGS_DEFAULT	linker options for systems with no USR_LDFLAGS_<osclass> specified
PROD_LDFLAGS	prod linker options
PROD_LDFLAGS_<osclass>	os specific prod linker options
PROD_LDFLAGS_DEFAULT	prod linker options for systems with no PROD_LDFLAGS_<osclass> specified
LIB_LDFLAGS	library linker options
LIB_LDFLAGS_<osclass>	os specific library linker options
LIB_LDFLAGS_DEFAULT	library linker options for systems with no LIB_LDFLAGS_<osclass> specified
<name>_LDFLAGS	prod or library specific linker options
<name>_LDFLAGS_<osclass>	prod or library specific linker flags for a specific os class
<name>_LDFLAGS_DEFAULT	linker options for systems with no <name>_LDFLAGS_<osclass> specified
STATIC_BUILD	Is static build desired (YES or NO) (default is NO). On win32 if STATIC_BUILD=YES then set SHARED_LIBRARIES=NO)

Build Option	Description
Header files to be installed	
INC	list of include files to install into $(INSTALL_DIR)/include
INC_<osclass>	os specific includes to installed under $(INSTALL_DIR)/include/os/<osclass>
INC_DEFAULT	include files to install where no INC_<osclass> is specified
Perl, csh, tcl etc. script installation	
SCRIPTS	scripts to install for all systems
SCRIPTS_<osclass>	os-specific scripts to install
SCRIPTS_DEFAULT	scripts to install for systems with no SCRIPTS_<osclass> specified
SCRIPTS_IOC	scripts to install for ioc type archs.
SCRIPTS_IOC_<osclass>	os specific scripts to install for ioc type archs
SCRIPTS_IOC_DEFAULT	scripts to install for ioc type arch systems with no SCRIPTS_IOC_<osclass> specified
SCRIPTS_HOST	scripts to install for host type archs. T
SCRIPTS_HOST_<osclass>	os class specific scripts to install for host type archs
SCRIPTS_HOST_DEFAULT	scripts to install for host type arch systems with no OBJS_HOST_<osclass> specified
TCLLIBNAME	list of tcl scripts to install into $(INSTALL_DIR)/lib/<osclass> (Unix hosts only)
TCLINDEX	name of tcl index file to create from TCLLIBNAME scripts
Object files	The names in the following OBJS definitions should NOT include a suffix (.o or.obj).
OBJS	object files to build and install for all system.
OBJS_<osclass>	os-specific object files to build and install.
OBJS_DEFAULT	object files to build and install for systems with no OBJS_<osclass> specified.
OBJS_IOC	object files to build and install for ioc type archs.
OBJS_IOC_<osclass>	os specific object files to build and install for ioc type archs
OBJS_IOC_DEFAULT	object files to build and install for ioc type arch systems with no OBJS_IOC_<osclass> specified
OBJS_HOST	object files to build and install for host type archs. T
OBJS_HOST_<osclass>	os class specific object files to build and install for host type archs
OBJS_HOST_DEFAULT	object files to build and install for host type arch systems with no OBJS_HOST_<osclass> specified
Documentation	

Build Option	Description
DOCS	text files to be installed into the $(INSTALL_DIR)/doc directory
HTMLS_DIR	name install Hypertext directory name i.e. $(INSTALL_DIR)/html/ $(HTMLS_DIR)
HTMLS	hypertext files to be installed into the $(INSTALL_DIR)/html/ $(HTMLS_DIR) directory
TEMPLATES_DIR	template directory to be created as $(INSTALL_DIR)/templates/ $(TEMPLATE_DIR)
TEMPLATES	template files to be installed into $(TEMPLATE_DIR)
Database Definition files	
DBD	database definition files to be installed or created and installed into $(INSTALL_DBD).
DBDINC	names, without suffix, of menus or record database definitions and headers to be installed or created and installed.
USR_DBDFLAGS	optional flags for dbExpand. Currently only include path (-I <path>) and macro substitution (-S <substitution>) are supported.
DBD_INSTALLS	files from specified directory to install into $(INSTALL_DBD) (e.g. DBD_INSTALLS = $(APPNAME)/dbd/test.dbd
Database Files	
DB	database files to be installed or created and installed into $(INSTALL_DB).
DB_INSTALLS	files from specified directory to install into $(INSTALL_DB) (e.g. DB_INSTALLS = $(APPNAME)/db/test.db
Options for other programs	
YACCOPT	yacc options
LEXOPT	lex options
SNCFLAGS	state notation language, snc, options
<name>_SNCFLAGS	product specific state notation language options
E2DB_FLAGS	e2db options
SCH2EDIF_FLAGS	sch2edif options
RANLIBFLAGS	ranlib options
Facilities for building Java programs	
CLASSES	names of Java class files to be built and installed
TESTCLASSES	names of Java class files to be built
JAVAINC	names of C header file to be created in O.Common subdirectory
JAR	name of Jar file to be built

Build Option	Description
JAR_INPUT	names of files to be included in JAR
JAR_MANIFEST	name of manifest file for JAR
USR_JAVACFLAGS	javac tool options
USR_JAVAHFLAGS	javah tool options
Facilities for Windows 95/NT resource (.rc) files	
RCS	resource files (<name>.rc) needed to build every PROD and LIBRARY
RCS_<osclass>	resource files (<name>.rc) needed to build every PROD and LIBRARY for ioc type archs
RCS_DEFAULT	resource files needed to build every PROD and LIBRARY for ioc type arch systems with no RCS_<osclass> specified
<name>_RCS	resource files needed to build a specific PROD or LIBRARY
<name>_RCS_<osclass>	os specific resource files to build a specific PROD or LIBRARY
<name>_RCS_DEFAULT	resource files needed to build a specific PROD or LIBRARY for ioc type arch systems with no RCS_<osclass> specified
Other definitions:	
USR_VPATH	list of directories
BIN_INSTALLS	files from specified directories to be instaledl into $(INSTALL_BIN) (e.g. BIN_INSTALLS = $(EPICS_BASE_BIN)/aiRecord$(OBJ))
BIN_INSTALLS_<osclass>	os class specific files from specified directories to be installed into $(INSTALL_BIN)
BIN_INSTALLS_DEFAULT	files from specified directories to be installed into $(INSTALL_BIN) for target archs with no BIN_INSTALLS_<osclass> specified
LIB_INSTALLS	files from specified directories to be installed into $(INSTALL_LIB)
LIB_INSTALLS_<osclass>	os class specific files from specified directories to be installed into $(INSTALL_LIB)
LIB_INSTALLS_DEFAULT	files from specified directories to be installed into $(INSTALL_LIB) for target archs with no LIB_INSTALLS_<osclass> specified
TARGETS	files to create but not install
INSTALL_LOCATION	installation directory (defaults to $(TOP))

4.8 Configuration Files

4.8.1 Base Configure Directory

The base/configure directory has the following directory structure:

```
base/
   configure/
      os/
      tools/
```

4.8.2 Base Configure File Descriptions

The configure files contain definitions and make rules to be included in the various makefiles.

`CONFIG.CrossCommon`
Definitions for all hosts and all targets for a cross build (host different than target).

`CONFIG.gnuCommon`
Definitions for all hosts and all targets for builds using the gnu compiler.

`CONFIG_ADDONS`
Definitions which setup the variables that have <osclass> and DEFAULT options.

`CONFIG_BASE`
EPICS base specific definitions.

`CONFIG_BASE_VERSION`
Definitions for the version number of EPICS base. This file is used for creating epicsVersion.h which is installed into base/include.

`CONFIG_COMMON`
Definitions common to all builds.

`CONFIG_ENV`
Default definitions of the EPICS environment variables. This file is used for creating envData.c which is included in the Com library.

`CONFIG_SITE`
File in which you add to or modify make variables in EPICS base. A definition normally overridden is:

```
CROSS_COMPILER_TARGET_ARCHS =
```

`CONFIG_SITE_ENV`
Defaults for site specific definitions of EPICS environment variables. This file is used for creating envData.c which is included in the Com library.

`CONFIG`
Include statements for all the other configure files. You can override any definitions in other CONFIG* files by placing override definitions at the end of this file.

`RELEASE`
Specifies the location of external products such as Tornado II and external <tops> such as EPICS base.

`RULES`
This file just includes the appropriate rules configuration file.

`RULES.Db`
Rules for building and installing database and database definition files. Databases generated from templates and/or CapFast schematics are supported.

`RULES_ARCHS`
Definitions and rules which allow building the make target for each target architecture.

`RULES_BUILD`
Build rules for the Makefiles

RULES_DIRS
: Definitions and rules which allow building the make targets in each subdirectory. This file is included by Makefiles in directories with subdirectories to be built.

RULES_JAVA
: Definitions and rules which allow building java class files and java jar files.

RULES_TOP
: Rules specific to a <top> level directory e.g. uninstall and tar. It also includes the RULES_DIRS file.

RULES.ioc
: Rules which allow building in the iocBoot/<iocname> directory of an ioc application.

Makefile
: Definitions to allow creation of CONFIG_APP_INCLUDE and installtion of the CONFIG* files into the $(INSTALL_LOCATION) directory.

4.8.3 Base configure/os File Descriptions

The configure/os directory contains os specific make definitions. The naming convention for the files in this directory is CONFIG.<host>.<target> where <host> is either the arch for a specific host system or Common for all supported host systems and <target> is either the arch for a specific target system or Common for all supported target systems.

For example, the file CONFIG.Common.vxWorks-pentium will contain make definitions to be used for builds on all host systems when building for a vxWorks-pentium target system.

Also, if a group of host or target files have the same make definitions these common definitions can be moved to a new file which is then included in each host or target file. An example of this is all Unix hosts which have common definitions in a CONFIG.UnixCommon.Common file and all vxWorks targets with definitions in CONFIG.Common.vxWorksCommon.

The base/configure/os directory contains the following os-arch specific definitions

CONFIG.<host>.<target>
: Specific host-target build definitions

CONFIG.Common.<target>
: Specific target definitions for all hosts

CONFIG.<host>.Common
: Specific host definitions for all targets

CONFIG.UnixCommon.Common
: Definitions for Unix hosts and all target

CONFIG.<host>.vxWorksCommon
: Specific host definitions for all vx targets

CONFIG_COMPAT
: R3.13 arch compatibility definitions

CONFIG_SITE.<host>.<target>
: Site specific host-target definitions

CONFIG_SITE.Common.<target>
: Site specific target defs for all hosts

CONFIG_SITE.<host>.Common
: Site specific host defs for all targets

4.8.4 Base configure/tool File Descriptions

The configure/tools directory contains Perl script tools used for the build. The tools currently in this directory are:

convertRelease.pl
: This Perl script does consistency checks for the external <top> definitions in the RELEASE file and generates include directory, bin directory, and library directory definitions for these external <top>s. These definitions are

included into the CONFIG file for use by the application Makefiles.This script also creates -include statements for RULES_BUILD files from the external <top> definitions in the RELEASE file.

`cp.pl`
This Perl script copies an existing file.

`cvsclean.pl`
This perl script traverses a directory structure removing all .#* cvs files.

`filterWarnings.pl`
This is a perl script that filters compiler warning output (for HP-UX).

`fullpathname.pl`
This perl script returns the fullpathname of a file.

`installEpics.pl`
This is a Perl script that installs build created files into the install directories.

`makeIncludeDbd.pl`
This perl script creates an include dbd file from file names

`makeMakefile.pl`
This is a perl script that creates a Makefile in the created O.<arch> directories.

`makeMakefileInclude.pl`
This perl script creates a file to be included by Makefiles. This file contains a build target's specific definitions and dependencies.

`mkdir.pl`
This perl script creates a directory like the Unix mkdir command.

`mkmf.pl`
This perl script generates include file dependencies for targets from source file include statements.

`munch.pl`
This is a perl script that creates a ctdt.c file for vxWorks target arch builds which lists the c++ static constructors and destructors. See munching in the vxWorks documentation for more information.

`mv.pl`
This perl script renames an existing file.

`replaceVAR.pl`
This is a perl script that changes VAR(xxx) style macros in CapFast generated databases into the $(xxx) notation used in EPICS databases.

`rm.pl`
This perl script quietly removes an existing file.

4.9 Build Documentation Files

4.9.1 Base Documentation Directory

The base/documentation directory contains README files to help users setup and build epics/base.

4.9.2 Base Documentation File Descriptions

The files currently in the base/documentation directory are:

`README.1st`
Instructions for setup and building epics base

`README.html`
html version of README.1st

`README.WIN32`

Microsoft WIN32 specific instructions

`README.niCpu030`
NI cpu030 specific instructions

`README.hpux`
HPUX 11 (hpux-parisc) specific instructions

`README.darwin.html`
Installation notes for Mac OS X (Darwin)

`BuildingR3.13AppsWithR3.14.html`
Describes how to modify a R3.13 vxWorks application so that it builds with release R3.14.1.

`ConvertingR3.13AppsToR3.14.html`
Describes how to convert a R3.13 vxWorks application so that it contains a R3.14 configure directory and R3.14 Makefiles and builds with R3.14.1.

`ConvertingR3.14.0alpha2AppsTobeta1.html`
Describes how to modify a R3.14.0alpha1 application so that it builds with release R3.14.0beta1.

`ConvertingR3.14.0beta1AppsTobeta2.html`
Describes how to modify a R3.14.0beta1 application so that it builds with release R3.14.0beta2.

`ConvertingR3.14.0beta2AppsToR3.14.1.html`
Describes how to modify a R3.14.0beta2 application so that it builds with release R3.14.1.

`ConvertingR3.14.*AppsToR3.14.*.html`
Describes how to modify a R3.14.* application so that it builds with next release after R3.14.*.

`BuildingR3.13ExtensionsWithR3.14.html`
Describes how to modify a R3.13 extension so that it builds with release R3.14.1.

`RELEASE_NOTES.html`
Describes changes in the R3.14.1 release

`KnownProblems.html`
List of known problems in EPICS base R3.14.1.

`ReleaseChecklist.html`
Checklist of things that must be done when creating a new release of EPICS Base.

`TSdriver.html`
Synchronized Time Stamp Support documentation

4.10 Startup Files

4.10.1 Base Startup Directory

The base/startup directory contains scripts to help users set the required environment variables and path. The appropriate startup files should be executed before any EPICS builds.

4.10.2 Base Startup File Descriptions

The scripts currently in the base/startup directory are:

`EpicsHostArch`
c shell script to set EPICS_HOST_ARCH environment variable

`EpicsHostArch.pl`
perl script to set EPICS_HOST_ARCH environment variable

`Site.profile`
Unix bourne shell script to set path and environment variables

`Site.cshrc`

Unix c shell script to set path and environment variables

`borland.bat`

WIN32 bat file to set path and environment variables for building with Borland C++ compiler

`win32.bat`

WIN32 bat file to set path and environment variables for building with MS Visual C++ compilers

Chapter 5: Database Locking, Scanning, And Processing

5.1 Overview

Before describing particular components of the IOC software, it is helpful to give an overview of three closely related topics: Database locking, scanning, and processing. Locking is done to prevent two different tasks from simultaneously modifying related database records. Database scanning is the mechanism for deciding when records should be processed. The basics of record processing involves obtaining the current value of input fields and outputting the current value of output fields. As records become more complex so does the record processing.

One powerful feature of the DATABASE is that records can contain links to other records. This feature also causes considerable complication. Thus, before discussing locking, scanning, and processing, record links are described.

5.2 Record Links

A database record may contain links to other records. Each link is one of the following types:

- INLINK
  OUTLINK
  INLINKs and OUTLINKs can be one of the following:
  - constant link
    Not discussed in this chapter
  - database link
    A link to another record in the same IOC.
  - channel access link
    A link to a record in another IOC. It is accessed via a special IOC client task. It is also possible to force a link to be a channel access link even it references a record in the same IOC.
  - hardware link
    Not discussed in this chapter
- FWDLINK
  A forward link refers to a record that should be processed whenever the record containing the forward link is processed. The following types are supported:
  - constant link
    Ignored.
  - database link
    A link to another record in the same IOC.
  - channel access link
    A link to a record in another IOC or a link forced to be a channel access link. Unless the link references the PROC field it is ignored. If it does reference the PROC field a channel access put with a value of 1 is issued.

Links are defined in file `link.h`.

NOTE: This chapter discusses mainly database links.

5.3 Database Links

Database links are referenced by calling one of the following routines:

- **dbGetLink**: The value of the field referenced by the input link retrieved.
- **dbPutLink**: The value of the field referenced by the output link is changed.
- **dbScanPassive**: The record referred to by the forward link is processed if it is passive.

A forward link only makes sense when it refers to a passive record that the should be processed when the record containing the link is processed. For input and output links, however, two other attributes can be specified by the application developer, process passive and maximize severity.

5.3.1 Process Passive

Process passive (`PP` or `NPP`), is either `TRUE` or `FALSE`. It determines if the linked record should be processed before getting a value from an input link or after writing a value to an output link. The linked record will be processed, via a call to `dbProcess`, only if the record is a passive record and process passive is `TRUE`.

NOTE: Three other options may also be specified: CA, CP, and CPP. These options force the link to be handled like a Channel Access Link. See last section of this chapter for details.

5.3.2 Maximize Severity

Maximize severity (`MS` or `NMS`), is `TRUE` or `FALSE`. It determines if alarm severity is propagated across links. For input links the alarm severity of the record referred to by the link is propagated to the record containing the link. For output links the alarm severity of the record containing the link is propagated to the record referred to by the link. In either case, if the severity is changed, the alarm status is set to `LINK_ALARM`.

The method of determining if the alarm status and severity should be changed is called ”maximize severity”. In addition to its actual status and severity, each record also has a new status and severity. The new status and severity are initially 0, which means `NO_ALARM`. Every time a software component wants to modify the status and severity, it first checks the new severity and only makes a change if the severity it wants to set is greater than the current new severity. If it does make a change, it changes the new status and new severity, not the current status and severity. When database monitors are checked, which is normally done by a record processing routine, the current status and severity are set equal to the new values and the new values reset to zero. The end result is that the current alarm status and severity reflect the highest severity outstanding alarm. If multiple alarms of the same severity are present the status reflects the first one detected.

5.4 Database Locking

The purpose of database locking is to prevent a record from being processed simultaneously by two different tasks. In addition, it prevents ”outside” tasks from changing any field while the record is being processed.

The following routines are provided for database locking.

```
dbScanLock(precord);
```

```
dbScanUnlock(precord);
```

The basic idea is to call `dbScanLock` before accessing database records and calling `dbScanUnlock` afterwords. Because of database links (Input, Output, and Forward) a modification to one record can cause modification to other records. Records linked together are placed in the same lock set. `dbScanLock` locks the entire lock set not just the record requested. `dbScanUnlock` unlocks the entire set.

The following rules determine when the lock routines must be called:

1. The periodic, I/O event, and event tasks lock before and unlock after processing:
2. `dbPutField` locks before modifying a record and unlocks afterwards.
3. `dbGetField` locks before reading and unlocks afterwards.
4. Any asynchronous record support completion routine must lock before modifying a record and unlock afterwards.

All records linked via `OUTLINKs` and `FWDLINKs` are placed in the same lock set. Records linked via `INLINK`s with `process_passive` or `maximize_severity` `TRUE` are also forced to be in the same lock set.

5.5 Database Scanning

Database scanning refers to requests that database records be processed. Four types of scanning are possible:

1. **Periodic** - Records are scanned at regular intervals.
2. **I/O event** - A record is scanned as the result of an I/O interrupt.
3. **Event** - A record is scanned as the result of any task issuing a `post_event` request.
4. **Passive** - A record is scanned as a result of a call to `dbScanPassive`. `dbScanPassive` will issue a record processing request if and only if the record is passive and is not already being processed.

A `dbScanPassive` request results from a task calling one of the following routines:

- **dbScanPassive**: Only record processing routines, `dbGetLink`, `dbPutLink`, and `dbPutField` call `dbScanPassive`. Record processing routines call it for each forward link in the record.
- **dbPutField**: This routine changes the specified field and then, if the field has been declared `process_passive`, calls `dbScanPassive`. Each field of each record type has the attribute `process_passive` declared `TRUE` or `FALSE` in the definition file. This attribute is a global property, i.e. the application developer has no control of it. This use of `process_passive` is used only by `dbPutField`. If `dbPutField` finds the record already active (this can happen to asynchronous records) and it is supposed to cause it to process, it arranges for it to be processed again, when the current processing completes.
- **dbGetLink**: If the link specifies process passive, this routine calls `dbScanPassive`. Whether or not `dbScanPassive` is called, it then obtains the specified value.
- **dbPutLink**: This routine changes the specified field. Then, if the link specifies process passive, it calls `dbScanPassive`. `dbPutLink` is only called from record processing routines. Note that this usage of `process_passive` is under the control of the application developer. If `dbPutLink` finds the record already active because of a `dbPutField` directed to this record then it arranges for the record to be processed again, when the current processing completes.

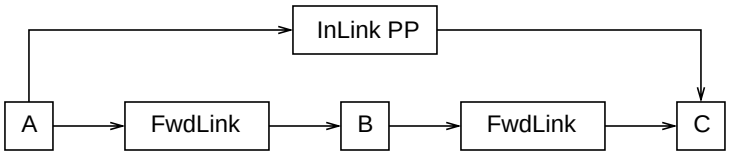
All non-record processing tasks (Channel Access, Sequence Programs, etc.) call `dbGetField` to obtain database values. `dbGetField` just reads values without asking that a record be processed.

5.6 Record Processing

A record is processed as a result of a call to `dbProcess`. Each record support module must supply a routine `process`. This routine does most of the work related to record processing. Since the details of record processing are record type specific this topic is discussed in greater detail in Chapter "Record Support" for details.

5.7 Guidelines for Creating Database Links

The ability to link records together is an extremely powerful feature of the IOC software. In order to use links properly it is important that the Application Developer understand how they are processed. As an introduction consider the following example :



Assume that A, B, and C are all passive records. The notation states that A has a forward link to B and B to C. C has an input link obtaining a value from A. Assume, for some reason, A gets processed. The following sequence of events occurs:

1. A begins processing. While processing a request is made to process B.
2. B starts processing. While processing a request is made to process C.
3. C starts processing. One of the first steps is to get a value from A via the input link.
4. At this point a question occurs. Note that the input link specifies process passive (signified by the `PP` after `InLink`). But process passive states that A should be processed before the value is retrieved. Are we in an infinite loop? The answer is no. Every record contains a field `pact` (processing active), which is set `TRUE` when record processing begins and is not set `FALSE` until all processing completes. When C is processed A still has `pact` `TRUE` and will not be processed again.
5. C obtains the value from A and completes its processing. Control returns to B.
6. B completes returning control to A
7. A completes processing.

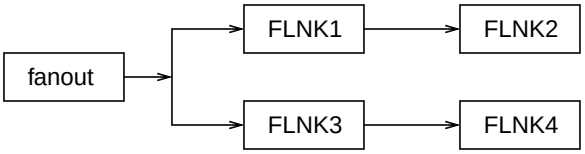
This brief example demonstrates that database links needs more discussion.

5.7.1 Rules Relating to Database Links

5.7.1.1 Processing Order

The processing order is guaranteed to follow the following rules:

1. Forward links are processed in order from left to right and top to bottom. For example the following records are processed in the order `FLNK1`, `FLNK2`, `FLNK3`, `FLNK4` .
2. If a record has multiple input links (calculation and select records) the input is obtained in the natural order. For example if the fields are named `INPA`, `INPB`, ..., `INPL`, then the links are read in the order A then B then C, etc. Thus if obtaining an input results in a record being processed, the processing order is guaranteed.



3. All input and output links are processed before the forward link.

5.7.1.2 Lock Sets

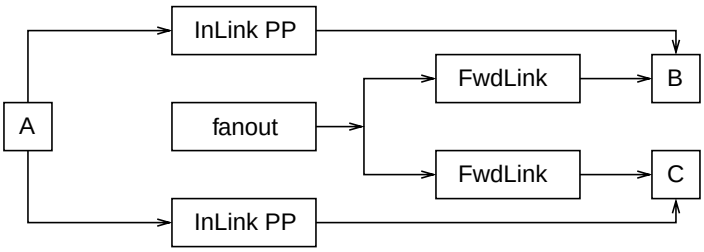
All records, except for the conditions listed in the next paragraph, linked together directly or indirectly are placed in the same lock set. When `dbScanLock` is called the entire set, not just the specified record, is locked. This prevents two different tasks from simultaneously modifying records in the same lock set.

5.7.1.3 PACT - processing active

Each record contains a field `pact`. This field is set `TRUE` at the beginning of record processing and is not set `FALSE` until the record is completely processed. In particular no links are processed with `pact FALSE`. This prevents infinite processing loops. The example given at the beginning of this section gives an example. It will be seen in the next two sections that `pact` has other uses.

5.7.1.4 Process Passive: Link option

Input and output links have an option called process passive. For each such link the application developer can specify process passive `TRUE` (`PP`) or process passive `FALSE` (`NPP`). Consider the following example

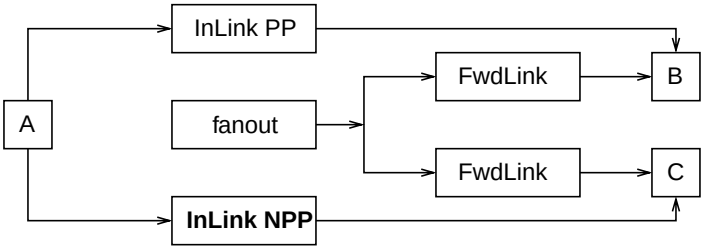


Assume that all records except fanout are passive. When the fanout record is processed the following sequence of events occur:

1. Fanout starts processing and asks that B be processed.
2. B begins processing. It calls `dbGetLink` to obtain data from A.
3. Because the input link has process passive true, a request is made to process A.
4. A is processed, the data value fetched, and control is returned to B
5. B completes processing and control is returned to fanout. Fanout asks that C be processed.
6. C begins processing. It calls `dbGetLink` to obtain data from A.
7. Because the input link has process passive `TRUE`, a request is made to process A.
8. A is processed, the data value fetched, and control is returned to C.
9. C completes processing and returns to fanout

10. The fanout completes

Note that A got processed twice. This is unnecessary. If the input link to C is declared no process passive then A will only be processed once. Thus we should have .



5.7.1.5 Process Passive: Field attribute

Each field of each database record type has an attribute called `process_passive`. This attribute is specified in the record definition file. It is not under the control of the application developer. This attribute is used only by `dbPutField`. It determines if a passive record will be processed after `dbPutField` changes a field in the record. Consult the record specific information in the record reference manual for the setting of individual fields.

5.7.1.6 Maximize Severity: Link option

Input and output links have an option called maximize severity. For each such link the application developer can specify maximize severity `TRUE` (`MS`) or maximize severity `FALSE` (`NMS`).

When database input or output links are defined, the application developer can specify if alarm severities should be propagated across links. For input links the severity is propagated from the record referred to by the link to the record containing the link. For output links the severity of the record containing the link is propagated to the record referenced by the link. The alarm severity is transferred only if the new severity will be greater than the current severity. If the severity is propagated the alarm status is set equal to `LINK_ALARM`.

5.8 Guidelines for Synchronous Records

A synchronous record is a record that can be completely processed without waiting. Thus the application developer never needs to consider the possibility of delays when he defines a set of related records. The only consideration is deciding when records should be processed and in what order a set of records should be processed.

The following reviews the methods available to the application programmer for deciding when to process a record and for enforcing the order of record processing.

1. A record can be scanned periodically (at one of several rates), via I/O event, or via Event.
2. For each periodic group and for each Event group the phase field can be used to specify processing order.
3. The application programmer has no control over the record processing order of records in different groups.
4. The disable fields (`SDIS`, `DISA`, and `DISV`) can be used to disable records from being processed. By letting the `SDIS` field of an entire set of records refer to the same input record, the entire set can be enabled or disabled simultaneously. See the Record Reference Manual for details.

5. A record (periodic or other) can be the root of a set of passive records that will all be processed whenever the root record is processed. The set is formed by input, output, and forward links.
6. The `process_passive` option specified for each field of each record determines if a passive record is processed when a `dbPutField` is directed to the field. The application developer must be aware of the possibility of record processing being triggered by external sources if `dbPutFields` are directed to fields that have `process_passive` `TRUE`.
7. The `process_passive` option for input and output links provides the application developer control over how a set of records are scanned.
8. General link structures can be defined. The application programmer should be wary, however, of defining arbitrary structures without carefully analyzing the processing order.

5.9 Guidelines for Asynchronous Records

The previous discussion does not allow for asynchronous records. An example is a GPIB input record. When the record is processed the GPIB request is started and the processing routine returns. Processing, however, is not really complete until the GPIB request completes. This is handled via an asynchronous completion routine. Lets state a few attributes of asynchronous record processing.

During the initial processing for all asynchronous records the following is done:

1. `pact` is set `TRUE`
2. Data is obtained for all input links
3. Record processing is started
4. The record processing routine returns

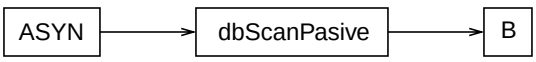
The asynchronous completion routine performs the following algorithm:

5. Record processing continues
6. Record specific alarm conditions are checked
7. Monitors are raised
8. Forward links are processed
9. `pact` is set `FALSE`.

A few attributes of the above rules are:

10. Asynchronous record processing does not delay the scanners.
11. Between the time record processing begins and the asynchronous completion routine completes, no attempt will be made to again process the record. This is because `pact` is `TRUE`. The routine `dbProcess` checks `pact` and does not call the record processing routine if it is `TRUE`. Note, however, that if `dbProcess` finds the record active 10 times in succession, it raises a `SCAN_ALARM`.
12. Forward and output links are triggered only when the asynchronous completion routine completes record processing.

With these rules the following works just fine:

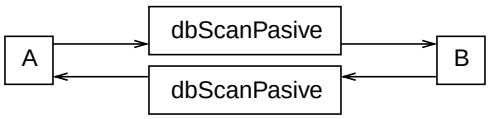


When `dbProcess` is called for record ASYN, processing will be started but `dbScanPassive` will not be called. Until the asynchronous completion routine executes any additional attempts to process ASYN are ignored. When the asynchronous callback is invoked the `dbScanPassive` is performed.

Problems still remain. A few examples are:

5.9.1 Infinite Loop

Infinite processing loops are possible.



Assume both A and B are asynchronous passive records and a request is made to process A. The following sequence of events occur.

1. A starts record processing and returns leaving `pact` `TRUE`.
2. Sometime later the record completion for A occurs. During record completion a request is made to process B. B starts processing and control returns to A which completes leaving its `pact` field `FALSE`.
3. Sometime later the record completion for B occurs. During record completion a request is made to process A. A starts processing and control returns to B which completes leaving its `pact` field `FALSE`.

Thus an infinite loop of record processing has been set up. It is up to the application developer to prevent such loops.

5.9.2 Obtain Old Data

A `dbGetLink` to a passive asynchronous record can get old data.

If A is a passive asynchronous record then the `dbGetLink` request forces `dbProcess` to be called for A. `dbProcess` starts the processing and returns. `dbGetLink` then reads the desired value which is still old because processing will only be completed at a later time.

5.9.3 Delays

Consider the following:

The second ASYN record will not begin processing until the first completes, etc. This is not really a problem except that the application developer must be aware of delays caused by asynchronous records. Again, note that scanners are not delayed, only records downstream of asynchronous records.

5.9.4 Task Abort

If the processing task aborts and the watch dog task cleans up before the asynchronous processing routine completes what happens? If the asynchronous routine completes before the watch dog task runs everything is okay. If it doesn't? This is a more general question of the consequences of having the watchdog timer restart a scan task. EPICS currently does not allow scanners to be automatically restarted.

5.10 Cached Puts

The rules followed by `dbPutLink` and `dbPutField` provide for "cached" puts. This is necessary because of asynchronous records. Two cases arise.

The first results from a `dbPutField`, which is a put coming from outside the database, i.e. Channel Access puts. If this is directed to a record that already has `pact TRUE` because the record started processing but asynchronous completion has not yet occurred, then a value is written to the record but nothing will be done with the value until the record is again processed. In order to make this happen `dbPutField` arranges to have the record reprocessed when the record finally completes processing.

The second case results from `dbPutLink` finding a record already active because of a `dbPutField` directed to the record. In this case `dbPutLink` arranges to have the record reprocessed when the record finally completes processing. If the record is already active because it appears twice in a chain of record processing, it is not reprocessed because the chain of record processing would constitute an infinite loop.

Note that the term caching not queuing is used. If multiple requests are directed to a record while it is active, each new value is placed in the record but it will still only be processed once, i.e. last value wins.

5.11 putNotify

dbPutNotify, which is called when a Channel Access client calls ca_put_callback, is a request to notify the caller when all records processed as a result of the put complete. Because of asynchronous records this can be complicated and the set of records that are processed because of a put may not be deterministic. The result of a dbPutNotify is the same as a dbPutField except for the following:

- dbPutNotifys are queued rather than cached. Thus when additional dbPutNotifys are directed to a record that already has an active dbPutNotify, they are queued. As each one finishes it releases the next one in the queue.
- If a dbPutNotify links to a record that is not active but has a dbPutNotify attached to it, then no attempt is made to process the record.

5.12 Channel Access Links

A channel access link is:

1. A record link that references a record in a different IOC.
2. A link that the application developer forces to be a channel access link.

A channel access client task (dbCa) handles all I/O for channel access links. It does the following:

- At IOC initialization dbCa issues channel access search requests for each channel access link.

- For each input link it establishes a channel access monitor. It uses `ca_field_type` and `ca_element_count` when it establishes the monitor. It also monitors the alarm status. Whenever the monitor is invoked the new data is stored in a buffer belonging to dbCa. When iocCore or the record support module asks for data the data is taken from the buffer and converted to the requested type.
- For each output link, a buffer is allocated the first time iocCore/record support issues a put and a channel access connection has been made. This buffer is allocated according to `ca_field_type` and `ca_element_count`. Each time iocCore/record support issues a put, the data is converted and placed in the buffer and a request is made to dbCa to issue a new ca_put.

Even if a link references a record in the same IOC it can be useful to force it to act like a channel access link. In particular the records will not be forced to be in the same lock set. As an example consider a scan record that links to a set of unrelated records, each of which can cause a lot of records to be processed. It is often NOT desirable to force all these records into the same lock set. Forcing the links to be handled as channel access links solves the problem.

CA links which connect between IOCs incur the extra overhead associated with message passing protocols, operating system calls, and network activity. In contrast, CA links which connect records in the same IOC are executed more efficiently by directly calling database access functions such as dbPutField() and dbGetField(), or by receiving callbacks directly from a database monitor subscription event queue.

Because channel access links interact with the database only via dbPutField, dbGetField, and a database monitor subscription event queue, their interaction with the database is fundamentally different from database links which are tightly integrated within the code that executes database records. For this reason and because channel access does not understand process passive or maximize severity, the semantics of channel access links are not the same as database links. Let's discuss the channel access semantics of INLINK, OUTLINK, and FWDLINK separately.

5.12.1 INLINK

The options for process passive are:

- **PP** or **NPP** - This link is made a channel access link because the referenced record is not found in the local IOC. It is not possible to honor PP, thus the link always acts like NPP.
- **CA** - Force the link to be a channel access link.
- **CP** - Force the link to be a channel access link and also request that the record containing the link be processed whenever a monitor occurs.
- **CPP** - Force the link to be a channel access link and also request that the record containing the link, if it is passive, be processed whenever a monitor occurs.

Maximize Severity is honored.

5.12.2 OUTLINK

The options for process passive are:

- **PP** or **NPP** - This link is made a channel access link because the referenced record is not found in the local IOC. It is not possible to honor PP thus the link always acts like NPP.
- **CA** - Force the link to be a channel access link.

Maximize Severity is not honored.

5.12.3 FWDLINK

A channel access forward link is honored only if it references the PROC field of a record. In that case a ca_put with a value of 1 is written each time a forward link request is issued.

The options for process passive are:

- **PP** or **NPP** - This link is made a channel access link because the referenced record is not found in the local IOC. It is not possible to honor PP thus it always acts like NPP.
- **CA** - Force the link to be a channel access link.

Maximize Severity is not honored.

Chapter 6: Database Definition

6.1 Overview

This chapter describes database definitions. The following definitions are described:

- Menu
- Record Type
- Device
- Driver
- Registrar
- Variable
- Function
- Breakpoint Table
- Record Instance

Record Instances are fundamentally different from the other definitions. A file containing record instances should never contain any of the other definitions and vice-versa. Thus the following convention is followed:

- **Database Definition File** - A file that contains any type of definition except record instances.
- **Record Instance File** - A file that contains only record instance definitions.

This chapter also describes utility programs which operate on these definitions

Any combination of definitions can appear in a single file or in a set of files related to each other via include files.

6.2 Brief Summary of Database Definition Syntax

```
path "path"
addpath "path"
include "filename"
#comment
menu(name) {
   include "filename"
   choice(choice_name,"choice_value")
   ...
}

recordtype(record_type) {
   include "filename"
   field(field_name,field_type) {
      asl(asl_level)
      initial("init_value")
```

```
         promptgroup(gui_group)
         prompt("prompt_value")
         special(special_value)
         pp(pp_value)
         interest(interest_level)
         base(base_type)
         size(size_value)
         extra("extra_info")
         menu(name)
      }
      ...
   }

   device(record_type,link_type,dset_name,”choice_string”)

   driver(drvet_name)

   registrar(function_name)

   variable(variable_name)

   breaktable(name) {
      raw_value eng_value
      ...
   }

#The Following defines a Record Instance

   record(record_type,record_name) {
      include "filename"
      field(field_name,"value")
      ...
   }
#NOTE: GDCT uses the keyword grecord instead of record
```

6.3 General Rules for Database Definition

6.3.1 Keywords

The following are keywords, i.e. they may not be used as values unless they are enclosed in quotes:

```
path
addpath
include
menu
choice
recordtype
field
device
driver
```

```
registrar
variable
breaktable
record
grecord
```

6.3.2 Unquoted Strings

In the summary section, some values are shown as quoted strings and some unquoted. The actual rule is that any string consisting of only the following characters does not have to be quoted unless it contains one of the above keywords:

```
a-z A-Z 0-9 _ - : . [ ] < > ;
```

These are also the legal characters for process variable names. Thus in many cases quotes are not needed.

6.3.3 Quoted Strings

A quoted string can contain any ascii character except the quote character ". The quote character itself can given by using \ as an escape. For example "\"" is a quoted string containing the single character ".

6.3.4 Macro Substitution

Macro substitutions are permitted inside quoted strings. Macro instances take the form:

```
$(name)
```

or

```
${name}
```

There is no distinction between the use of parentheses or braces for delimiters, although the two must match for a given macro instance. The macro name can be made up from other macros, for example:

```
$(name_$(sel))
```

A macro instance can also provide a default value that is used when no macro with the given name is defined. The default value can be defined in terms of other macros if desired, but cannot contain any unescaped comma characters. The syntax for specifying a default value is as follows:

```
$(name=default)
```

Finally macro instances can also contain definitions of other macros, which can (temporarily) override any existing values for those macros but are in scope only for the duration of the expansion of this macro instance. These definitions consist of `name=value` sequences separated by commas, for example:

```
$(abcd=$(a)$(b)$(c)$(d),a=A,b=B,c=C,d=D)
```

6.3.5 Escape Sequences

The database routines translate standard C escape sequences inside database field value strings only. The standard C escape sequences supported are:

```
\a \b \f \n \r \t \v \\ \? \' \" \ooo \xhh
```

`\ooo` represents an octal number with 1, 2, or 3 digits. `\xhh` represents a hexadecimal number with 1 or 2 digits.

6.3.6 Define before referencing

No item can be referenced until it is defined. For example a `recordtype` menu field can not reference a menu unless that menu definition has already been defined. Another example is that a record instance can not appear until the associated record type has been defined.

6.3.7 Multiple Definitions

If a particular menu, recordtype, device, driver, or breakpoint table is defined more than once, then only the first instance is used. Record instance definitions are cumulative, i.e. each time a new field value is encountered it replaces the previous value.

6.3.8 filename extension

By convention:

- Record instances files have the extension ".`db`"
- Database definition files have the extension ".`dbd`".

6.3.9 path addpath

The path follows the standard Unix convention, i.e. it is a list of directory names separated by colons (Unix) or semicolons (winXX).

Format:

```
path "dir:dir...:dir"
addpath "dir:dir...:dir
```

NOTE: In winXX the separator is ; instead of :

The `path` command specifies the current path. The `addpath` appends directory names to the current path. The path is used to locate the initial database file and included files. An empty `dir` at the beginning, middle, or end of a non-empty path string means the current directory. For example:

```
nnn::mmm    # Current directory is between nnn and mmm
:nnn        # Current directory is first
nnn:        # Current directory is last
```

Utilities which load database files (`dbExpand`, `dbLoadDatabase`, etc.) allow the user to specify an initial path. The `path` and `addpath` commands can be used to change or extend the initial path.

The initial path is determined as follows:

> If an initial path is specified, it is used. Else:
> If the environment variable `EPICS_DB_INCLUDE_PATH` is defined, it is used. Else:
> the default path is ".", i.e. the current directory.

The path is used unless the filename contains a / or \. The first directory containing the specified file is used.

6.3.10 include

Format:

```
include "filename"
```

An include statement can appear at any place shown in the summary. It uses the path as specified above.

6.3.11 comment

The comment symbol is "#". Whenever the comment symbol appears, it and all characters through the end of the line are ignored.

6.4 Menu

Format:

```
menu(name) {
   choice(choice_name,"choice_value")
   ...
}
```

Where:

name - Name for menu. This is the unique name identifying the menu. If duplicate definitions are specified, only the first is used.
choice_name - The name placed in the `enum` generated by `dbToMenuH` or `dbToRecordtypeH`
choice_value - The value associated with the choice.

Example:

```
menu(menuYesNo) {
   choice(menuYesNoNO,"NO")
   choice(menuYesNoYES,"YES")
}
```

6.5 Record Type

6.5.1 Format:

```
recordtype(record_type) {
   field(field_name,field_type) {
      asl(asl_level)
      initial("init_value")
      promptgroup(gui_group)
      prompt("prompt_value")
      special(special_value)
      pp(pp_value)
      interest(interest_level)
      base(base_type)
      size(size_value)
      extra("extra_info")
      menu("name")
```

```
    }
    ...
}
```

6.5.2 rules

- **asl** - Access Security Level. The default is `ASL1`. Access Security is discussed in a later chapter. Only two values are permitted for this field (`ASL0` and `ASL1`). Fields which operators normally change are assigned `ASL0`. Other fields are assigned `ASL1`. For example, the `VAL` field of an analog output record is assigned `ASL0` and all other fields `ASL1`. This is because only the `VAL` field should be modified during normal operations.
- **initial** - Initial Value.
- **promptgroup** - Prompt group to which field belongs. This is for use by Database Configuration Tools. This is defined only for fields that can be given values by database configuration tools. File `guigroup.h` contains all possible definitions. The different groups allow database configuration tools to present the user with groups of fields rather than all prompt fields. I don't know of any tool that currently uses groups.
- **prompt** - A prompt string for database configuration tools. Optional if `promptgroup` is not defined.
- **special** - If specified, then special processing is required for this field at run time.
- **pp** - Should a passive record be processed when Channel Access writes to this field? The default is `NO`.
- **interest** - Only used by the `dbpr` shell command.
- **base** - For integer fields, a base of `DECIMAL` or `HEX` can be specified. The default is `DECIMAL`.
- **size** - Must be specified for `DBF_STRING` fields.
- **extra** - Must be specified for `DBF_NOACCESS` fields.
- **menu** - Must be specified for `DBF_MENU` fields. It is the name of the associated menu.

6.5.3 definitions

- **record_type** - The unique name of the record type. If duplicates are specified, only the first definition is used.
- **field_name** - The field name. Only alphanumeric characters are allowed. When include files are generated, the field name is converted to lower case. Previous versions of EPICS required that field name be a maximum of four characters. Although this restriction no longer exists, problems may arrise with some Channel Access clients if longer field names are chosen.
- **field_type** - This must be one of the following values:
    - `DBF_STRING`
    - `DBF_CHAR`
    - `DBF_UCHAR`
    - `DBF_SHORT`
    - `DBF_USHORT`
    - `DBF_LONG`
    - `DBF_ULONG`
    - `DBF_FLOAT`
    - `DBF_DOUBLE`
    - `DBF_ENUM`
    - `DBF_MENU`
    - `DBF_DEVICE`
    - `DBF_INLINK`
    - `DBF_OUTLINK`
    - `DBF_FWDLINK`

    - DBF_NOACCESS
- **asl_level** - This must be one of the following values:
    - ASL0
    - ASL1 (default value)
- **init_value** - A legal value for data type.
- **prompt_value** - A prompt value for database configuration tools.
- **gui_group** - This must be one of the following:
    - GUI_COMMON
    - GUI_ALARMS
    - GUI_BITS1
    - GUI_BITS2
    - GUI_CALC
    - GUI_CLOCK
    - GUI_COMPRESS
    - GUI_CONVERT
    - GUI_DISPLAY
    - GUI_HIST
    - GUI_INPUTS
    - GUI_LINKS
    - GUI_MBB
    - GUI_MOTOR
    - GUI_OUTPUT
    - GUI_PID
    - GUI_PULSE
    - GUI_SELECT
    - GUI_SEQ1
    - GUI_SEQ2
    - GUI_SEQ3
    - GUI_SUB
    - GUI_TIMER
    - GUI_WAVE
    - GUI_SCAN

      NOTE: GUI types were invented with the intention of allowing database configuration tools to prompt for groups of fields and when a user selects a group the fields within the group. Since this feature has seldom been used, many record types have not assigned the correct GUI groups to some fields.
- **special_value** must be one of the following:
    - An integer value greater than 103. In this case, the record support special routine is called whenever the field is modified by database access. This feature is present only for compatibility. New support modules should use SPC_MOD.

      The following value disallows access to field.
    - SPC_NOMOD - This means that field can not be modified at runtime except by the record/device support modules for the record type.

      The following values are used for database common. They must NOT be used for record specific fields.
    - SPC_SCAN - Scan related field.
    - SPC_ALARMACK - Alarm acknowledgment field.

- SPC_AS - Access security field.

  The following value is used if record support wants to trap dbNameToAddr calls.
- SPC_DBADDR - This is set if the record support cvt_dbaddr routine should be called whenever dbNameToAddr is called, i.e. when code outside record/device support want to access the field.

  The following values all result in the record support special routine being called whenever database access modifies the field. The only reason for multiple values is that originally it seemed like a good idea. New support modules should only use SPC_MOD.
- SPC_MOD - Notify when modified, i.e. call the record support special routine whenever the field is modified by database access.
- SPC_RESET - a reset field is being modified.
- SPC_LINCONV - A linear conversion field is being modified.
- SPC_CALC - A calc field is being modified.

- **pp_value** - Should a passive record be processed when Channel Access writes to this field? The allowed values are:
  - NO (default)
  - YES
- **interest_level** - An interest level for the dbpr command.
- **base** - For integer type fields, the default base. The legal values are:
  - DECIMAL (Default)
  - HEX
- **size_value** - The number of characters for a DBF_STRING field.
- **extra_info** - For DBF_NOACCESS fields, this is the C language definition for the field. The definition must end with the fieldname in lower case.

6.5.4 Example

The following is the definition of the binary input record.

```
recordtype(bi) {
   include "dbCommon.dbd"
   field(INP,DBF_INLINK) {
      prompt("Input Specification")
      promptgroup(GUI_INPUTS)
      interest(1)
   }
   field(VAL,DBF_ENUM) {
      prompt("Current Value")
      promptgroup(GUI_INPUTS)
      asl(ASL0)
      pp(TRUE)
   }
   field(ZSV,DBF_MENU) {
      prompt("Zero Error Severity")
      promptgroup(GUI_ALARMS)
      pp(TRUE)
      interest(1)
      menu(menuAlarmSevr)
   }
```

```
field(OSV,DBF_MENU) {
   prompt("One Error Severity")
   promptgroup(GUI_BITS1)
   pp(TRUE)
   interest(1)
   menu(menuAlarmSevr)
}
field(COSV,DBF_MENU) {
   prompt("Change of State Svr")
   promptgroup(GUI_BITS2)
   pp(TRUE)
   interest(1)
   menu(menuAlarmSevr)
}
field(ZNAM,DBF_STRING) {
   prompt("Zero Name")
   promptgroup(GUI_CALC)
   pp(TRUE)
   interest(1)
   size(20)
}
field(ONAM,DBF_STRING) {
   prompt("One Name")
   promptgroup(GUI_CLOCK)
   pp(TRUE)
   interest(1)
   size(20)
}
field(RVAL,DBF_ULONG) {
   prompt("Raw Value")
   pp(TRUE)
}
field(ORAW,DBF_ULONG) {
   prompt("prev Raw Value")
   special(SPC_NOMOD)
   interest(3)
}
field(MASK,DBF_ULONG) {
   prompt("Hardware Mask")
   special(SPC_NOMOD)
   interest(1)
}
field(LALM,DBF_USHORT) {
   prompt("Last Value Alarmed")
   special(SPC_NOMOD)
   interest(3)
}
field(MLST,DBF_USHORT) {
   prompt("Last Value Monitored")
   special(SPC_NOMOD)
   interest(3)
}
field(SIOL,DBF_INLINK) {
```

```
      prompt("Sim Input Specifctn")
      promptgroup(GUI_INPUTS)
      interest(1)
   }
   field(SVAL,DBF_USHORT) {
      prompt("Simulation Value")
   }
   field(SIML,DBF_INLINK) {
      prompt("Sim Mode Location")
      promptgroup(GUI_INPUTS)
      interest(1)
   }
   field(SIMM,DBF_MENU) {
      prompt("Simulation Mode")
      interest(1)
      menu(menuYesNo)
   }
   field(SIMS,DBF_MENU) {
      prompt("Sim mode Alarm Svrty")
      promptgroup(GUI_INPUTS)
      interest(2)
      menu(menuAlarmSevr)
   }
}
```

6.6 Device

6.6.1 Format:

```
device(record_type,link_type,dset_name,”choice_string”)
   ...
```

6.6.2 definitions

- **record_type** - Record type. The combination of `record_type` and `choice_string` must be unique. If the same combination appears multiple times, the first definition is used.
- **link_type -** Link type. This must be one of the following:
  - `CONSTANT`
  - `PV_LINK`
  - `VME_IO`
  - `CAMAC_IO`
  - `AB_IO`
  - `GPIB_IO`
  - `BITBUS_IO`
  - `INST_IO`
  - `BBGPIB_IO`
  - `RF_IO`

    - `VXI_IO`
- **dset_name -** The exact name of the device support entry table without the trailing "`DSET`". Duplicates are not allowed.
- **choice_string** Choice string for database configuration tools. Note that it must be enclosed in "". Note that for a given record type, each `choice_string` must be unique.

6.6.3 Examples

```
device(ai,CONSTANT,devAiSoft,"Soft Channel")
device(ai,VME_IO,devAiXy566Se,"XYCOM-566 SE Scanned")
```

6.7 Driver

6.7.1 Format:

```
driver(drvet_name)
```

6.7.2 Definitions

- **drvet_name -** If duplicates are defined, only the first is used.

6.7.3 Examples

```
driver(drvVxi)
driver(drvXy210)
```

6.8 Registrar Declaration

6.8.1 Format:

```
registrar(function_name)
```

6.8.2 Definitions

- **function_name -** The name of an C function that accepts no arguments, returns void and has been exported from its source file with an epicsExportRegistrar declaration, e.g.

  ```
  static void myRegistrar(void);
  epicsExportRegistrar(myRegistrar);
  ```

This can be used to register functions for use by subroutine records or that can be invoked from iocsh. The example application described in Chapter 2.2, “Example IOC Application” on page 11" provides an example of how to register functions for subroutine records.

6.8.3 Example

```
registrar(asSub)
```

6.9 Variable Declaration

6.9.1 Format:

```
variable(variable_name[, type])
```

6.9.2 Definitions

- **variable_name** - The name of a C variable which has been exported from its source file with an epicsExportAddress declaration.
- **type** - The C variable type. If not present, **int** is assumed. Currently only **int** and **double** variables are supported.

This registers a diagnostic/configuration variable for device and driver support or a subroutine record subroutine so that the variable can be read and set with the iocsh var command (Section on page 249). The example application described in Section 2.2 on page 11 provides an example of how to register a debug variable for a subroutine record.

6.9.3 Example

In an application C source file:

```
#include <epicsExport.h>
.
.
static double myParameter;
epicsExportAddress(double, myParameter);
```

In an application database definition file:

```
variable(myParameter, double)
```

6.10 Function Declaration

6.10.1 Format:

```
function(function_name)
```

6.10.2 Definitions

- **function_name** - The name of a C function which has been exported from its source file with an epicsRegisterFunction declaration.

This registers a function so that it can be found in the function registry for use by records which refer to the function by name. The example application described in Chapter 2.2, “Example IOC Application” on page 11 provides an example of how to register functions for a subroutine record.

6.10.3 Example

In an application C source file:

```
#include <epicsExport.h>
.
.
static long myFunction(void *argp) {
.
.
}
epicsRegisterFunction(myFunction);
```

In an application database definition file:

```
function(myFunction
```

6.11 Breakpoint Table

6.11.1 Format:

```
breaktable(name) {
   raw_value eng_value
   ...
}
```

6.11.2 Definitions

- **name** - Name, which must be alpha-numeric, of the breakpoint table. If duplicates are specified the first is used.
- **raw_value** - The raw value, i.e. the actual ADC value associated with the beginning of the interval.
- **eng_value** - The engineering value associated with the beginning of the interval.

6.11.3 Example

```
breaktable(typeJdegC) {
    0.000000 0.000000
    365.023224 67.000000
    1000.046448 178.000000
    3007.255859 524.000000
```

```
    3543.383789 613.000000
    4042.988281 692.000000
    4101.488281 701.000000
}
```

6.12 Record Instance

6.12.1 Format:

```
record(record_type, record_name) {
   field(field_name, "field_value")
   info(info_name, "info_value")
   ...
}
```

6.12.2 definitions

- **record_type** - The record type.
- **record_name** - The record name. This must be composed of the following characters:
  `a-z A-Z 0-9 _ - + : [ ] < > ;`
  NOTE: If macro substitutions are used the name must be quoted.
  If duplicate definitions are given for the same record, then the last value given for each field is the value assigned to the field.
- **field_name** - A field name
- **field_value** - Depends on field type. Inside the double quotes the field value string may contain escaped C89 characters such as \", \t, \n, \064 and \x7e, and these will be translated appropriately when loading the database.
  - `DBF_STRING`
    Any ASCII string. If it exceeds the field length, it will be truncated.
  - `DBF_CHAR`, `DBF_UCHAR`, `DBF_SHORT`, `DBF_USHORT`, `DBF_LONG`, `DBF_ULONG`
    A string that represents a valid integer. The standard C conventions are applied, i.e. a leading 0 means the value is given in octal and a leading 0x means that value is given in hex.
  - `DBF_FLOAT`, `DBF_DOUBLE`
    The string must represent a valid floating point number.
  - `DBF_MENU`
    The string must be one of the valid choices for the associated menu.
  - `DBF_DEVICE`
    The string must be one of the valid device choice strings.
  - `DBF_INLINK`, `DBF_OUTLINK`
    `NOTES:`
    - In the field is INP or OUT then it is associated with field DTYP. Other DBF_INLINK and DBF_OUTLINK fields can be either CONSTANT or PV_LINKs
    - `DTYP` must be defined before the associated INP or OUT field.
    - Choosing the DTYP implicitly chooses a bus type.
    - A DTYP of CONSTANT can be either a constant or a PV_LINK.

    The allowed value depends on the bus type as follows:

- `CONSTANT`
  A constant valid for the field associated
- `PV_LINK`
  A value of the form:

  record.field process maximize

  `field, process`, and `maximize` are optional.
  The default value for `field` is `VAL`.
  `process` can have one of the following values:
  - `NPP` - No Process Passive (Default)
  - `PP` - Process Passive
  - `CA` - Force link to be a channel access link
  - `CP` - CA and process on monitor
  - `CPP` - CA and process on monitor if record is passive
    NOTES:
    CP and CPP are valid only for INLINKs.
    FWD_LINKs can be PP or CA. If a FWD_LINK is a channel access link it must reference the PROC field.

  `maximize` can have one of the following values
  - `NMS` - No Maximize Severity (Default)
  - `MS` - Maximize severity
- `VME_IO`
  #Ccard Ssignal @parm
  where:
  `card` - the card number of associated hardware module.
  `signal` - signal on card
  `parm` - An arbitrary character string of up to 31 characters.
  This field is optional and is device specific.
- `CAMAC_IO`
  #Bbranch Ccrate Nstation Asubaddress Ffunction @parm
  `branch`, `crate`, `station`, `subaddress`, and `function` should be obvious to `camac` users. `Subaddress` and `function` are optional (0 if not given). `Parm` is also optional and is device dependent (25 characters max).
- `AB_IO`
  #Llink Aadapter Ccard Ssignal @parm
  `link` - Scanner., i.e. vme scanner number
  `adapter` - Adapter. Allen Bradley also calls this rack
  `card` - Card within Allen Bradley Chassis
  `signal` - signal on card
  `parm` - An optional character string that is device dependent(27 char max)
- `GPIB_IO`
  #Llink Aaddr @parm
  `link` - gpib link, i.e. interface
  `addr` - GPIB address
  `parm` - device dependent character string (31 char max)
- `BITBUS_IO`
  #Llink Nnode Pport Ssignal @parm
  `link` - link, i.e. vme bitbus interface.
  `node` - bitbus node
  `port` - port on the node
  `signal` - signal on port
  `parm` - device specific character string(31 char max)

- `INST_IO`
  @parm
  `parm` - Device dependent character string(35 char max)
- `BBGPIB_IO`
  #Llink Bbbaddr Ggpibaddr @parm
  `link` - link, i.e. vme bitbus interface.
  `bbadddr` - bitbus address
  `gpibaddr` - gpib address
  `parm` - optional device dependent character string(31 char max)
- `RF_IO`
  `#Rcryo Mmicro Ddataset Eelement`
- `VXI_IO`
  #Vframe Cslot Ssignal @parm (Dynamic addressing)
  or
  `#Vla Signal @parm  (Static Addressing)`
  `frame` - VXI frame number
  `slot` - Slot within VXI frame
  `la` - Logical Address
  `signal` - Signal Number
  `parm` - device specific character string(25 char max)

- `DBF_FWDLINK`
  This is either not defined or else is a `PV_LINK`. See above for definitions.

- **info_name** - The name of an information item related to this record. See section 6.13 below for more on information items.
- **info_value** - Any ASCII string. IOC applications using this information item may place additional restrictions on the contents of the string.

6.12.3 Examples

```
record(ai,STS_AbAiMaS0) {
   field(SCAN,".1 second")
   field(DTYP,"AB-1771IFE-4to20MA")
   field(INP,"#L0 A2 C0 S0 F0 @")
   field(PREC,"4")
   field(LINR,"LINEAR")
   field(EGUF,"20")
   field(EGUL,"4")
   field(EGU,"MilliAmps")
   field(HOPR,"20")
   field(LOPR,"4")
}
record(ao,STS_AbAoMaC1S0) {
   field(DTYP,"AB-1771OFE")
   field(OUT,"#L0 A2 C1 S0 F0 @")
   field(LINR,"LINEAR")
   field(EGUF,"20")
   field(EGUL,"4")
   field(EGU,"MilliAmp")
   field(DRVH,"20")
   field(DRVL,"4")
   field(HOPR,"20")
   field(LOPR,"4")
```

```
   info(autosaveFields,"VAL")
}
record(bi,STS_AbDiA0C0S0) {
   field(SCAN,"I/O Intr")
   field(DTYP,"AB-Binary Input")
   field(INP,"#L0 A0 C0 S0 F0 @")
   field(ZNAM,"Off")
   field(ONAM,"On")
}
```

6.13 Record Information Item

Information items provide a way to attach named string values to individual record instances that are loaded at the same time as the record definition. They can be attached to any record without having to modify the record type, and can be retrieved by programs running on the IOC (they are not visible via Channel Access at all). Each item attached to a single record must have a unique name by which it is addressed, and database access provides routines to allow a record's info items to be scanned, searched for, retrieved and set. At runtime a `void*` pointer can also be associated with each item, although only the string value can be initialized from the record definition when the database is loaded.

6.14 Record Attribute

Each record type can have a set of record attributes. Each attribute is a "psuedo" field that can be accessed via database and channel access. An attribute is given a name the acts like a field name which has the same value for every instance of the record type. Two attributes are generated automatically for each record type: RTYP and VERS. The value for RTYP is the record type name. The default value for VERS is "none specified", which can be changed by record support. Record support can call the following routine to create new attributes or change existing attributes:

```
long dbPutAttribute(char *recordTypename,
    char *name,char*value)
```

The arguments are:

`recordTypename` - The name of recordtype.
`name` - The attribute name, i.e. the psuedo field name.
`value` - The value assigned to the attribute.

6.15 Breakpoint Tables - Discussion

The menu `menuConvert` is used for field `LINR` of the `ai` and `ao` records. These records allow raw data to be converted to/from engineering units via one of the following:

1. No Conversion.
2. Slope Conversion.
3. Linear Conversion.
4. Breakpoint table.

Other record types can also use this feature. The first choice specifies no conversion; the second and third are both linear conversions, the difference being that for Slope conversion the user specifies the conversion slope and offset directly, whereas for Linear conversions these are calculated by the device support from the requsted Engineering Units range and the device support's knowledge of the hardware conversion range. The remaining choices are assumed to be the names of breakpoint tables. If a breakpoint table is chosen, the record support modules calls `cvtRawToEngBpt` or `cvtEngToRawBpt`. You can look at the `ai` and `ao` record support modules for details.

If a user wants to add additional breakpoint tables, then the following should be done:

- Copy the `menuConvert.dbd` file from EPICS `base/src/bpt`
- Add definitions for new breakpoint tables to the end
- Make sure modified `menuConvert.dbd` is loaded into the IOC instead of EPICS version.

It is only necessary to load a breakpoint file if a record instance actually chooses it. It should also be mentioned that the Allen Bradley IXE device support misuses the `LINR` field. If you use this module, it is very important that you do not change any of the EPICS supplied definitions in `menuConvert.dbd`. Just add your definitions at the end.

If a breakpoint table is chosen, then the corresponding breakpoint file must be loaded into the IOC before `iocInit` is called.

Normally, it is desirable to directly create the breakpoint tables. However, sometimes it is desirable to create a breakpoint table from a table of raw values representing equally spaced engineering units. A good example is the Thermocouple tables in the OMEGA Engineering, INC Temperature Measurement Handbook. A tool `makeBpt` is provided to convert such data to a breakpoint table.

The format for generating a breakpoint table from a data table of raw values corresponding to equally spaced engineering values is:

```
!comment line
<header line>
<data table>
```

The header line contains the following information:

- **Name**: An alphanumeric ascii string specifying the breakpoint table name
- **Low Value Eng**: Engineering Units Value for first breakpoint table entry
- **Low Value Raw**: Raw value for first breakpoint table entry
- **High Value Eng**: Engineering Units: Highest Value desired
- **High Value Raw**: Raw Value for High Value Eng
- **Error**: Allowed error (Engineering Units)
- **First Table**: Engineering units corresponding to first data table entry
- **Last Table**: Engineering units corresponding to last data table entry
- **Delta Table**: Change in engineering units per data table entry

An example definition is:

```
"TypeKdegF" 32 0 1832 4095 1.0 -454 2500 1
<data table>
```

The breakpoint table can be generated by executing

```
makeBpt bptXXX.data
```

The input file must have the extension of data. The output filename is the same as the input filename with the extension of dbd.

Another way to create the breakpoint table is to include the following definition in a Makefile.Vx:

```
BPTS += bptXXX.dbd
```

NOTE: This requires the naming convention that all data tables are of the form bpt<name>.data and a breakpoint table bpt<name>.dbd.

6.16 Menu and Record Type Include File Generation.

6.16.1 Introduction

Given a file containing menus, `dbToMenuH` generates an include file that can be used by any code which uses the associated menus. Given a file containing any combination of menu definitions and record type definitions, `dbToRecordtypeH` generates an include file that can be used by any code which uses the menus and record type.

EPICS base uses the following conventions for managing menu and recordtype definitions. Users generating local record types are encouraged to do likewise.

- Each menu that is either for fields in database common (for example `menuScan`) or is of global use (for example `menuYesNo`) is defined in a separate file. The name of the file is the same as the menu name with an extension of `dbd`. The name of the generated include file is the menu name with an extension of `h`. Thus `menuScan` is defined in a file `menuScan.dbd` and the generated include file is named `menuScan.h`
- Each record type definition is defined in a separate file. In addition, this file contains any menu definitions that are used only by that record type. The name of the file is the same as the recordtype name followed by `Record.dbd`. The name of the generated include file is the same name with an extension of `h`. Thus `aoRecord` is defined in a file `aoRecord.dbd` and the generated include file is named `aoRecord.h`. Since `aoRecord` has a private menu called `aoOIF`, the `dbd` file and the generated include file have definitions for this menu. Thus for each record type, there are two source files (`xxxRecord.dbd` and `xxxRecord.c`) and one generated file (`xxxRecord.h`).

Before continuing, it should be mentioned that Application Developers don't have to execute `dbToMenuH` or `dbToRecordtypeH`. If a developer uses the proper naming conventions, it is only necessary to add definitions to their `Makefile`. Consult the chapter on the EPICS Build Facility for details..

6.16.2 dbToMenuH

This tool is executed as follows:

```
dbToMenuH -Idir -Smacsub menuXXX.dbd
```

It generates a file which has the same name as the input file but with an extension of `h`. Multiple `-I` options can be specified for an include path and multiple `-S` options for macro substitution.

For example `menuPriority.dbd`, which contains the definitions for processing priority contains:

```
menu(menuPriority) {
   choice(menuPriorityLOW,"LOW")
   choice(menuPriorityMEDIUM,"MEDIUM")
   choice(menuPriorityHIGH,"HIGH")
}
```

The include file, `menuPriority.h`, generated by `dbToMenuH` contains:

```
#ifndef INCmenuPriorityH
#define INCmenuPriorityH
typedef enum {
   menuPriorityLOW,
   menuPriorityMEDIUM,
```

```
   menuPriorityHIGH,
}menuPriority;
#endif /*INCmenuPriorityH*/
```

Any code that needs to use the priority menu values should use these definitions.

6.16.3 dbToRecordtypeH

This tool is executed as follows:

```
dbTorecordtypeH -Idir -Smacsub xxxRecord.dbd
```

It generates a file which has the same name as the input file but with an extension of `h`. Multiple `-I` options can be specified for an include path and multiple `-S` options for macro substitution.

For example `aoRecord.dbd`, which contains the definitions for the analog output record contains:

```
menu(aoOIF) {
   choice(aoOIF_Full,"Full")
   choice(aoOIF_Incremental,"Incremental")
}
recordtype(ao) {
   include "dbCommon.dbd"
   field(VAL,DBF_DOUBLE) {
      prompt("Desired Output")
      asl(ASL0)
      pp(TRUE)
   }
   field(OVAL,DBF_DOUBLE) {
      prompt("Output Value")
   }
   ... (Many more field definitions
   }
}
```

The include file, `aoRecord.h`, generated by `dbToRecordtypeH` contains:

```
#include "ellLib.h"
#include "epicsMutex.h"
#include "link.h"
#include "epicsTime.h"
#include "epicsTypes.h"

#ifndef INCaoOIFH
#define INCaoOIFH
typedef enum {
        aoOIF_Full,
        aoOIF_Incremental,
}aoOIF;
#endif /*INCaoOIFH*/
#ifndef INCaoH
#define INCaoH
typedef struct aoRecord {
        char            name[29]; /*Record Name*/
        ... Remaining fields in database common
```

```
        double          val;    /*Desired Output*/
        double          oval;   /*Output Value*/
        ... remaining record specific fields
} aoRecord;
#define aoRecordNAME    0
... defines for remaining fields in database common
#define aoRecordVAL     42
#define aoRecordOVAL    43
... defines for remaining record specific fields
#ifdef GEN_SIZE_OFFSET
int aoRecordSizeOffset(dbRecordType *pdbRecordType)
{
    aoRecord *prec = 0;
  pdbRecordType->papFldDes[0]->size=sizeof(prec->name);
  pdbRecordType->papFldDes[0]->offset=
      (short)((char *)&prec->name - (char *)prec);
  ... code to compute size&offset for other fields in dbCommon
  pdbRecordType->papFldDes[42]->size=sizeof(prec->val);
  pdbRecordType->papFldDes[42]->offset=
      (short)((char *)&prec->val - (char *)prec);
  pdbRecordType->papFldDes[43]->size=sizeof(prec->oval);
  pdbRecordType->papFldDes[43]->offset=
      (short)((char *)&prec->oval - (char *)prec);
  ... code to compute size&offset for remaining fields
  pdbRecordType->rec_size = sizeof(*prec);
  return(0);
}
#endif /*GEN_SIZE_OFFSET*/
```

The analog output record support module and all associated device support modules should use this include file. No other code should use it. Let's discuss the various parts of the file.:

- The `enum` generated from the menu definition should be used to reference the value of the field associated with the menu.
- The `typedef` and `structure` defining the record are used by record support and device support to access fields in an analog output record.
- A `#define` is present for each field within the record. This is useful for the record support routines that are passed a pointer to a `DBADDR` structure. They can have code like the following:

```
switch (dbGetFieldIndex(pdbAddr)) {
   case aoRecordVAL :
      ...
       break;
   case aoRecordXXX:
      ...
      break;
   default:
      ...
}
```

The C source routine `aoRecordSizeOffset` is automatically called when a record type file is loaded into an IOC. Thus user code does not have to be aware of this routine except for the following convention: The associate record support module MUST include the statements:

```
#define GEN_SIZE_OFFSET
#include "xxxRecord.h"
#undef GEN_SIZE_OFFSET
```

This convention ensures that the routine is defined exactly once.

6.17 dbExpand

`dbExpand -Idir -Smacsub -ooutfile file1 file2 ...`

Multiple `-I` options can be specified for an include path, and multiple `-S` options for macro substitution. If no output filename is specified with `-ooutfile` then the output will go to stdout. Note that the environment variable `EPICS_DB_INCLUDE_PATH` can also be used in place of the `-I` options.

NOTE: This is supported only on the host.

This command reads all the input files and then writes a file containing the definitions for all information described by the input files. The output content differs from the input in that comment lines do not appear and all include files are expanded.

This routine is extremely useful if an IOC is not using NFS for the `dbLoadDatabase` commands. It takes more than 2 minutes to load the `base/rec/base.dbd` file into an IOC if NFS is not used. If `dbExpand` creates a local `base.dbd` file, it takes about 7 seconds to load (25 MHZ 68040 IOC).

6.18 dbLoadDatabase

`dbLoadDatabase(char *dbdfile, char *path, char *substitutions)`

NOTES:

- IOC Only
- Using a path on a vxWorks ioc does not work very well.
- Both path and substitutions can be null.
- `dbdfile` may contain environment variable macros of the form `${MOTOR}` which will be expanded before the file is opened.

This command loads a database file containing any of the definitions given in the summary at the beginning of this chapter.

`As each line of dbdfile` is read, the substitutions specified in `substitutions` is performed. The substitutions are specified as follows:

```
"var1=sub1,var2=sub3,..."
```

Variables are specified in the dbfile as $(variable_name). If the substitution string

```
"a=1,b=2,c=\"this is a test\""
```

were used, any variables $(a), $(b), $(c) would be substituted with the appropriate data.

6.18.1 EXAMPLE

For example, let `test.db` be:

```
record(ai,"$(pre)testrec1")
record(ai,"$(pre)testrec2")
record(stringout,"$(pre)testrec3") {
   field(VAL,"$(STR)")
   field(SCAN,"$(SCAN)")
}
```

Then issuing the command:

```
dbLoadDatabase("test.db",0,"pre=TEST,STR=test,SCAN=Passive")
```

gives the same results as loading:

```
record(ai,"TESTtestrec1")
record(ai,"TESTtestrec2")
record(stringout,"TESTtestrec3") {
   field(VAL,"test")
   field(SCAN,"Passive")
}
```

6.19 dbLoadRecords

```
dbLoadRecords(char* dbfile, char* substitutions)
```

NOTES:

- IOC Only.
- `dbfile` must contain only record instances.
- `dbfile` may contain environment variable macros of the form `${MOTOR}` which will be expanded before the file is opened.

6.20 dbLoadTemplate

```
dbLoadTemplate(char* template_def)
```

NOTES:

- IOC Only.
- MSI can be used to expand templates on the host.

`dbLoadTemplate` reads a template definition file. This file contains rules about loading database instance files, which contain `$(xxx)` macros, and performing substitutions.

`template_def` contains the rules for performing substitutions on the instance files. For convenience two formats are provided. The format is either:

```
file name.template {
   { var1=sub1_for_set1, var2=sub2_for_set1, var3=sub3_for_set1, ... }
   { var1=sub1_for_set2, var2=sub2_for_set2, var3=sub3_for_set2, ... }
   { var1=sub1_for_set3, var2=sub2_for_set3, var3=sub3_for_set3, ... }
}
```

or:

```
file name.template {
   pattern { var1, var2, var3, ... }
   { sub1_for_set1, sub2_for_set1, sub3_for_set1, ... }
   { sub1_for_set2, sub2_for_set2, sub3_for_set2, ... }
   { sub1_for_set3, sub2_for_set3, sub3_for_set3, ... }
}
```

The first line (`file name.template`) specifies the record instance input file. The file name may appear inside double quotation marks; these are required if the name contains any characters that are not in the following set, or if it contains environment variable macros of the form `${ENV_VAR_NAME}` which are to be expanded before the file is opened:

```
a-z A-Z 0-9 _ + - . / \ : ; [ ] < >
```

Each set of definitions enclosed in `{}` is variable substitution for the input file. The input file has each set applied to it to produce one composite file with all the completed substitutions in it. Version 1 should be obvious. In version 2, the variables are listed in the "`pattern{}`" line, which must precede the braced substitution lines. The braced substitution lines contains sets which match up with the `pattern{}` line.

6.20.1 EXAMPLE

Two simple template file examples are shown below. The examples specify the same substitutions to perform: `this=sub1` and `that=sub2` for a first set, and `this=sub3` and `that=sub4` for a second set.

```
file test.template {
   { this=sub1,that=sub2 }
   { this=sub3,that=sub4 }
}

file test.template {
   pattern{this,that}
   {sub1,sub2}
   {sub3,sub4 }
}
```

Assume that the file `test.template` contains:

```
record(ai,"$(this)record") {
   field(DESC,"this = $(this)")
}
record(ai,"$(that)record") {
   field(DESC,"this = $(that)")
}
```

Using `dbLoadTemplate` with either input is the same as defining the records:

```
record(ai,"sub1record") {
   field(DESC,"this = sub1")
}
record(ai,"sub2record") {
   field(DESC,"this = sub2")
}

record(ai,"sub3record") {
```

```
      field(DESC,"this = sub3")
   }
   record(ai,"sub4record") {
      field(DESC,"this = sub4")
   }
```

6.21 dbReadTest

`dbReadTest -Idir -Smacsub file.dbd ... file.db ...`

This utility can be used to check for correct syntax in database definition and database instance files. It just reads all the specified files

Multiple `-I,` and `-S` options can be specified. An arbitrary number of database definition and database instance files can be specified.

Chapter 7: IOC Initialization

7.1 Overview - Environments requiring a main program

If a main program is required (most likely on all environments except vxWorks and RTEMS), then initialization is performed by statements residing in startup scripts passed to `iocsh`. An example main program is:

```
int main(int argc,char *argv[])
{
    if(argc>=2) {
        iocsh(argv[1]);
        epicsThreadSleep(.2);
    }
    iocsh(NULL);
    epicsExit(0)
    return 0;
}
```

The first call to `iocsh` executes commands from the startup script filename which must be passed as an argument to the program. The second call to `iocsh` with a `NULL` argument puts `iocsh` into interactive mode. This allows the user to issue the commands described in chapter "IOC Test Facilities" as well as some additional commands like `help`.

The command file passed is usually called the startup script, and contains statements like these:

```
< envPaths
cd ${TOP}
dbLoadDatabase "dbd/appname.dbd"
appname_registerRecordDeviceDriver pdbbase
dbLoadRecords "db/file.db", "macro=value"
cd ${TOP}/iocBoot/${IOC}
iocInit
```

The envPaths file is automatically generated in the IOC boot directory and defines several environment variables that are useful later in the startup script. The definitions shown below are always provided; additional entries will be created for each support module referenced in the application's configure/RELEASE file:

```
epicsEnvSet("ARCH","linux-x86")
epicsEnvSet("IOC","iocname")
epicsEnvSet("TOP","/path/to/application")
epicsEnvSet("EPICS_BASE","/path/to/base")
```

7.2 Overview - vxWorks

After vxWorks is loaded at IOC boot time, commands like the following, normally in the vxWorks startup script, are issued to load and initialize the application code:

```
# Many vxWorks board support packages need the following:
#cd <full path to IOC boot directory>
< cdCommands
cd topbin
ld < appname.munch

cd top
dbLoadDatabase "dbd/appname.dbd"
appname_registerRecordDeviceDriver pdbbase
dbLoadRecords "db/file.db", "macro=value"

cd startup
iocInit
```

The `cdCommands` script is automatically generated in the IOC boot directory and defines several vxWorks global variables that allow `cd` commands to various locations, and also sets several environment variables. The definitions shown below are always provided; additional entries will be created for each support module referenced in the application's configure/RELEASE file:

```
startup = "/path/to/application/iocBoot/iocname"
putenv "ARCH=vxWorks-68040"
putenv "IOC=iocname"
top = "/path/to/application"
putenv "TOP=/path/to/application"
topbin = "/path/to/application/bin/vxWorks-68040"
epics_base = "/path/to/base"
putenv "EPICS_BASE=/path/to/base"
epics_basebin = "/path/to/base/bin/vxWorks-68040"
```

The `ld` command in the startup script loads EPICS core, the record, device and driver support the IOC needs, and any application specific modules that have been linked into it.

`dbLoadDatabase` loads database definition files describing the record/device/driver support used by the application..

`dbLoadRecords` loads record instance definitions.

`iocInit` initializes the various epics components and starts the IOC running.

7.3 Overview - RTEMS

RTEMS applications can start up in many different ways depending on the board-support package for a particular piece of hardware. Systems which use the Cexp package can be treated much like vxWorks. Other systems first read initialization parameters from non-volatile memory or from a BOOTP/DHCP server. The exact mechanism depends upon the BSP. TFTP or NFS filesystems are then mounted and the IOC shell is used to read commands from a startup script. The location of this startup script is specified by a initialization parameter. This script is often similar or identical to the one used with vxWorks. The RTEMS startup code calls

```
epicsRtemsInitPreSetBootConfigFromNVRAM(struct rtems_bsdnet_config *);
```

just before setting the initialization parameters from non-volatile memory, and

```
epicsRtemsInitPostSetBootConfigFromNVRAM(struct rtems_bsdnet_config *);
```

just after setting the initialization parameters. An application may provide either or both of these routines to perform any custom initialization required. These function prototypes and some useful external variable declarations can be found in thje header file `epicsRtemsInitHooks.h`

7.4 IOC Initialization

An IOC is normally started with the `iocInit` command shown in the startup scritps above, but it can also be initialized using the `iocBuild` command, which puts it into a quiescent state without actually starting the various internal threads from running. From this state the `iocRun` command can be used to bring it online very quickly. A running IOC can also be quiesced using the `iocPause` command, which freezes all internal operations; at this point `iocRun` can be used to restart it from where it left off, or the IOC should be shut down (exit the program or reboot on vxWorks/RTEMS). Most device support and drivers have not been written with the possibility of pausing the IOC in mind though, so this feature may not be safe to use on an IOC which talks to external devices or software.

IOC initialization performs the following functions:

7.4.1 Set Task Flags

Sets the `epicsThreadIsOkToBlock` flag, and calls `epicsSignalInstallSigHupIgnore` which on Unix architectures prevents the process from shutting down when it received a HUP signal.

At this point, `initHooks(initHookAtBeginning)` is called.

7.4.2 General Purpose Modules

Calls `coreRelese` which prints a message showing which version of iocCore is being used.

Calls `taskwdInit` to start the task watchdog. This accepts requests to watch other tasks. It runs periodically and checks to see if any of the tasks is suspended. If so it issues an error message, and can also optionally invoke callback routines registered by the task itself or by other software that is interested in the state of the IOC. See “Task Watchdog” on page 235 for details.

Starts the general purpose callback tasks by calling `callbackInit`. Three tasks are started at different scheduling priorities.

`initHooks(initHookAfterCallbackInit)` is called.

7.4.3 Channel Access Links

Calls `dbCaLinkInit`. The initializes the module that handles database channel access links, but does not allow its task to run yet.

`initHooks(initHookAfterCaLinkInit)` is called.

7.4.4 Driver Support

`initDrvSup` locates each device driver entry table and calls the `init` routine of each driver.

`initHooks(initHookAfterInitDrvSup)` is called.

7.4.5 Record Support

`initRecSup` locates each record support entry table and calls the `init` routine of each record type.

`initHooks(initHookAfterInitRecSup)` is called.

7.4.6 Device Support

`initDevSup` locates each device support entry table and calls the `init` routine with an argument specifying that this is the initial call.

`initHooks(initHookAfterInitDevSup)` is called.

7.4.7 Database Records

`initDatabase` makes three passes over the database performing the following functions:

1. Initializes the fields `RSET`, `RDES`, `MLOK`, `MLIS`, `PACT` and `DSET` for each record.
   Calls record support's `init_record` (first pass).
2. Convert each `PV_LINK` into a `DB_LINK` or `CA_LINK`
   Calls any extended device support's `add_record` routine.
3. Calls record support's `init_record` (second pass).

Finally `initDatabase` registers an epicsAtExit routine to shut down the database when the IOC application exits.

Next `dbLockInitRecords` is called to create the lock sets.

Then `dbBkptInit` is run to initialize the database debugging module.

`initHooks(initHookAfterInitDatabase)` is called.

7.4.8 Device Support again

`initDevSup` locates each device support entry table and calls the `init` routine with an argument specifying that this is the finish call.

`initHooks(initHookAfterFinishDevSup)` is called.

7.4.9 Scanning and Access Security

The periodic, event, and I/O event scanners are initialized by calling `scanInit`, but the scan tasks are not allowed to run yet.

A call to `asInit` initailizes access security. If this reports failure, the IOC initialization is aborted.

`dbPutNotifyInit` initializes support for put notification.

After a short delay, `initHooks(initHookAfterScanInit)` is called.

7.4.10 Initial Processing

`initialProcess` processes all records that have PINI set true.

`initHooks(initHookAfterInitialProcess)` is called.

7.4.11 Channel Access Server

The Channel Access server is started by calling `rsrv_init`, but its tasks are not allowed to run so it does not announce its presence to the network yet.

At this point, the IOC has been initialized but is still quiescent. If started with `iocBuild` this command completes here.

7.4.12 Enable Record Processing

If the `iocRun` command is used to bring the IOC out of its initial quiescent state, it starts here.

The routines `scanRun` and `dbCaRun` are called in turn to enable their associated tasks.

The global variable `interruptAccept` is set `TRUE`. Until this time all I/O interrupts have been ignored.

If the IOC is starting for the first time, `initHooks(initHookAfterInterruptAccept)` is called.

7.4.13 Enable CA Server

The Channel Access server tasks are allowed to run by calling `rsrv_run`.

If the IOC is starting for the first time, `initHooks(initHookAtEnd)` is called.

7.5 IOC Pausing

The command `iocPause` brings a running IOC to a quiescent state with all record processing frozen (other than possibly the completion of asynchronous I/O operations). A paused IOC may be able to be restarted using the `iocRun` command, but whether this succeeds or not can depend on how long it has been quiescent and the status of any device drivers which have been running. The operations which make up the pause operation are as follows:

1. Pause the Channel Access Server tasks by calling `rsrv_pause`
2. Set the global variable `interruptAccept` to `FALSE`.
3. Call `dbCaPause` and `scanPause` to pause their associated tasks.

7.6 Changing iocCore fixed limits

The following commands can be issued after iocCore is loaded to change iocCore fixed limits. The commands should be given before any dbLoad commands.

```
callbackSetQueueSize(size)
dbPvdTableSize(size)
scanOnceSetQueueSize(size)
errlogInit(buffersize)
```

7.6.1 callbackSetQueueSize

Requests for the general putpose callback tasks are placed in a ring buffer. This command can be used to set the size for the ring buffers. The default is 2000. A message is issued when a ring buffer overflows. It should rarely be necessary to override this default. Normally the ring buffer overflow messages appear when a callback task fails.

7.6.2 dbPvdTableSize

Record instance names are stored in a process variable directory, which is a hash table. The default number of hash entries is 512. `dbPvdTableSize` can be called to change the size. It must be called before any `dbLoad` commands and must be a power of 2 between 256 and 65536. If an IOC contains very large databases (several thousand records) then a larger hash table size speeds up searches for records.

7.6.3 scanOnceSetQueueSize

`scanOnce` requests are placed in a ring buffer. This command can be used to set the size for the ring buffer. The default is 1000. It should rarely be necessary to override this default. Normally the ring buffer overflow messages appear when the scanOnce task fails.

7.6.4 errlogInit

This overrides the default buffer size for the errlog message queue. The default is 1280 bytes.

7.7 initHooks

The inithooks facility allows application functions to be called at various states during ioc initialization. The states are defined in initHooks.h, which contains the following definitions:

```
typedef enum {
    initHookAtBeginning,
    initHookAfterCallbackInit,
    initHookAfterCaLinkInit,
    initHookAfterInitDrvSup,
    initHookAfterInitRecSup,
    initHookAfterInitDevSup,
    initHookAfterInitDatabase,
    initHookAfterFinishDevSup,
    initHookAfterScanInit,
    initHookAfterInitialProcess,
    initHookAfterInterruptAccept,
    initHookAtEnd
}initHookState;

typedef void (*initHookFunction)(initHookState state);
int initHookRegister(initHookFunction func);
const char *initHookName(initHookState state);
```

Any functions that are registered before `iocInit` reaches the desired state will be called when it reaches that state. The `initHookName` function returns a static string representation of the state passed into it which is intended for printing. The following skeleton code shows how to use this facility:

```
static initHookFunction myHookFunction;

int myHookInit(void)
{
  return(initHookRegister(myHookFunction));
}

static void myHookFunction(initHookState state)
{
  switch(state) {
    case initHookAfterInitRecSup:
      ...
      break;
    case initHookAfterInterruptAccept:
      ...
      break;
    default:
      break;
  }
}
```

An arbitrary number of functions can be registered.

7.8 Environment Variables

Various environment variables are used by iocCore:

```
EPICS_CA_ADDR_LIST
EPICS_CA_AUTO_ADDR_LIST
EPICS_CA_CONN_TMO
EPICS_CAS_BEACON_PERIOD
EPICS_CA_REPEATER_PORT
EPICS_CA_SERVER_PORT
EPICS_CA_MAX_ARRAY_BYTES
EPICS_TS_NTP_INET
EPICS_IOC_LOG_PORT
EPICS_IOC_LOG_INET
```

For an explanation of the `EPICS_CA_`... and `EPICS_CAS_`... variables see the EPICS Channel Access Reference Manual. For an explaination of the `EPICS_IOC_LOG_`... variables see “iocLogClient” on page 166 of this manual. `EPICS_TS_NTP_INET` is used only on vxWorks and RTEMS, where it sets the address of the Network Time Protocol server. If it is not defined the IOC uses the boot server as its NTP server.

These variables can be set through iocsh via the `epicsEnvSet` command, or on vxWorks using `putenv`. For example:

```
epicsEnvSet("EPICS_CA_CONN_TMO,"10")
```

All `epicsEnvSet` commands should be issued after iocCore is loaded and before any dbLoad commands.

The following commands can be issued to iocsh:

`epicsPrtEnvParams` - This shows just the environment variables used by iocCore.

`epicsEnvShow` - This shows all environment variables on your system.

7.9 Initialize Logging

Initialize the logging system. See chapter "IOC Error Logging" for details. The following can be used to direct the log client to use a specific host log server.

```
epicsEnvSet("EPICS_IOC_LOG_PORT","<port>")
epicsEnvSet("EPICS_IOC_LOG_INET","<inet addr>")
```

These command must be given immediately after iocCore is loaded.

To start logging you must issue the command:

```
iocLogInit
```

Chapter 8: Access Security

8.1 Overview

This chapter describes access security. i.e. the system that limits access to IOC databases. It consists of the following sections:

1. Overview - This section
2. Quick start - A summary of the steps necessary to start access security.
3. User's Guide - This explains what access security is and how to use it.
4. Design Summary - Functional Requirements and Design Overview.
5. Application Programmer's Interface
6. Database Access Security - Access Security features for EPICS IOC databases.
7. Channel Access Security - Access Security features in Channel Access
8. Trapping Channel Access Writes - This allows trapping of all writes from external channel access clients.
9. Implementation Overview

The requirements for access security were generated at ANL/APS in 1992. The requirements document is:

EPICS: Channel Access Security - Functional Requirements, Ned D. Arnold, 03/-9/92.

This document is available through the EPICS website.

8.2 Quick Start

In order to "turn on" access security for a particular IOC the following must be done:

- Create the access security file.
- IOC databases may have to be modified
  - Record instances may have to have values assigned to field ASG. If ASG is null the record is in group DEFAULT.
  - Access security files can be reloaded after iocInit via a subroutine record with `asSubInit` and `asSubProcess` as the associated subroutines. Writing the value 1 to this record will cause a reload.
- The vxWorks startup file must contain the following command before iocInit.
  ```
  asSetFilename("accessSecurityFile")
  ```
  The following is an optional command.
  ```
  asSetSubstitutions("var1=sub1,var2=sub2,...”))
  ```

The following rules decide if access security is turned on for an IOC:

- If asSetFilename is not executed before iocInit, access security will NEVER be started..
- If asSetFile is given and any error occurs while first initializing access security, then ALL access to that ioc is denied.

- If after successfully starting access security, an attempt is made to restart and an error occurs then the previous access security configuration is maintained.

After an IOC has been booted with access security enabled, the access security rules can be changed by issuing the asSetFilename, asSetSubstitutions, and asInit. The functions asInitialize, asInitFile, and asInitFP, which are described below, can also be used.

8.3 User's Guide

8.3.1 Features

Access security protects IOC databases from unauthorized Channel Access Clients. Access security is based on the following:

- **Who**: Userid of the channel access client.
- **Where**: Hostid where the user is logged on. This is the host on which the channel access client exists. Thus no attempt is made to see if a user is local or is remotely logged on to the host.
- **What**: Individual fields of records are protected. Each record has a field containing the Access Security Group (ASG) to which the record belongs. Each field has an access security level, which must be 0 or 1.The security level is defined in the ascii record definition file. Thus the access security level for a field is the same for all record instances of a record type.
- **When**: Access rules can contain input links and calculations similar to the calculation record.

8.3.2 Limitations

An IOC database can be accessed only via Channel Access or via the vxWorks or ioc shell. It is assumed that access to the local IOC console is protected via physical security and `telnet`/`rlogin` access protected via normal networking and physical security methods.

No attempt has been made to protect against the sophisticated saboteur. Network security methods must be used to limit access to the subnet on which the iocs reside.

8.3.3 Definitions

This document uses the following terms:

- **ASL**: Access Security Level (Called access level in Req Doc)
- **ASG**: Access Security Group (Called PV Group in Req Doc)
- **UAG**: User Access Group
- **HAG**: Host Access Group

8.3.4 Access Security Configuration File

This section describes the format of a file containing definitions of the user access groups, host access groups, and access security groups. An IOC creates an access configuration database by reading an access configuration file (the extension `.acf` is recommended). Lets first give a simple example and then a complete description of the syntax.

8.3.4.1 Simple Example

```
UAG(uag) {user1,user2}
HAG(hag) {host1,host2}
ASG(DEFAULT) {
   RULE(1,READ)
   RULE(1,WRITE) {
      UAG(uag)
      HAG(hag)
   }
}
```

These rules provide read access to anyone located anywhere and write access to `user1` and `user2` if they are located at `host1` or `host2`.

8.3.4.2 Syntax Definition

In the following description:

`[ ]`	Surrounds optional elements
`|`	Separates alternatives
`...`	Means that an arbitrary number of definitions may be given.

Any line beginning with a # character is a comment

The elements <name>, <user>, <host>, <pvname>, and <calculation> can be given a quoted or unquoted strings. The rules for unquoted strings are the same as for database definitions.

```
UAG(<name>) [{ <user> [, <user> ...] }]
...
HAG(<name>) [{ <host> [, <host> ...] }]
...
ASG(<name>) [{
   [INP<index>(<pvname>)
   ...]
   RULE(<level>,NONE | READ | WRITE [, NOTRAPWRITE | TRAPWRITE]) {
      [UAG(<name> [,<name> ...])]
      [HAG(<name> [,<name> ...])]
      CALC(<calculation>)
   }
   ...
}]
...
```

8.3.4.3 Discussion

- **UAG**: User Access Group. This is a list of user names. The list may be empty. The same user can appear in multiple UAGs. For vxWorks iocs the user name is taken from the user field of the boot parameters.
- **HAG**: Host Access Group. This is a list of host names. It may be empty. The same host name can appear in multiple HAGs. For iocs the host name is taken from the target name of the boot parameters. NOTE: host names are converted to lower case.
- **ASG**: An access security group. The group "`DEFAULT`" is a special case. If a member specifies a null group or a group which has no ASG definition then the member is assigned to the group "`DEFAULT`".

- **INP<index>** Index must have one of the values "A" to "L". These are just like the INP fields of a calculation record. It is necessary to define INP fields if a CALC field is defined in any RULE for the ASG.
- **RULE** This defines access permissions. <level> must be 0 or 1. Permission for a level 1 field implies permission for level 0 fields. The permissions are NONE, READ, and WRITE. WRITE permission implies READ permission. The standard EPICS record types have all fields set to level 1 except for VAL, CMD (command), and RES (reset). An optional argument specifies if writes should be trapped. See the section below on trapping Channel Access writes for how this is used. If not given the default is NOTRAPWRITE.
    - **UAG** specifies a list of user access groups that can have the access privilege. If UAG is not defined then all users are allowed.
    - **HAG** specifies a list of host access groups that have the access privilege. If HAG is not defined then all hosts are allowed.
    - **CALC** is just like the CALC field of a calculation record except that the result must evaluate to TRUE or FALSE. The rule only applies if the calculation result is TRUE, where the actual test for TRUE is (0.99 < result < 1.01). Anything else is regarded as FALSE and will cause the rule to be ignored. Assignment statements are not permitted in CALC expressions here.

Each IOC record contains a field ASG, which specifies the name of the ASG to which the record belongs. If this field is null or specifies a group which is not defined in the access security file then the record is placed in group "DEFAULT".

The access privilege for a channel access client is determined as follows:

1. The ASG associated with the record is searched.
2. Each RULE is checked for the following:
    a. The field's level must be less than or equal to the level for this RULE.
    b. If UAG is defined, the user must belong to one of the specified UAGs. If UAG is not defined all users are accepted.
    c. If HAG is defined, the user's host must belong to one one of the HAGs. If HAG is not defined all hosts are accepted.
    d. If CALC is specified, the calculation must yield the value 1, i.e. TRUE. If any of the INP fields associated with this calculation are in INVALID alarm severity the calculation is considered false. The actual test for TRUE is .99 < result < 1.01.
3. The maximum access allowed by step 2 is the access chosen.

Multiple RULEs can be defined for a given ASG, even RULEs with identical levels and access permission.

8.3.5 ascheck - Check Syntax of Access Configuration File

After creating or modifying an access configuration file it can be checked for syntax errors by issuing the command:

```
ascheck -S "xxx=yyy,..." < "filename"
```

This is a Unix command. It displays errors on stdout. If no errors are detected it prints nothing. Only syntax errors not logic errors are detected. Thus it is still possible to get your self in trouble. The flag -S means a set of macro substitutions may appear. This is just like the macro substitutions for dbLoadDatabase.

8.3.6 IOC Access Security Initialization

In order to have access security turned on during IOC initialization the following command must appear in the startup file before iocInit is called:

```
asSetFilename("<access security file>")
```

If this command does not appear then access security will not be started by iocInit. If an error occurs when iocInit calls asInit than all access to the ioc is disabled, i.e. no channel access client will be able to access the ioc.

Access security also supports macro substitution just like `dbLoadDatabase`. The following command specifies the desired substitutions:

```
asSetSubstitutions("var1=sub1,var2=sub2,...")
```

This command must be issued before `iocInit`.

After an IOC is initialized the access security database can be changed. The preferred way is via the subroutine record described in the next section. It can also be changed by issuing the following command to the vxWorks shell:

```
asInit
```

It is also possible to reissue `asSetFilename` and/or `asSetSubstitutions` before `asInit`. If any error occurs during `asInit` the old access security configuration is maintained. It is **NOT** permissable to call `asInit` before `iocInit` is called.

Restarting access security after ioc initialization is an expensive operation and should not be used as a regular procedure.

8.3.7 Database Configuration

8.3.7.1 Access Security Group

Each database record has a field `ASG` which holds a character string. Any database configuration tool can be used to give a value to this field. If the ASG of a record is not defined or is not equal to a ASG in the configuration file then the record is placed in `DEFAULT`.

8.3.7.2 Subroutine Record Support

Two subroutines, which can be attached to a subroutine record, are available (provided with `iocCore`):

```
asSubInit
asSubProcess
```

NOTE: These subroutines are automatically registered thus do NOT put a `registrar` definition in your database definition file.

If a record is created that attaches to these routines, it can be used to force the IOC to load a new access configuration database. To change the access configuration:

1. Modify the file specified by the last call to `asSetFilename` so that it contains the new configuration desired.
2. Write a 1 to the subroutine record `VAL` field. Note that this can be done via channel access.

The following action is taken:

3. When the value is found to be 1, `asInit` is called and the value set back to 0.
4. The record is treated as an asynchronous record. Completion occurs when the new access configuration has been initialized or a time-out occurs. If initialization fails the record is placed into alarm with a severity determined by `BRSV`.

8.3.7.3 Record Type Description

Each field of each record type has an associated access security level of `ASL0` or `ASL1`. See the chapter "Database Definition" for details.

8.3.8 Example:

Lets design a set of rules for a Linac. Assume the following:

1. Anyone can have read access to all fields at anytime.
2. Linac engineers, located in the injection control or control room, can have write access to most level 0 fields only if the Linac is not in operational mode.
3. Operators, located in the injection control or control room, can have write access to most level 0 fields anytime.
4. The operations supervisor, linac supervisor, and the application developers can have write access to all fields but must have some way of not changing something inadvertently.
5. Most records use the above rules but a few (high voltage power supplies, etc.) are placed under tighter control. These will follow rules 1 and 4 but not 2 or 3.
6. IOC channel access clients always have level 1 write privilege.

Most Linac IOC records will not have the `ASG` field defined and will thus be placed in ASG "`DEFAULT`". The following records will have an `ASG` defined:

- `LI:OPSTATE` and any other records that need tighter control have `ASG="critical"`. One such record could be a subroutine record used to cause a new access configuration file to be loaded. `LI_OPSTATE` has the value (0,1) if the Linac is (not operational, operational).
- `LI:lev1permit` has `ASG="permit"`. In order for the `opSup`, `linacSup`, or an `appDev` to have write privilege to everything this record must be set to the value 1.

The following access configuration satisfies the above rules.

```
UAG(op) {op1,op2,superguy}
UAG(opSup) {superguy}
UAG(linac) {waw,nassiri,grelick,berg,fuja,gsm}
UAG(linacSup) {gsm}
UAG(appDev) {nda,kko}
HAG(icr) {silver,phebos,gaea}
HAG(cr) {mars,hera,gold}
HAG(ioc) {ioclic1,ioclic2,ioclid1,ioclid2,ioclid3,ioclid4,ioclid5}
ASG(DEFAULT) {
   INPA(LI:OPSTATE)
   INPB(LI:lev1permit)
   RULE(0,WRITE) {
      UAG(op)
      HAG(icr,cr)
      CALC(”A=1”)
   }
   RULE(0,WRITE) {
      UAG(op,linac,appdev)
      HAG(icr,cr)
      CALC(”A=0”)
   }
   RULE(1,WRITE) {
      UAG(opSup,linacSup,appdev)
      CALC("B=1")
   }
   RULE(1,READ)
   RULE(1,WRITE) {
      HAG(ioc)
   }
```

```
}
ASG(permit) {
   RULE(0,WRITE) {
       UAG(opSup,linacSup,appDev)
   }
   RULE(1,READ)
   RULE(1,WRITE) {
      HAG(ioc)
   }
}
ASG(critical) {
   INPB(LI:lev1permit)
   RULE(1,WRITE) {
      UAG(opSup,linacSup,appdev)
      CALC("B=1")
   }
   RULE(1,READ)
   RULE(1,WRITE) {
      HAG(ioc)
   }
}
```

8.4 Design Summary

8.4.1 Summary of Functional Requirements

A brief summary of the Functional Requirements is:

1. Each field of each record type is assigned an access security level.
2. Each record instance is assigned to a unique access security group.
3. Each user is assigned to one or more user access groups.
4. Each node is assigned to a host access group.
5. For each access security group a set of access rules can be defined. Each rule specifies:
    a. Access security level
    b. READ or READ/WRITE access.
    c. An optional list of User Access Groups or * meaning anyone.
    d. An optional list of Host Access Groups or * meaning anywhere.
    e. Conditions based on values of process variables

8.4.2 Additional Requirements

8.4.2.1 Performance

Although the functional requirements doesn't mention it, a fundamental goal is performance. The design provides almost no overhead during normal database access and moderate overhead for the following: channel access client/server connection, ioc initialization, a change in value of a process variable referenced by an access calculation, and dynamically

changing a records access control group. Dynamically changing the user access groups, host access groups, or the rules, however, can be a time consuming operation. This is done, however, by a low priority IOC task and thus does not impact normal ioc operation.

8.4.2.2 Generic Implementation

Access security should be implemented as a stand alone system, i.e. it should not be imbedded tightly in database or channel access.

8.4.2.3 No Access Security within an IOC

Within an IOC no access security is invoked. This means that database links and local channel access clients calls are not subject to access control. Also test routines such as dbgf should not be subject to access control.

8.4.2.4 Defaults

It must be possible to easily define default access rules.

8.4.2.5 Access Security is Optional

When an IOC is initialized, access security is optional.

8.4.3 Design Overview

The implementation provides a library of routines for accessing the security system. This library has no knowledge of channel access or IOC databases, i.e. it is generic. Database access, which is responsible for protecting an IOC database, calls library routines to add each IOC record to one of the access control groups.

Lets briefly discuss the access security system and how database access and channel access interact with it.

8.4.3.1 Configuration File

User access groups, host access groups, and access security groups are configured via an ASCII file.

8.4.3.2 Access Security Library

The access security library consists of the following groups of routines: initialization, group manipulation, client manipulation, access computation, and diagnostic. The initialization routine reads a configuration file and creates a memory resident access control database. The group manipulation routines allow members to be added and removed from access groups. The client routines provide services for clients attached to members.

8.4.3.3 IOC Database Access Security

The interface between an IOC database and the access security system.

8.4.3.4 Channel Access Security

Whenever the Channel Access broadcast server receives a `ca_search` request and finds the process variable, it calls `asAddClient`. Whenever it disconnects it calls `asRemoveClient`. Whenever it issues a get or put to the database it must call `asCheckGet` or `asCheckPut`.

8.4.4 Comments

It is likely that the access rules will be defined such that many IOCs will attach to a common process variable. As a result the IOC containing the PV will have many CA clients.

What about password protection and encryption? I maintain that this is a problem to be solved in a level above the access security described in this document. This is the issue of protecting against the sophisticated saboteur.

8.4.5 Performance and Memory Requirements

Performance has not yet been measured but during the tests to measure memory usage no noticeable change in performance during ioc initialization or during Channel Access clients connection was noticed. Unless access privilege is violated the overhead during channel access gets and puts is only an extra comparison.

In order to measure memory usage, the following test was performed:

1. A database consisting of 5000 soft analog records was created.
2. A channel access client (`caput`) was created that performs `ca_puts` on each of the 5000 channels. Each time it begins a new set of puts the value increments by 1.
3. A channel access client (`caget`) was created that has monitors on each of the 5000 channels.

The memory consumption was measured before `iocInit`, after `iocInit`, after `caput` connected to all channels, and after `caget` connected to all 5000 channels. This was done for APS release 3.11.5 (before access security) and the first version which included access security. The results were:

	R3.11.5	After
Before iocInit	4,244,520	4,860,840
After iocInit	4,995,416	5,964,904
After caput	5,449,780	6,658,868
After caget	8,372,444	9,751,796

Before the database was loaded the memory used was 1,249,692 bytes. Thus most of the memory usage before iocInit resulted from storage for records. The increase since R3.11.5 results from added fields to `dbCommon`. Fields were added for access security, synchronous time support and for the new caching put support. The other increases in memory usage result from the control blocks needed to support access control. The entire design was based on maximum performance. This resulted in increased memory usage.

8.5 Access Security Application Programmer's Interface

8.5.1 Introduction

File `asLib.h` describes the access security data structures and the last section of this chapter has a diagram describing the relationship between the structures. The structures are:

- ASBASE - Contains the list head for lists of UAGs, HAGs, and ASGs
- UAG - A user access group.
- HAG - A host access group
- ASG - An access secuity group. It contains the list head for ASGINPs, ASGRULEs, and ASGMEMBERs
- ASGINP - Contains the information for an INPx.
- ASGRULE - Contains the information for a rule

- ASGMEMBER - Contains the information for a member of an access secururity group. It contains the list head for ASGCLIENTs.

All structures except ASGMEMBER and ASGCLIENT are created by the access security library itself when it reads an access security file. An ASGMEMBER is created each time asAddMember is called by code that interfaces to the database. An ASGCLIENT is created each time asAddClient is called by a channel access server.

8.5.2 Definitions

The following are descriptions of arguments of routines described later.

```
typedef struct asgMember *ASMEMBERPVT;
typedef struct asgClient *ASCLIENTPVT;
typedef int (*ASINPUTFUNCPTR)(char *buf,int max_size);
typedef enum{
    asClientCOAR   /*Change of access rights*/
    /*For now this is all*/
} asClientStatus;
typedef void (*ASCLIENTCALLBACK)(ASCLIENTPVT,asClientStatus);
```

8.5.3 Initialization

```
long asInitialize(ASINPUTFUNPTR inputFunction)
long asInitFile(const char *filename,const char *substitutions)
long asInitFP(FILE *fp,const char *substitutions)
```

These routines read an access definition file and perform all initialization necessary. The caller must provide a routine to provide input lines for `asInitialize. asInitFile` and `asInitFP` do their own input and also perform macro substitutions.

The initilization routines can be called multiple times. If an access system already exists the old definitions are removed and the new one initialized. Existing members are placed in the new `ASG`s.

8.5.4 Group manipulation

The routines are called by code that knows how to associate ASG names with the database. In the case of IOC databases, dbCommon has a field ASG. At IOC initialization a call is made to asAddMember for every record instance in the IOC database.

8.5.4.1 add Member

```
long asAddMember(ASMEMBERPVT *ppvt, const char *asgName);
```

This routine adds a new member to ASG `asgName`. The calling routine must provide storage for `ASMEMBERPVT`. Upon successful return `*ppvt` will be equal to the address of storage used by the access control system. The access system keeps an orphan list for all `asgNames` not defined in the access configuration.

The caller must provide permanent storage for `asgName`.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.4.2 remove Member

```
long asRemoveMember(ASMEMBERPVT *ppvt);
```

This routine removes a member from an access control group. If any clients are still present it returns an error status of S_asLib_clientExists without removing the member.

This routine returns S_asLib_asNotActive without doing anything if access control is not active.

8.5.4.3 get Member Pvt

```
void *asGetMemberPvt(ASMEMBERPVT pvt);
```

For each member, the access system keeps a pointer that can be used by the caller. This routine returns the value of the pointer.

This routine returns NULL if access security is not active

8.5.4.4 put Member Pvt

```
long asPutMemberPvt(ASMEMBERPVT pvt,void *userPvt);
```

This routine is used to set the pointer returned by asGetMemberPvt.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.4.5 change Group

```
long asChangeGroup(ASMEMBERPVT *ppvt,const char *newAsgName);
```

This routine changes the group for an existing member. The access rights of all clients of the member are recomputed.

The caller must provide permanent storage for `newAsgName`.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.5 Client Manipulation

This code is called by a channel access server.

8.5.5.1 add Client

```
long asAddClient(ASCLIENTPVT *ppvt,ASMEMBERPVT pvt,int asl,
                     const char *user,char*host);
```

This routine adds a client to an ASG member. The calling routine must provide storage for `ASCLIENTPVT`. `ASMEMBERPVT` is the value that was set by calling `asAddMember`. The database code and the server code must develop a convention that allows the server code to locate the `ASMEMBERPVT`. For IOC databases, `ASMEMBERPVT` is kept in dbCommon. `asl` is the access security level.

The caller must provide permanent storage for `user` and `host`. Note that user is "const char *" but host is just "char *". The reason is the host names are converted to lower case.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.5.2 change Client

```
long asChangeClient(ASCLIENTPVT ppvt,int asl,
   const char *user,char*host);
```

This routine changes one or more of the values `asl`, `user`, and `host` for an existing client. Again the caller must provide permanent storage for `user` and `host`. It is permissible to use the same `user` and `host` used in the call to `asAddClient` with different values.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.5.3 remove Client

```
long asRemoveClient(ASCLIENTPVT *pvt);
```

This call removes a client.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.5.4 get Client Pvt

```
void *asGetClientPvt(ASCLIENTPVT pvt);
```

For each client, the access system keeps a pointer that can be used by the caller. This routine returns the value of the pointer.

This routine returns `NULL` if access security is not active.

8.5.5.5 put Client Pvt

```
void asPutClientPvt(ASCLIENTPVT pvt, void *userPvt);
```

This routine is used to set the pointer returned by `asGetClientPvt`.

8.5.5.6 register Callback

```
long asRegisterClientCallback(ASCLIENTPVT pvt,
   ASCLIENTCALLBACK pcallback);
```

This routine registers a callback that will be called whenever the access privilege of the client changes.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.5.7 check Get

```
long asCheckGet(ASCLIENTPVT pvt);
```

This routine, actually a macro, returns (`TRUE`,`FALSE`) if the client (has, doesn't have) get access rights.

8.5.5.8 check Put

```
long asCheckPut(ASCLIENTPVT pvt);
```

This routine, actually a macro, returns (`TRUE`,`FALSE`) if the client (has, doesn't have) put access rights.

8.5.5.9 asTrapWriteBefore and asTrapWriteAfter

```
void *asTrapWriteBefore(ASCLIENTPVT clientPvt,
   const char *userid, const char *hostid, void *serverSpecific);
void *asTrapWriteAfter(void *trapPvt);
```

These routines must be called before and after any write performed for a client. The value returned by `asTrapWriteBefore` must be the value passed to `asTrapWriteAfter`. The severSpecific argument is assigned to the `serverSpecific` field of the `asTrapWriteMessage` described below.

8.5.6 Access Computation

8.5.6.1 compute all Asg

```
long asComputeAllAsg(void);
```

This routine calls `asComputeAsg` for each access security group.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.6.2 compute Asg

```
long asComputeAsg(ASG *pasg);
```

This routine calculates all `CALC` entries for the `ASG` and calls `asCompute` for each client of each member of the specified access security group.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.6.3 compute access rights

```
long asCompute(ASCLIENTPVT pvt);
```

This routine computes the access rights of a client. This routine is normally called by the access library itself rather than use code.

This routine returns `S_asLib_asNotActive` without doing anything if access control is not active.

8.5.7 Diagnostics

8.5.7.1 Dump

```
int asDump(void (*member)(ASMEMBERPVT),
   void (*client)(ASCLIENTPVT),int verbose);
int asDumpFP(FILE *fp,void (*member)(ASMEMBERPVT),
   void (*client)(ASCLIENTPVT),int verbose);
```

These routines print the current access security database. If verbose is 0 (`FALSE`), then only the information obtained from the access security file is printed.

If verbose is `TRUE` then additional information is printed. The value of each `INP` is displayed. The list of members belonging to each ASG and the clients belonging to each member are displayed. If member callback is specified as an argument, then it is called for each member. If client callback is specified, it is called for each access security client.

8.5.7.2 Dump UAG

```
int asDumpUag(char *uagname)
int asDumpUagFP(FILE *fp,char *uagname)
```

These routines display the specified `UAG` or if `uagname` is `NULL` each `UAG` defined in the access security database.

8.5.7.3 Dump HAG

```
int asDumpHag(char *hagname)
int asDumpHagFP(FILE *fp,char *hagname)
```

These routines display the specified `UAG` or if `uagname` is `NULL` each `UAG` defined in the access security database.

8.5.7.4 Dump Rules

```
int asDumpRules(char *asgname)
int asDumpRulesFP(FILE *fp,char *asgname)
```

These routines display the rules for the specified ASG or if asgname is NULL the rules for each ASG defined in the access security database.

8.5.7.5 Dump member

```
int asDumpMem(char *asgname,
   void (*memcallback)(ASMEMBERPVT),int clients)
int asDumpMemFP(FILE *fp,char *asgname,
   void (*memcallback)(ASMEMBERPVT),int clients)
```

This routine displays the member and, if clients is TRUE, client information for the specified ASG or if asgname is NULL the member and client information for each ASG defined in the access security database. It also calls memcallback for each member if this argument is not NULL.

8.5.7.6 Dump hash table

```
int asDumpHash(void)
int asDumpHash(FILE *fp,void)
```

These show the contents of the hash table used to locate UAGs and HAGs,

8.6 Database Access Security

8.6.1 Access Level definition

The definition of access level means that a level is defined for each field of each record type.

1. Structure fldDes (dbBase.h), which describes the attributes of each field, contains a field access_security _level. In addition definitions exist for the symbols: ASL0 and ASL1.
2. Each field description in a record description contains a field with the value ASLx.

The meanings of the Access Security Level definitions are as follows:

- ASL0Assigned to fields used during normal operation
- ASL1Assigned to fields that may be sensitive to change. Permission to access this level implies permission for ASL0.

Most record types assign ASL as follows: The fields VAL, RES (Reset), and CMD use the value ASL0. All other fields use ASL1.

8.6.2 Access Security Group definition

dbCommon contains the fields ASG and ASP. ASG (Access Security Group) is a character string. The value can be assigned via a database configuration tool or else a utility could be provided to assign values during ioc initialization. ASP is an access security private field. It contains the address of an ASGMEMBER.

8.6.3 Access Client Definition

Struct dbAddr contains a field asPvt, which contains the address of an ASGCLIENT. This definition is also added to struct db_addr so that old database access also supports access security.

8.6.4 Database Access Library

Two files `asDbLib.c` and `asCa.c` implement the interface between IOC databases and access control. It contains the following routines:

8.6.4.1 Initialization

```
int asSetFilename(char *acf)
```

Calling this routine sets the filename of an access configuration file. The next call to `asInit` uses this file. This routine must be called before `iocInit`otherwise access configuration is disabled. Is access security is disabled during iocInit it will never be turned on.

```
int asSetSubstitutions(char *substitutions)
```

This routine specifies macro substitutions.

```
int asInit()
int asInitAsyn(ASDBCALLBACK *pcallback)
```

This routines call `asInitialize`. If the current access configuration file, as specified by `asSetFilename`, is `NULL` then the routine just returns, otherwise the configuration file is used to create the access configuration database.

This routine is called by `iocInit`. `asInit` can also be called at any time to change the access configuration information.

`asInitAsyn` spawns a task `asInitTask` to perform the initialization. This allows `asInitAsyn` to be called from a subroutine called by the process entry of a subroutine record. `asInitTask` calls `taskwdInsert` so that if it suspends for some reason `taskwd` can detect the failure. After initialization all records in the database are made members of the appropriate access control group.

If the caller provides an `ASDBCALLBACK` then when either initialization completes or `taskwd` detects a failure the users callback routine is called via one of the standard callback tasks.

`asInitAsyn` will return a value of `-1` if access initialization is already active. It returns 0 if `asInitTask` is successfully spawned.

8.6.4.2 Routines used by Channel Access Server

```
int asDbGetAsl(void *paddr)
```

Get Access Security level for the field referenced by a database access structure. The argument is defined as a `void*` so that both old and new database access can be used.

```
void * asDbGetMemberPvt(void *paddr)
```

Get `ASMEMBERPVT` for the field referenced by a database access structure. The argument is defined as a `void*` so that both old and new database access can be used.

8.6.4.3 Routine to test asAddClient

```
int astac(char *pname,char *user,char *host)
```

This is a routine to test `asAddClient`. It simulates the calls that are made by Channel Access.

8.6.4.4 Subroutines attached to a subroutine record

These routines are provided so that a channel access client can force an ioc to load a new access configuration database.

```
long asSubInit(struct subRecord *prec,int pass)
long asSubProcess(struct subRecord *prec)
```

These are routines that can be attached to a subroutine record. Whenever a 1 is written to the record, `asSubProcess` calls `asInit`. If `asInit` returns success, it returns with asynchronously. When `asInitTask` calls the completion routine supplied by `asSubProcess`, the return status is used to place the record in alarm.

8.6.4.5 Diagnostic Routines

These routines provide interfaces to the `asDump` routines described in the previous chapter. They do NOT lock before calling the associated routine. Thus they may fail if the access security configuration is changing while they are running. However the danger of the user accidently aborting a command and leaving the access security system locked is considered a risk that should be avoided.

```
asdbdump(void)
asdbdumpFP(FILE *fp)
```

These routines call `asDumpFP` with a member callback and with verbose `TRUE`.

```
aspuag(char *uagname)
aspuagFP(FILE *fp,char *uagname)
```

These routines call `asDumpUag`FP.

```
asphag(char *hagname)
asphagFP(FILE *fp,char *hagname)
```

These routines call `asDumpHagFP`.

```
asprules(char *asgname)
asprulesFP(FILE *fp,char *asgname)
```

These routines call `asDumpRules`FP.

```
aspmem(char *asgname,int clients)
aspmemFP(FILE *fp,char *asgname,int clients)
```

These routines call `asDumpMemFP`.

8.7 Channel Access Security

EPICS Access Security was originally designed to protect Input Output Controllers (IOCs) from unauthorized access via the Channel Access (CA) network protocol. It can also be used by any Channel Access Server (CAS) tool. For example the Channel Access PV Gateway implements its own access security. This section describes the interaction between a CA server and the Access Security system. It also briefly describes how the current access rights state is communicated to clients of the EPICS control system via the CA client interface.

8.7.1 CA Server Interfaces to the Access Security System

The CA server calls `asAddClient()` and `asRegisterClientCallback()` for each of the channels that a client connects to the server. The routine `asRemoveClient()` is called whenever the client clears (removes) a channel or when the client disconnects.

The server maintains storage for the clients host and user names. The initial value of these strings are supplied to the server when the client connects and can be updated at any time by the client. When these strings change then `asChangeClient()` is called for each of the channels maintained by the server for the client.

The server checks for read access when processing gets and for write access when processing puts. If access is denied then an exception message is sent to the client. The macros `asCheckGet()` and `asCheckPut()` perform the checks.

The server checks for read access when processing requests to register an event callback (monitor) for the client. If there is read access the server always sends an initial update indicating the current value. If there isn't read access the server sends one update indicating no read access and disables subsequent updates.

The server receives asynchronous notification of access rights change via the callback registered with `asRegisterClientCallback()`. When a channel's access rights change the server communicates the current state to the client library. If read access to a channel is lost and there are events (monitors) registered on the channel then the server sends an update to the client for each of them indicating no access and disables future updates for each event. If read access is reestablished to a channel and there are events (monitors) registered on the channel then the server re-enables updates and sends an initial update message to the client for each of them.

The server must also call `asTrapWriteBefore()` and `asTrapWriteAfter()` before and after a put request from a client is performed.

8.7.2 Client Interfaces

Additional details on the channel access client side callable interfaces to access security can be obtained from the "Channel Access Reference Manual".

The client library stores and maintains the current state of the access rights for each channel that it has established. The client library receives asynchronous updates of the current access rights state from the server. It uses this state to check for read access when processing gets and for write access when processing puts. If a program issues a channel access request that is inconsistent with the client library's current knowledge of the access rights state then access is denied and an error code is returned to the application. The current access rights state as known by the client library can be tested by an applications program with the C macros `ca_read_access()` and `ca_write_access()`.

An application program can also receive asynchronous notification of changes to the access rights state by registering a function to be called back when the client library updates its storage of the access rights state. The application's call back function is installed for this purpose by calling `ca_replace_access_rights_event()`.

If the access rights state changes in the server after a request is queued in the client library but before the request is processed by the server then it is possible that the request will fail in the server. Under these circumstances then an exception will be raised in the client.

The server always sends one update to the client when the event (monitor) is initially registered. If there isn't read access then the status in the arguments to the application program's event call back function indicates no read access and the value in the arguments to the clients event call back is set to zero. If the read access right changes after the event is initially registered then another update is supplied to the application programs call back function.

8.8 Trapping Channel Access Writes

Access security provides a facility asTrapWrite that can trap write requests and pass them to any facility that registers a listener. In order to use this facility three things are necessary:

1. The facility, e.g. the channel access server, using access security must make two calls: `asTrapWriteBefore()` and `asTrapWriteAfter()`. These are defined in asLib.h. The channel access server on the ioc makes these calls.
2. `asTrapWrite()` gets called by `asTrapWriteBefore()` and `asTrapWriteAfter()` and uses the `TRAPWRITE` option specified with the RULEs given in the access configuration file to decide if listeners should be called. asTrapWrite also includes a routine `asTrapWriteRegisterListener()`.
3. Some facility not included with access security must call `asTrapWriteRegisterListener()`. If nothing calls `asTrapWriteRegisterListener`, asTrapWrite does nothing.

The remainder of this section describes how a facility can use `asTrapWrite.h`, which is defined as:

```
typedef struct asTrapWriteMessage {
    const char *userid;
    const char *hostid;
    void *serverSpecific;
    void *userPvt;
} asTrapWriteMessage;


typedef void *asTrapWriteId;
typedef void(*asTrapWriteListener)(asTrapWriteMessage *pmessage,int after);

asTrapWriteId asTrapWriteRegisterListener(asTrapWriteListener func);
void asTrapWriteUnregisterListener(asTrapWriteId id);
```

After a facility calls `asTrapWriteRegisterListener()` its `asTrapWriteListener()` will get called before and after each write with an associated RULE that has the option TRAPWRITE set.

`asTrapWriteRegisterListener()` is passed the address of an `asTrapWriteMessage`. This message contains the following fields:

- `userid` - Userid of whoever originated the request.
- `hostid` - Hostid of whoever originated the request.
- `serverSpecific` - The meaning of this field is server specific. If the listener uses this field it must know what type of server is supplying the messages. It is the value the server provides to asTrapWriteBefore.
- `userPvt` - This field is for use by the `asTrapWriteListener`. When the listener is called before the write, `userPvt` has the value 0. The listener can give it any value it desires and `userPvt` will have have the same value when the listener gets called after the write.

asTrapWriteListener delays the associated server thread so it must not do anything that causes it to block.

The IOC's RSRV server the calls `asTrapWriteBefore` with `serverSpecific` set to the dbAddr describing the database location.

8.9 Access Control: Implementation Overview

This section provides a few aids for reading the access security code. Include file `asLib.h` describes the control blocks used by the access security library.

8.9.1 Implementation Overview

The following files form the access security system:

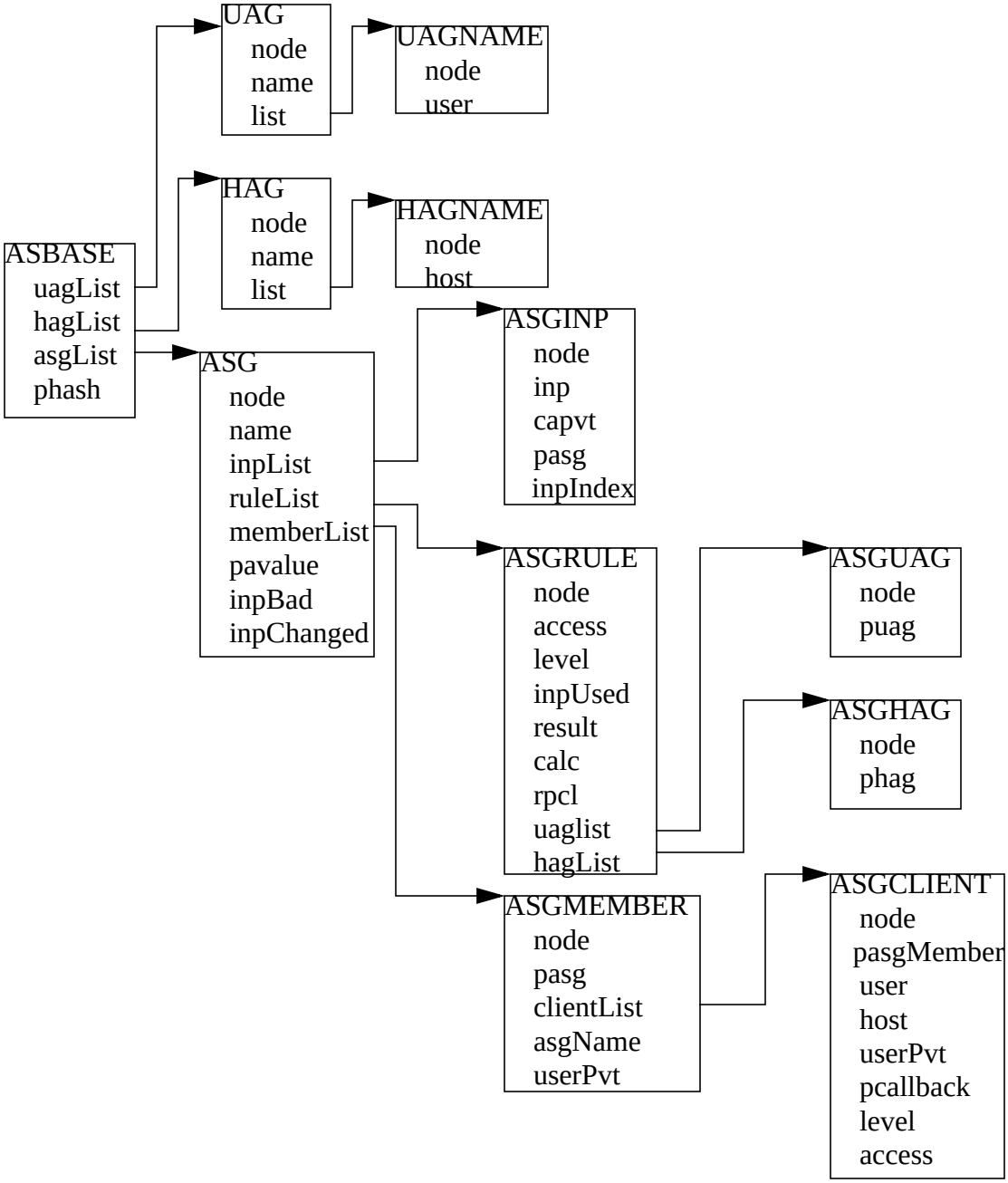
- **asLib.h** Definitions for the portion of access security that is independent of IOC databases.
- **asDbLib.h** Definitions for access routines that interface to an IOC database.
- a**sLib_lex.l** `Lex` and `Yacc` (actually EPICS `flex` and `antelope`) are used to parse the access configuration file. This is the `lex` input file.
- **asLib.y** This is the `yacc` input file. Note that it includes `asLibRoutines.c`, which do most of the work.
- **asLibRoutines.c** These are the routines that implement access security. This code has no knowledge of the database or channel access. It is a general purpose access security implementation.
- **asDbLib.c** This contains the code for interfacing access security to the IOC database.
- **asCa.c** This code contains the channel access client code that implements the `INP` and `CALC` definitions in an access security database.
- **ascheck.c** The Unix program which performs a syntax check on a configuration file.

8.9.2 Locking

Because it is possible for multiple tasks to simultaneously modify the access security database it is necessary to provide locking. Rather than try to provide low level locking, the entire access security database is locked during critical operations. The only things this should hold up are access initialization, CA searches, CA clears, and diagnostic routines. It should NEVER cause record processing to wait. In addition CA gets and puts should never be delayed. One exception exists. If the ASG field of a record is changed then `asChangeGroup` is called which locks.

All operations invoked from outside the access security library that cause changes to the internal structures of the access security database.routines lock.

8.10 Structures



Chapter 9: IOC Test Facilities

9.1 Overview

This chapter describes a number of IOC test routines that are of interest to both application developers and system developers. The routines are available via iocsh or the vxWorks shell. For both shells, the parentheses are optional, but the arguments must be separated by commas. On vxWorks all character string arguments must be enclosed in “”. For iocsh the "" are optional. For example:

```
dbpf("aiTest","2")
dbpf "aiTest","2"
```

are both valid with both iocsh and with the vxWorks shell.

```
dbpf aiTest 2
```

Is valid for iocsh but not for the vxWorks shell.

iosch also allows output redirection, i.e. the output of any iosch command can be redirected to a file. For example

```
dbl > dbl.lst
```

Will put the output of the dbl command in file"`dbl.lst`".

The user should also be aware of the field `TPRO`, which is present in every database record. If it is set `TRUE` then a message is printed each time its record is processed and a message is printed for each record processed as a result of it being processed.

If iocsh is being used it provides help for all commands that have been registered. Just type

```
help
```

or

```
help <command>
```

9.2 Database List, Get, Put

9.2.1 dbl

Database List:

```
dbl(“<record type>”,"<field list>")
```

Examples

```
dbl
dbl("ai")
```

```
dbl("*")
dbl("")
```

This command prints the names of records in the run time database. If `<record type>` is empty(`""`), `"*"`, or not specified, all records are listed. If `<record type>` is specified, then only the names of the records of that type are listed.

If `<field list>` is given and not empty then the values of the fields specified are also printed.

9.2.2 dbgrep

List Record Names That Match a Pattern:

```
dbgrep(“<pattern>”)
```

Examples

```
dbgrep(“S0*”)
dbgrep(“*gpibAi*”)
```

Lists all record names that match a pattern. The pattern can contain any characters that are legal in record names as well as “*”, which matches 0 or more characters.

9.2.3 dba

Database Address:

```
dba(“<record_name.field_name>”)
```

Example

```
dba(“aitest”)
dba(“aitest.VAL”)
```

This command calls `dbNameToAddr` and then prints the value of each field in the `dbAddr` structure describing the field. If the field name is not specified then `VAL` is assumed (the two examples above are equivalent).

9.2.4 dbgf

Get Field:

```
dbgf(“<record_name.field_name>”)
```

Example:

```
dbgf(“aitest”)
dbgf)“aitest.VAL”)
```

This performs a `dbNameToAddr` and then a `dbGetField`. It prints the field type and value. If the field name is not specified then `VAL` is assumed (the two examples above are equivalent). Note that `dbGetField` locks the record lockset, so `dbgf` will not work on a record with a stuck lockset; use `dbpr` instead in this case.

9.2.5 dbpf

Put Field:

```
dbpf(“<record_name.field_name>”,”<value>”)
```

Example:

```
dbpf("aitest","5.0")
```

This command performs a `dbNameToAddr` followed by a `dbPutField` and `dbgf`. If `<field_name>` is not specified `VAL` is assumed.

9.2.6 dbpr

Print Record:

```
dbpr("<record_name>",<interest level>)
```

Example

```
dbpr("aitest",2)
```

This command prints all fields of the specified record up to and including those with the indicated interest level. Interest level has one of the following values:

- **0**: Fields of interest to an Application developer and that can be changed as a result of record processing.
- **1**: Fields of interest to an Application developer and that do not change during record processing.
- **2**: Fields of major interest to a System developer.
- **3**: Fields of minor interest to a System developer.
- **4**: Fields of no interest.

9.2.7 dbtr

Test Record:

```
dbtr("<record_name>")
```

This calls `dbNameToAddr`, then `dbProcess` and finally `dbpr` (interest level 3). Its purpose is to test record processing.

9.2.8 dbnr

Print number of records:

```
dbnr(<all_recordtypes>)
```

This command displays the number of records of each type and the total number of records. If `all_record_types` is 0 then only record types with record instances are displayed otherwise all record types are displayed.

9.3 Breakpoints

A breakpoint facility that allows the user to step through database processing on a per lockset basis. This facility has been constructed in such a way that the execution of all locksets other than ones with breakpoints will not be interrupted. This was done by executing the records in the context of a separate task.

The breakpoint facility records all attempts to process records in a lockset containing breakpoints. A record that is processed through external means, e.g.: a scan task, is called an entrypoint into that lockset. The `dbstat` command described below will list all detected entrypoints to a lockset, and at what rate they have been detected.

9.3.1 dbb

Set Breakpoint:

```
dbb(“<record_name>”)
```

Sets a breakpoint in a record. Automatically spawns the `bkptCont`, or breakpoint continuation task (one per lockset). Further record execution in this lockset is run within this task’s context. This task will automatically quit if two conditions are met, all breakpoints have been removed from records within the lockset, and all breakpoints within the lockset have been continued.

9.3.2 dbd

Remove Breakpoint:

```
dbd(”<record_name>”)
```

Removes a breakpoint from a record.

9.3.3 dbs

Single Step:

```
dbs(“<record_name>”)
```

Steps through execution of records within a lockset. If this command is called without an argument, it will automatically step starting with the last detected breakpoint.

9.3.4 dbc

Continue:

```
dbc(“<record_name>”)
```

Continues execution until another breakpoint is found. This command may also be called without an argument.

9.3.5 dbp

Print Fields Of Suspended Record:

```
dbp("<record_name>,<interest_level>)
```

Prints out the fields of the last record whose execution was suspended.

9.3.6 dbap

Auto Print:

```
dbap(“<record_name>”)
```

Toggles the automatic record printing feature. If this feature is enabled for a given record, it will automatically be printed after the record is processed.

9.3.7 dbstat

Status:

```
dbstat
```

Prints out the status of all locksets that are suspended or contain breakpoints. This lists all the records with breakpoints set, what records have the autoprint feature set (by `dbap`), and what entrypoints have been detected. It also displays the vxWorks task ID of the breakpoint continuation task for the lockset. Here is an example output from this call:

```
LSet: 00009  Stopped at: so#B: 00001   T: 0x23cafac
             Entrypoint: so#C: 00001   C/S:     0.1
             Breakpoint: so(ap)
LSet: 00008#B: 00001   T: 0x22fee4c
             Breakpoint: output
```

The above indicates that two locksets contain breakpoints. One lockset is stopped at record "`so`." The other is not currently stopped, but contains a breakpoint at record "`output`." "`LSet`:" is the lockset number that is being considered. "`#B:`" is the number of breakpoints set in records within that lockset. "`T:`" is the vxWorks task ID of the continuation task. "`C:`" is the total number of calls to the entrypoint that have been detected. "`C/S:`" is the number of those calls that have been detected per second. `(ap)` indicates that the autoprint feature has been turned on for record "`so`."

9.4 Error Logging

9.4.1 eltc

Display error log messages on console:

```
eltc(int noYes)
```

This determines if error messages are displayed on the IOC console. 0 means no and any other value means yes.

9.5 Hardware Reports

9.5.1 dbior

I/O Report:

```
dbior ("<driver_name>",<interest level>)
```

This command calls the report entry of the indicated driver. If `<driver_name>` is "" or "*", then a report for all drivers is generated. The command also calls the report entry of all device support modules. Interest level is one of the following:

- **0**: Print a short report for each module.
- **1**: Print additional information.
- **2**: Print even more info. The user may be prompted for options.

9.5.2 dbhcr

Hardware Configuration Report:

```
dbhcr()
```

This command produces a report of all hardware links. To use it on the IOC, issue the command:

```
dbhcr > report
```

The report will probably not be in the sort order desired. The Unix command:

```
sort report > report.sort
```

should produce the sort order you desire.

9.6 Scan Reports

9.6.1 scanppl

Print Periodic Lists:

```
scanppl(double rate)
```

This routine prints a list of all records in the periodic scan list of the specified rate. If rate is 0.0 all period lists are shown.

9.6.2 scanpel

Print Event Lists:

```
scanpel(int event_number)
```

This routine prints a list of all records in the event scan list for the specified event nunber. If event_number is 0 all event scan lists are shown.

9.6.3 scanpiol

Print I/O Event Lists:

```
scanpiol
```

This routine prints a list of all records in the I/O event scan lists.

9.7 General Time

The built-in time providers depend on the IOC's target architecture, so some of the specific subsystem report commands listed below are only available on the architectures that use that particular provider.

9.7.1 generalTimeReport

Format:

```
generalTimeReport(int level)
```

This routine displays the time providers and their priority levels that have registered with the General Time subsystem for both current and event times. At level 1 it also shows the current time as obtained from each provider.

9.7.2 installLastResortEventProvider

Format:

```
installLastResortEventProvider
```

Installs the optional Last Resort event provider at priority 999, which returns the current time for every event number.

9.7.3 NTPTime_Report

Format:

```
NTPTime_Report(int level)
```

Only vxWorks and RTEMS targets use this time provider. The report displays the provider's synchronization state, and at interest level 1 it also gives the synchronization interval, when it last synchronized, the nominal and measured system tick rates, and on vxWorks the NTP server address.

9.7.4 NTPTime_Shutdown

Format:

```
NTPTime_Shutdown
```

On vxWorks and RTEMS this command shuts down the NTP time synchronization thread. With the thread shut down, the driver will no longer act as a current time provider.

9.7.5 ClockTime_Report

Format:

```
ClockTime_Report(int level)
```

This time provider is used on several target architectures, registered as the time provider of last resort. On vxWorks and RTEMS the report displays the synchronization state, when it last synchronized the system time with a higher priority provider, and the synchronization interval. On workstation operating systems the synchronization task is not started on the assumption that some other process is taking care of synchronzing the OS clock as appropriate, so the report is minimal.

9.7.6 ClockTime_Shutdown

Format:

```
ClockTime_Shutdown
```

Some sites may prefer to provide their own implementation of a system clock time provider to replace the built-in one. On vxWorks and RTEMS this command stops the OS Clock synchronization thread, allowing the OS clock to free-run. The time provider *will* continue to return the current system time after this command is used however.

9.8 Access Security Commands

9.8.1 asSetSubstitutions

Format:

```
asSetSubstitutions("substitutions")
```

Specifies macro substitutions used when access security is initialized.

9.8.2 asSetFilename

Format:

```
asSetFilename(“<filename>”)
```

This command defines a new access security file.

9.8.3 asInit

Format:

```
asInit
```

This command reinitializes the access security system. It rereads the access security file in order to create the new access security database. This command is useful either because the `asSetFilename` command was used to change the file or because the file itself was modified. Note that it is also possible to reinitialize the access security via a subroutine record. See the access security document for details.

9.8.4 asdbdump

Format:

```
asdbdump
```

This provides a complete dump of the access security database.

9.8.5 aspuag

Format:

```
aspuag(“<user access group>”)
```

Print the members of the user access group. If no user access group is specified then the members of all user access groups are displayed.

9.8.6 asphag

Format:

```
asphag("<host access group>")
```

Print the members of the host access group. If no host access group is specified then the members of all host access groups are displayed.

9.8.7 asprules

Format:

```
asprules("<access security group>")
```

Print the rules for the specified access security group or if no group is specified for all groups.

9.8.8 aspmem

Format:

```
aspmem("<access security group>", <print clients>)
```

Print the members (records) that belong to the specified access security group, for all groups if no group is specified. If `<print clients>` is (0, 1) then Channel Access clients attached to each member (are not, are) shown.

9.9 Channel Access Reports

9.9.1 casr

Channel Access Server Report

```
casr(<level>)
```

Level can have one of the following values:

0
: Prints server's protocol version level and a one line summary for each client attached. The summary lines contain the client's login name, client's host name, client's protocol version number, and the number of channel created within the server by the client.

1
: Level one provides all information in level 0 and adds the task id used by the server for each client, the client's IP protocol type, the file number used by the server for the client, the number of seconds elapsed since the last request was received from the client, the number of seconds elapsed since the last response was sent to the client, the number of unprocessed request bytes from the client, the number of response bytes which have not been flushed to the client, the client's IP address, the client's port number, and the client's state.

2
: Level two provides all information in levels 0 and 1 and adds the number of bytes allocated by each client and a list of channel names used by each client. Level 2 also provides information about the number of bytes in the server's free memory pool, the distribution of entries in the server's resource hash table, and the list of IP addresses to which the server is sending beacons. The channel names are shown in the form:

<name>(nrw)

where
n is number of ca_add_events the client has on this channel
r is (-,R) if client (does not, does) have read access to the channel.
w is(-, W) if client (does not, does) have write access to the channel.

9.9.2 dbel

Format:

```
dbel("<record_name>")
```

This routine prints the Channel Access event list for the specified record.

9.9.3 dbcar

Database to Channel Access Report - See "Record Link Reports"

9.9.4 ascar

Format:

```
ascar(level)
```

Prints a report of the channel access links for the INP fields of the access security rules. Level 0 produces a summary report. Level 1 produces a summary report plus details on any unconnect channels. Level 2 produces the summary nreport plus a detail report on each channel.

9.10 Interrupt Vectors

9.10.1 veclist

Format:

```
veclist
```

NOTE: This routine is only available on vxWorks. On PowerPC CPUs it requires BSP support to work, and even then it cannot display chained interrupts using the same vector.

Print Interrupt Vector List

9.11 Miscellaneous

9.11.1 epicsParamShow

Format:

```
   epicsParamShow
or
   epicsPrtEnvParams
```

Print the environment variables that are created with epicsEnvSet. These are defined in <base>/config/CONFIG_ENV and <base>/config/CONFIG_SITE_ENV or else by user applications calling `epicsEnvSet`.

9.11.2 epicsEnvShow

Format:

```
   epicsEnvShow("<name>")
```

Show Environment variables. On vxWorks it shows the variables created via calls to `putenv`.

9.11.3 coreRelease

Format:

```
   coreRelease
```

Print release information for iocCore.

9.12 Database System Test Routines

These routines are normally only of interest to EPICS system developers NOT to Application Developers.

9.12.1 dbtgf

Test Get Field:

```
   dbtgf(“<record_name.field_name>”)
```

Example:

```
   dbtgf(“aitest”)
   dbtgf)“aitest.VAL”)
```

This performs a `dbNameToAddr` and then calls `dbGetField` with all possible request types and options. It prints the results of each call. This routine is of most interest to system developers for testing database access.

9.12.2 dbtpf

Test Put Field:

```
dbtpf("<record_name.field_name>","<value>")
```

Example:

```
dbtpf("aitest","5.0")
```

This command performs a `dbNameToAddr`, then calls `dbPutField,` followed by `dbgf` for each possible request type. This routine is of interest to system developers for testing database access.

9.12.3 dbtpn

Test Put Notify:

```
dbtpn("<record_name.field_name>","<value>")
```

Example:

```
dbtpn("aitest","5.0")
```

This command performs a `dbNameToAddr`, then calls `dbPutNotify` and has a callback routine that prints a message when it is called. This routine is of interest to system developers for testing database access.

9.13 Record Link Reports

9.13.1 dblsr

Lock Set Report:

```
dblsr(<recordname>,<level>)
```

This command generates a report showing the lock set to which each record belongs. If `recordname` is 0, "", or "*" all records are shown, otherwise only records in the same lock set as `recordname` are shown.

`level` can have the following values:

0 - Show lock set information only.
1 - Show each record in the lock set.
2 - Show each record and all database links in the lock set.

9.13.2 dbcar

Database to channel access report

```
dbcar(<recordname>,<level>)
```

This command generates a report showing database channel access links. If `recordname` is "*" then information about all records is shown otherwise only information about the specified record.

`level` can have the following values:

0 - Show summary information only.
1 - Show summary and each CA link that is not connected.
2 - Show summary and status of each CA link.

9.13.3 dbhcr

Report hardware links. See “Hardware Reports”.

9.14 Old Database Access Testing

These routines are of interest to EPICS system developers. They are used to test the old database access interface, which is still used by Channel Access.

9.14.1 gft

Get Field Test:

```
gft(“<record_name.field_name>”)
```

Example:

```
gft(“aitest”)
gft(“aitest.VAL”)
```

This performs a `db_name_to_addr` and then calls `db_get_field` with all possible request types. It prints the results of each call. This routine is of interest to system developers for testing database access.

9.14.2 pft

Put Field Test:

```
pft(“<record_name.field_name>”,”<value>”)
```

Example:

```
pft(“aitest”,”5.0”)
```

This command performs a `db_name_to_addr`, `db_put_field`, `db_get_field` and prints the result for each possible request type. This routine is of interest to system developers for testing database access.

9.14.3 tpn

Test Put Notify:

```
tpn(“<record_name.field_name>”,”<value>”)
```

Example:

```
tpn(“aitest”,”5.0”)
```

This routine tests `dbPutNotify` via the old database access interface.

9.15 Routines to dump database information

9.15.1 dbDumpPath

Dump Path:

```
dbDumpPath(pdbbase)
```

```
dbDumpPath(pdbbase)
```

The current path for database includes is displayed.

9.15.2 dbDumpMenu

Dump Menu:

```
dbDumpMenu(pdbbase,"<menu>")
```

```
dbDumpMenu(pdbbase,"menuScan")
```

If the second argument is 0 then all menus are displayed.

9.15.3 dbDumpRecordType

Dump Record Description:

```
dbDumpRecordType(pdbbase,"<record type>")
```

```
dbDumpRecordType(pdbbase,"ai")
```

If the second argument is 0 then all descriptions of all records are displayed.

9.15.4 dbDumpField

Dump Field Description:

```
dbDumpField(pdbbase,"<record type>","<field name>")
```

```
dbDumpField(pdbbase,"ai","VAL")
```

If the second argument is 0 then the field descriptions of all records are displayed. If the third argument is 0 then the description of all fields are displayed.

9.15.5 dbDumpDevice

Dump Device Support:

```
dbDumpDevice(pdbbase,"<record type>")
```

```
dbDumpDevice(pdbbase,"ai")
```

If the second argument is 0 then the device support for all record types is displayed.

9.15.6 dbDumpDriver

Dump Driver Support:

```
dbDumpDriver(pdbbase)
```

```
dbDumpDriver(pdbbase)
```

9.15.7 dbDumpRecord

Dump Record Instances:

```
dbDumpRecord(pdbbase,"<record type>",level)
```

```
dbDumpRecords(pdbbase,"ai")
```

If the second argument is 0 then the record instances for all record types is displayed. The third argument determines which fields are displayed just like for the command `dbpr`.

9.15.8 dbDumpBreaktable

Dump breakpoint table

```
dbDumpBreaktable(pdbbase,name)
```

```
dbDumpBreaktable(pdbbase,"typeKdegF")
```

This command dumps a breakpoint table. If the second argument is 0 all breakpoint tables are dumped.

9.15.9 dbPvdDump

Dump the Process variable Directory:

```
dbPvdDump(pdbbase,verbose)
```

```
dbPvdDump(pdbbase,0)
```

This command shows how many records are mapped to each hash table entry of the process variable directory. If verbose is not 0 then the command also displays the names which hash to each hash table entry.

Chapter 10: IOC Error Logging

10.1 Overview

Errors detected by an IOC can be divided into classes: Errors related to a particular client and errors not attributable to a particular client. An example of the first type of error is an illegal Channel Access request. For this type of error, a status value should be passed back to the client. An example of the second type of error is a device driver detecting a hardware error. This type of error should be reported to a system wide error handler.

Dividing errors into these two classes is complicated by a number of factors.

- In many cases it is not possible for the routine detecting an error to decide which type of error occurred.
- Normally, only the routine detecting the error knows how to generate a fully descriptive error message. Thus, if a routine decides that the error belongs to a particular client and merely returns an error status value, the ability to generate a fully descriptive error message is lost.
- If a routine always generates fully descriptive error messages then a particular client could cause error message storms.
- While developing a new application the programmer normally prefers fully descriptive error messages. For a production system, however, the system wide error handler should not normally receive error messages cause by a particular client.

If used properly, the error handling facilities described in this chapter can process both types of errors.

This chapter describes the following:

- Error Message Generation Routines - Routines which pass messages to the errlog Task.
- Error Log Listeners - Any code can register to recieve errlog messages.
- errlogThread - A thread that passes the messages to all registered listeners.
- console output and message buffer size - Messages can also be written to the console. The storage for the message queue can be specified by the user.
- status codes - EPICS status codes.
- iocLog- A system wide error logger supplied with base. It writes all messages to a system wide file.
  NOTE: Many sites use CMLOG instead of iocLog.

NOTE: `recGbl` error routines are also provided. They in turn call one of the error message routines.

10.2 Error Message Routines

10.2.1 Basic Routines

```
int errlogPrintf(const char *pformat, ...);
int errlogVprintf(const char *pformat,va_list pvar);
int errlogMessage(const char *message);
```

```
void errlogFlush(void);
```

`errlogPrintf` and `errlogVprintf` are like `printf` and `vprintf` provided by the standard C library, except that the output is sent to the errlog task. Consult any book that describes the standard C library such as "The C Programming Language ANSI C Edition" by Kernighan and Ritchie. If epicsThreadIsOkToBlock is true, which is true during iocInit, errlogVprintf does NOT send output to the errlog task.

`errlogMessage` sends message to the errlog task.

`errlogFlush` wakes up the errlog task and then waits until all messages are flushed from the queue.

10.2.2 Log with Severity

```
typedef enum {
     errlogInfo,errlogMinor,errlogMajor,errlogFatal
}errlogSevEnum;

int errlogSevPrintf(const errlogSevEnum severity,
     const char *pformat, ...);
int errlogSevVprintf(const errlogSevEnum severity,
     const char *pformat,va_list pvar);

char *errlogGetSevEnumString(const errlogSevEnum severity);

void  errlogSetSevToLog(const errlogSevEnum severity );
errlogSevEnum errlogGetSevToLog(void);
```

`errlogSevPrintf` and `errlogSevVprintf` are like `errlogPrintf` and `errlogVprintf` except that they add the severity to the beginning of the message in the form "sevr=<value>" where value is on of "info, minor, major, fatal". Also the message is suppressed if severity is less than the current severity to suppress. If epicsThreadIsOkToBlock is true, which is true during iocInit, errlogSevVprintf does NOT send output to the errlog task.

`errlogGetSevEnumString` gets the string value of severity.

`errlogSetSevToLog` sets the severity to log. `errlogGetSevToLog` gets the current severity to log.

10.2.3 Status Routines

```
void errMessage(long status, char *message);

void errPrintf(long status, const char *pFileName,
     int lineno, const char *pformat, ...);
```

Routine `errMessage` (actually a macro that calls `errPrintf`) has the following format:

```
void errMessage(long  status, char  *message);
```

Where status is defined as:

- **0**: Find latest vxWorks or Unix error.
- **-1**: Don't report status.
- Other: See "Return Status Values" above.

`errMessage`, via a call to `errPrintf`, prints the message, the status symbol and string values, and the name of the task which invoked `errMessage`. It also prints the name of the source file and the line number from which the call was issued.

The calling routine is expected to pass a descriptive message to this routine. Many subsystems provide routines built on top of `errMessage` which generate descriptive messages.

An IOC global variable `errVerbose`, defined as an `external` in `errMdef.h`, specifies verbose messages. If `errVerbose` is `TRUE` then `errMessage` should be called whenever an error is detected even if it is known that the error belongs to a specific client. If `errVerbose` is `FALSE` then `errMessage` should be called only for errors that are not caused by a specific client.

Routine `errPrintf` is normally called as follows:

```
errPrintf(status, __FILE__, __LINE__,"<fmt>",...);
```

Where status is defined as:

- **0**: Find latest vxWorks or Unix error.
- **-1**: Don't report status.
- Other: See "Return Status Values", above.

FILE and LINE are defined as:

- __FILE__ As shown or `NULL` if the file name and line number should not be printed.
- __LINE__ As shown

The remaining arguments are just like the arguments to the C `printf` routine. `errVerbose` determines if the filename and line number are shown.

An EPICS status code can also be converted to a string. If the supplied status code isn't registered in the status code database then the raw status code number is converted into a string in the destination buffer.

```
#include "errMdef.h"
void errSymLookup(long status, char *pBuf, unsigned bufLength);
```

10.2.4 Obsolete Routines

```
int epicsPrintf(const char *pformat, ...);
int epicsVprintf(const char *pformat,va_list pvar);
```

These are macros that call errlogPrintf and errlogVprintf. They are provided for compatibility.

10.3 errlog Listeners

Any code can receive errlog message. The following are the calls to add and remove a listener.

```
typedef void(*errlogListener) (void *pvt,const char *message);
void errlogAddListener(errlogListener listener,void *pPrivate);
void errlogRemoveListener(errlogListener listener);
```

These routines add/remove a callback that receives each error message. These routines are the interface to the actual system wide error handlers.

10.4 errlogThread

The error message routines can be called by any non-interrupt level code. These routines pass the message to the errlog Thread. If any of the error message routines are called at interrupt level, `epicsInterruptContextMessage` is called with the message "errlogPrintf called from interrupt level".

errlogThread manages the messages. Messages are placed in a message queue, which is read by errlogThread. The message queue uses a fixed block of memory to hold all messages. When the message queue is full additional messages are rejected but a count of missed messages is kept. The next time the message queue empties an extra message about the missed messages is generated.

The maximum message size is by default 256 characters. If a message is longer, the message is truncated and a message explaining that it was truncated is appended. There is a chance that long messages corrupt memory. This only happens if client code is defective. Long messages most likely result from "%s" formats with a bad string argument.

errlogThread passes each message to any registered listener.

10.5 console output and message queue size

The errlog system can also display messages on the ioc console. It calls `epicsThreadIsOkToBlock` to decide when to display the message. If it is OK to block, the message is displayed by the same thread that calls one of the errlog print routines. If it is not OK to block, errlorThread displays the messages.

Normally the errlog system displays all messages on the console. `eltc` can be used to suppress these messages.

```
int eltc(int yesno); /* error log to console (0 or 1) */
int errlogInit(int bufsize);
int errlogInit2(int bufsize, int maxMsgSize);
```

eltc determines if errlog task writes message to the console. During error messages storms this command can be used to suppress console messages. A argument of 0 suppresses the messages and any other value lets the message go to the console.

errlogInit or errlogInit2 can be used to initialize the error logging system with a larger buffer and maximum message size. The default buffer size is 1280 bytes, and the default maximum message size is 256.

10.6 Status Codes

EPICS defined status values provide the following features:

- Whenever possible, IOC routines return a status value: (0, non-0) means (`OK`, `ERROR`).
- The include files for each IOC subsystem contain macros defining error status symbols and strings.
- Routines are provided for run time access of the error status symbols and strings.
- A global variable `errVerbose` helps code decide if error messages should be generated.

WARNING: During the fall of 1995 a series of tech-talk messages were generated concerning EPICS status values. No consensus was reached.

Whenever it makes sense, IOC routines return a status value encoded similar to the vxWorks error status encoding. The most significant short word indicates the subsystem module within which the error occurred. The low order short word is a subsystem status value. In order that status values do not conflict with the vxWorks error status values all subsystem numbers are greater than 500.

A file `epics/share/epicsH/errMdef.h` defines each subsystem number. For example the `define` for the database access routines is:

```
#define M_dbAccess  (501 << 16)   \
      /*Database Access Routines*/
```

Directory "`epics/share/epicsH`" contains an `include` library for every IOC subsystem that returns standard status values. The status values are encoded with lines of the following format:

```
#define S_xxxxxxx value /*string value*/
```

For example:

```
#define S_dbAccessBadDBR (M_dbAccess|3) \
      /*Invalid Database Request*/
```

For example, when `dbGetField` detects a bad database request type, it executes the statement:

```
return(S_dbAccessBadDBR);
```

The calling routine checks the return status as follows:

```
status = dbGetField( ...);
if(status) {/* Call was not successful */ }
```

10.7 iocLog

NOTE: Many sites use CMLOG instead of iocLog. See the CMLOG documentation for details.

This consists of two modules: iocLogServer and iocLogClient. The client code runs on each ioc and listens for the messages generated locally by the errlog system. It also reports the messages from the vxWorks logMsg facility.

10.7.1 iocLogServer

This runs on a host. It receives messages for all enabled iocLogClients in the local area network. The messages are written to a file. Epics base provides a startup file "base/src/util/rc2.logServer", which is a SystemV init script to start the server. Consult this script for details.

To start a log server on a UNIX or PC workstation you must first set the following environment variables and then run the executable "iocLogServer" on your PC or UNIX workstation.

EPICS_IOC_LOG_FILE_NAME
: The name and path to the log file.

EPICS_IOC_LOG_FILE_LIMIT
: The maximum size in characters for the log file (after which it becomes a circular file and writes new messages over old messages at the beginning of the file). If the value is zero then there is no limit on the size of the log file.

EPICS_IOC_LOG_FILE_COMMAND
: A shell command string used to obtain the log file path name during initialization and in response to SIGHUP. The new path name will replace any path name supplied in EPICS_IOC_LOG_FILE_NAME.
Thus, if EPICS_IOC_LOG_FILE_NAME is
"a/b/c.log" and EPICS_IOC_LOG_FILE_COMMAND returns "A/B" or "A/B/" the log server will be stored at "A/B/c.log"

If EPICS_IOC_LOG_FILE_COMMAND is empty then this behavior is disabled. This feature is used at some sites for switching the server to a new directory at a fixed time each day. This variable is currently used only by the UNIX version of the log server.

EPICS_IOC_LOG_PORT
: THE TCP/IP port used by the log server.

To configure an IOC so that its messages are placed in the log you must set the environment variable EPICS_IOC_LOG_INET to the IP address of the host that is running the log server, and EPICS_IOC_LOG_PORT to the TCP/IP port used by the log server.

Defaults for all of the above parameters are specified in the files $(EPICS_BASE)/config/CONFIG_SITE_ENV and $(EPICS_BASE)/config/CONFIG_ENV.

10.7.2 iocLogClient

This runs on each ioc. It is started by calling:

```
iocLogInit();
```

The global variable `iocLogDisable` can be used to enable/disable the messages from being sent to the server. Setting this variable to (0,1) (enables,disables) the messages generation. If `iocLogDisable` is set to 1 before calling `iocLogInit` then `iocLogClient` will not even initialize itself. `iocLogDisable` can also be changed to turn logging on or off.

`iocLogClient` calls `errlogAddListener` and sends each message to the `iocLogServer`.

10.7.3 Configuring a Private Log Server

In a testing environment it is desirable to use a private log server. This can be done as follows:

- Add a epicsEnvSet command to your IOC startup file. For example
  ```
  ld  <  iocCore
  epicsEnvSet("EPICS_IOC_LOG_INET=xxx.xxx.xxx.xxx")
  ```
  The inet address is that of your host workstation.
- On your host workstation, start the log server.

Chapter 11: Record Support

11.1 Overview

The purpose of this chapter is to describe record support in sufficient detail such that a C programmer can write new record support modules. Before attempting to write new support modules, you should carefully study a few of the existing support modules. If an existing support module is similar to the desired module most of the work will already be done.

From previous chapters, it should be clear that many things happen as a result of record processing. The details of what happens are dependent on the record type. In order to allow new record types and new device types without impacting the core IOC system, the concept of record support and device support has been created. For each record type, a record support module exists. It is responsible for all record specific details. In order to allow a record support module to be independent of device specific details, the concept of device support has been created.

A record support module consists of a standard set of routines which are called by database access routines. These routines implement record specific code. Each record type can define a standard set of device support routines specific to that record type.

By far the most important record support routine is `process`, which `dbProcess` calls when it wants to process a record. This routine is responsible for the details of record processing. In many cases it calls a device support I/O routine. The next section gives an overview of what must be done in order to process a record. Next is a description of the entry tables that must be provided by record and device support modules. The remaining sections give example record and device support modules and describe some global routines useful to record support modules.

The record and device support modules are the only modules that are allowed to include the record specific include files as defined in `base/rec`. Thus they are the only routines that access record specific fields without going through database access.

11.2 Overview of Record Processing

The most important record support routine is `process`. This routine determines what record processing means. Before the record specific "`process`" routine is called, the following has already been done:

- Decision to process a record.
- Check that record is not active, i.e. `pact` must be FALSE.
- Check that the record is not disabled.

The `process` routine, together with its associated device support, is responsible for the following tasks:

- Set record active while it is being processed
- Perform I/O (with aid of device support)
- Check for record specific alarm conditions
- Raise database monitors
- Request processing of forward links

A complication of record processing is that some devices are intrinsically asynchronous. It is **NEVER** permissible to wait for a slow device to complete. Asynchronous records perform the following steps:

1. Initiate the I/O operation and set `pact TRUE`
2. Determine a method for again calling process when the operation completes
3. Return immediately without completing record processing
4. When process is called after the I/O operation complete record processing
5. Set `pact FALSE` and return

The examples given below show how this can be done.

11.3 Record Support and Device Support Entry Tables

Each record type has an associated set of record support routines. These routines are located via the data structures defined in `epics/share/epicsH/recSup.h`. The concept of record support routines isolates the `iocCore` software from the details of each record type. Thus new records can be defined and supported without affecting the IOC core software.

Each record type also has zero or more sets of device support routines. Record types without associated hardware, e.g. calculation records, normally do not have any associated device support. Record types with associated hardware normally have a device support module for each device type. The concept of device support isolates IOC core software and even record support from device specific details.

Corresponding to each record type is a set of record support routines. The set of routines is the same for every record type. These routines are located via a Record Support Entry Table (RSET), which has the following structure

```
rset {   /* record support entry table */
   long     number;       /* number of support routine */
   RECSUPFUN   report;       /* print report */
   RECSUPFUN   init;         /* init support */
   RECSUPFUN   init_record;  /* init record */
   RECSUPFUN   process;      /* process record */
   RECSUPFUN   special;     /* special processing */
   RECSUPFUN   get_value;   /* OBSOLETE: Just leave NULL */
   RECSUPFUN   cvt_dbaddr;   /* cvt  dbAddr */
   RECSUPFUN   get_array_info;
   RECSUPFUN   put_array_info;
   RECSUPFUN   get_units;
   RECSUPFUN   get_precision;
   RECSUPFUN   get_enum_str;   /* get string from enum */
   RECSUPFUN   get_enum_strs;   /* get all enum strings */
   RECSUPFUN   put_enum_str;   /* put enum from string */
   RECSUPFUN   get_graphic_double;
   RECSUPFUN   get_control_double;
   RECSUPFUN   get_alarm_double;
};
```

Each record support module must define its RSET. The external name must be of the form:

```
<record_type>RSET
```

Any routines not needed for the particular record type should be initialized to the value `NULL`. Look at the example below for details.

Device support routines are located via a Device Support Entry Table (DSET), which has the following structure:

```
struct dset {   /* device support entry table */
   long         number;   /* number of support routines */
   DEVSUPFUN   report;   /* print report */
   DEVSUPFUN   init;   /* init support */
   DEVSUPFUN   init_record;/* init record instance*/
   DEVSUPFUN    get_ioint_info;   /* get io interrupt info*/
   /* other functions are record dependent*/
};
```

Each device support module must define its associated DSET. The external name must be the same as the name which appears in `devSup.ascii`.

Any record support module which has associated device support must also include definitions for accessing its associated device support modules. The field"`dset`", which is located in `dbCommon`, contains the address of the DSET. It is given a value by `iocInit`.

11.4 Example Record Support Module

This section contains the skeleton of a record support package. The record type is `xxx` and the record has the following fields in addition to the `dbCommon` fields: `VAL`, `PREC`, `EGU`, `HOPR`, `LOPR`, `HIHI`, `LOLO`, `HIGH`, `LOW`, `HHSV`, `LLSV`, `HSV`, `LSV`, `HYST`, `ADEL`, `MDEL`, `LALM`, `ALST`, `MLST`. These fields will have the same meaning as they have for the `ai` record. Consult the Record Reference manual for a description.

11.4.1 Declarations

```
/* Create RSET - Record Support Entry Table*/
#define report NULL
#define initialize NULL
static long init_record();
static long process();
#define special NULL
#define get_value NULL
#define cvt_dbaddr NULL
#define get_array_info NULL
#define put_array_info NULL
static long get_units();
static long get_precision();
#define get_enum_str NULL
#define get_enum_strs NULL
#define put_enum_str NULL
static long get_graphic_double();
static long get_control_double();
static long get_alarm_double();

rset xxxRSET={
   RSETNUMBER,
   report,
   initialize,
   init_record,
```

```
   process,
   special,
   get_value,
   cvt_dbaddr,
   get_array_info,
   put_array_info,
   get_units,
   get_precision,
   get_enum_str,
   get_enum_strs,
   put_enum_str,
   get_graphic_double,
   get_control_double,
   get_alarm_double
};
epicsExportAddress(rset,xxxRSET);

/* declarations for associated DSET */
typedef struct xxxdset { /* analog input dset */
   long   number;
   DEVSUPFUN   dev_report;
   DEVSUPFUN   init;
   DEVSUPFUN   init_record; /* returns: (1,0)=> (failure, success)*/
   DEVSUPFUN   get_ioint_info;
   DEVSUPFUN   read_xxx;
}xxxdset;

/* forward declaration for internal routines*/
static void checkAlarams(xxxRecord *pxxx);
static void monitor(xxxRecord *pxxx);
```

The above declarations define the Record Support Entry Table (RSET), a template for the associated Device Support Entry Table (DSET), and forward declarations to private routines.

The RSET must be declared with an external name of `xxxRSET`. It defines the record support routines supplied for this record type. Note that forward declarations are given for all routines supported and a `NULL` declaration for any routine not supported.

The template for the DSET is declared for use by this module.

11.4.2 init_record

```
static long init_record(void *precord, int  pass)
{
   xxxRecord*pxxx = (xxxRecord *)precord;
   xxxdset  *pdset;
   long     status;

   if(pass==0) return(0);

   if((pdset = (xxxdset *)(pxxx->dset)) == NULL) {
      recGblRecordError(S_dev_noDSET,pxxx,"xxx: init_record");
      return(S_dev_noDSET);
   }
```

```
   /* must have read_xxx function defined */
   if( (pdset->number < 5) || (pdset->read_xxx == NULL) ) {
      recGblRecordError(S_dev_missingSup,pxxx,
         ”xxx: init_record”);
      return(S_dev_missingSup);
   }
   if( pdset->init_record ) {
      if((status=(*pdset->init_record)(pxxx))) return(status);
   }
   return(0);
}
```

This routine, which is called by `iocInit` twice for each record of type `xxx`, checks to see if it has a proper set of device support routines and, if present, calls the `init_record` entry of the DSET.

During the first call to `init_record` (pass=0) only initializations relating to this record can be performed. During the second call (pass=1) initializations that may refer to other records can be performed. Note also that during the second pass, other records may refer to fields within this record. A good example of where these rules are important is a waveform record. The `VAL` field of a waveform record actually refers to an array. The waveform record support module must allocate storage for the array. If another record has a database link referring to the waveform `VAL` field then the storage must be allocated before the link is resolved. This is accomplished by having the waveform record support allocate the array during the first pass (pass=0) and having the link reference resolved during the second pass (pass=1).

11.4.3 process

```
static long process(void *precord)
{
   xxxRecord*pxxx = (xxxRecord *)precord;
   xxxdset  *pdset = (xxxdset *)pxxx->dset;
   long     status;
   unsigned char pact=pxxx->pact;

   if( (pdset==NULL) || (pdset->read_xxx==NULL) ) {
      /* leave pact true so that dbProcess doesnt call again*/
      pxxx->pact=TRUE;
      recGblRecordError(S_dev_missingSup,pxxx,”read_xxx”);
      return(S_dev_missingSup);
   }

   /* pact must not be set true until read_xxx completes*/
   status=(*pdset->read_xxx)(pxxx); /* read the new value */
    /* return if beginning of asynch processing*/
   if(!pact && pxxx->pact) return(0);
   pxxx->pact = TRUE;
   recGblGetTimeStamp(pxxx);

   /* check for alarms */
   alarm(pxxx);
   /* check event list */
   monitor(pxxx);
   /* process the forward scan link record */
   recGblFwdLink(pxxx);
```

```
   pxxx->pact=FALSE;
   return(status);
}
```

The record processing routines are the heart of the IOC software. The record specific process routine is called by `dbProcess` whenever it decides that a record should be processed. Process decides what record processing really means. The above is a good example of what should be done. In addition to being called by `dbProcess` the process routine may also be called by asynchronous record completion routines.

The above model supports both synchronous and asynchronous device support routines. For example, if `read_xxx` is an asynchronous routine, the following sequence of events will occur:

- `process` is called with `pact` `FALSE`
- `read_xxx` is called. Since `pact` is `FALSE` it starts I/O, arranges callback, and sets `pact` `TRUE`
- `read_xxx` returns
- because `pact` went from `FALSE` to `TRUE` process just returns
- Any new call to `dbProcess` is ignored because it finds `pact` `TRUE`
- Sometime later the callback occurs and `process` is called again.
- `read_xxx` is called. Since `pact` is `TRUE` it knows that it is a completion request.
- `read_xxx` returns
- `process` completes record processing
- `pact` is set `FALSE`
- `process` returns

At this point the record has been completely processed. The next time `process` is called everything starts all over from the beginning.

11.4.4 Miscellaneous Utility Routines

```
static long get_units(DBADDR *paddr, char *units)
{
   xxxRecord  *pxxx=(xxxRecord *)paddr->precord;

   strncpy(units,pxxx->egu,sizeof(pxxx->egu));
   return(0);
}

static long get_graphic_double(DBADDR *paddr,
      struct dbr_grDouble *pgd)
{
   xxxRecord  *pxxx=(xxxRecord *)paddr->precord;
   int      fieldIndex = dbGetFieldIndex(paddr);

   if(fieldIndex == xxxRecordVAL) {
      pgd->upper_disp_limit = pxxx->hopr;
      pgd->lower_disp_limit = pxxx->lopr;
   } else recGblGetGraphicDouble(paddr,pgd);
   return(0);
}
/* similar routines would be provided for */
/* get_control_double and get_alarm_double*/
```

These are a few examples of various routines supplied by a typical record support package. The functions that must be performed by the remaining routines are described in the next section.

11.4.5 Alarm Processing

```
static void checkAlarms(xxxRecord *pxxx)
{
   double        val;
   float         hyst,lalm,hihi,high,low,lolo;
   unsigned short hhsv,llsv,hsv,lsv;

   if(pxxx->udf == TRUE ){
      recGblSetSevr(pxxx,UDF_ALARM,VALID_ALARM);
      return;
   }

   hihi=pxxx->hihi; lolo=pxxx->lolo;
   high=pxxx->high; low=pxxx->low;
   hhsv=pxxx->hhsv; llsv=pxxx->llsv;
   hsv=pxxx->hsv; lsv=pxxx->lsv;
   val=pxxx->val; hyst=pxxx->hyst; lalm=pxxx->lalm;

   /* alarm condition hihi */
   if (hhsv && (val >= hihi
   || ((lalm==hihi) && (val >= hihi-hyst)))) {
      if(recGblSetSevr(pxxx,HIHI_ALARM,pxxx->hhsv)
          pxxx->lalm = hihi;
      return;
   }
   /* alarm condition lolo */
   if (llsv && (val <= lolo
   || ((lalm==lolo) && (val <= lolo+hyst)))) {
      if(recGblSetSevr(pxxx,LOLO_ALARM,pxxx->llsv))
         pxxx->lalm = lolo;
      return;
   }
   /* alarm condition high */
   if (hsv && (val >= high
   || ((lalm==high) && (val >= high-hyst)))) {
      if(recGblSetSevr(pxxx,HIGH_ALARM,pxxx->hsv))
         pxxx->lalm = high;
      return;
   }
   /* alarm condition low */
   if (lsv && (val <= low
   || (lalm==low) && (val <= low+hyst)))) {
      if(recGblSetSevr(pxxx,LOW_ALARM,pxxx->lsv))
         pxxx->lalm = low;
      return;
   }
   /*we get here only if val is out of alarm by at least hyst*/
   pxxx->lalm=val;
```

```
   return;
}
```

This is a typical set of code for checking alarms conditions for an analog type record. The actual set of code can be very record specific. Note also that other parts of the system can raise alarms. The algorithm is to always maximize alarm severity, i.e. the highest severity outstanding alarm will be reported.

The above algorithm also honors a hysteresis factor for the alarm. This is to prevent alarm storms from occurring in the event that the current value is very near an alarm limit and noise makes it continually cross the limit. It honors the hysteresis only when the value is going to a lower alarm severity.

Note the test:

```
   if(pxxx->udf == TRUE ){
      recGblSetSevr(pxxx,UDF_ALARM,VALID_ALARM);
      return;
   }
```

Database common defines the field UDF, which means that field VAL is undefined. The STAT and SEVR fields are initialized as though `recGblSetSevr(pxxx,UDF_ALARM,VALID_ALARM)`was called. Thus if the record is never processed the record will be in an INVALID UNDEFINED alarm state. Field UDF is initialized to the value 1, i.e. TRUE. Thus the above code will keep the record in the INVALID UNDEFINED alarm state as long as UDF is not given the value 0.

The UDF field means Undefined, i.e. the VAL field has never been given a value. When records are loaded into an ioc this is the initial state of records. Whevever code gives a value to the VAL field it is also supposed to set UDF false. Unless a particular record type has unusual semantics no code should set UDF true. UDF normally means that the field was never given a value.

For input records device support is responsible for obtaining an input value. If no input value can be obtained neither record support nor device support sets UDF false. If device support reads a raw value it returns a value telling record support to perform a conversion. After the record support sets VAL equal to the converted value, it sets UDF false. If device support obtains a converted value that it writes to VAL, it sets UDF false.

For output records either something outside record/device support writes to the VAL field or else VAL is given a value because record support obtains a value via the OMSL field. In either case the code that writes to the VAL field sets UDF false.

Whenever database access writes to the VAL field it sets UDF false.

Routine recGblSetSevr is called to raise alarms. It can be called by iocCore, record support, or device support. The code that detects an alarm is responsible for raising the alarm.

11.4.6 Raising Monitors

```
static void monitor(xxxRecord *pxxx)
{
   unsigned short   monitor_mask;
   float            delta;

   monitor_mask = recGblResetAlarms(pxxx);
   /* check for value change */
   delta = pxxx->mlst - pxxx->val;
   if(delta<0.0) delta = -delta;
   if (delta > pxxx->mdel) {
      /* post events for value change */
      monitor_mask |= DBE_VALUE;
```

```
      /* update last value monitored */
      pxxx->mlst = pxxx->val;
   }
   /* check for archive change */
   delta = pxxx->alst - pxxx->val;
   if(delta<0.0) delta = 0.0;
   if (delta > pxxx->adel) {
      /* post events on value field for archive change */
      monitor_mask |= DBE_LOG;
      /* update last archive value monitored */
      pxxx->alst = pxxx->val;
   }
   /* send out monitors connected to the value field */
   if (monitor_mask){
      db_post_events(pxxx,&pxxx->val,monitor_mask);
   }
   return;
}
```

All record types should call `recGblResetAlarms` as shown. Note that `nsta` and `nsev` will have the value 0 after this routine completes. This is necessary to ensure that alarm checking starts fresh after processing completes. The code also takes care of raising alarm monitors when a record changes from an alarm state to the no alarm state. It is essential that record support routines follow the above model or else alarm processing will not follow the rules.

Analog type records should also provide monitor and archive hysteresis fields as shown by this example.

`db_post_events` results in channel access issuing monitors for clients attached to the record and field. The call is

```
int db_post_events(void *precord, void *pfield,
      unsigned int monitor_mask)
```

where:

`precord` - The address of the record
`pfield` - The address of the field
`monitor_mask` - A bit mask that can be any combinations of the following:
DBE_ALARM - A change of alarm state has occured. This is set by `recGblResetAlarms`.
DBE_LOG - Archive change of state.
DBE_VAL - Value change of state

IMPORTANT: The record support module is responsible for calling `db_post_event` for any fields that change as a result of record processing. Also it should **NOT** call `db_post_event` for fields that do not change.

11.5 Record Support Routines

This section describes the routines defined in the RSET. Any routine that does not apply to a specific record type must be declared `NULL`.

11.5.1 Generate Report of Each Field in Record

```
report(void *precord);   /* addr of record*/
```

This routine is not used by most record types. Any action is record type specific.

11.5.2 Initialize Record Processing

```
initialize(void);
```

This routine is called once at IOC initialization time. Any action is record type specific. Most record types do not need this routine.

11.5.3 Initialize Specific Record

```
init_record(
   void *precord,   /* addr of record*/
   int     pass);
```

`iocInit` calls this routine twice (pass=0 and pass=1) for each database record of the type handled by this routine. It must perform the following functions:

- Check and/or issue initialization calls for the associated device support routines.
- Perform any record type specific initialization.
- During the first pass it can only perform initializations that affect the record referenced by precord.
- During the second pass it can perform initializations that affect other records.

11.5.4 Process Record

```
process(void *precord);   /* addr of record*/
```

This routine must follow the guidelines specified previously.

11.5.5 Special Processing

```
special(
   struct dbAddr   *paddr,
   int   after);/*(FALSE,TRUE)=>(Before,After)Processing*/
```

This routine implements the record type specific special processing for the field referred to by `dbAddr`. Note that it is called twice. Once before any changes are made to the associated field and once after. File `special.h` defines special types. This routine is only called for user special fields, i.e. fields with `SPC_xxx` >= 100. A field is declared special in the ASCII record definition file. New values should not by added to `special.h`, instead use `SPC_MOD`.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.5.6 Get Value

This routine is no longer used. It should be left as a NULL procedure in the record support entry table.

11.5.7 Convert dbAddr Definitions

```
cvt_dbaddr(struct dbAddr *paddr);
```

This routine is called by `dbNameToAddr` if the field has special set equal to `SPC_DBADDR`. A typical use is when a field refers to an array. This routine can change any combination of the `dbAddr` fields: `no_elements`, `field_type`, `field_size`, `special,pfield,` and `dbr_type`. For example if the `VAL` field of a waveform record is passed to `dbNameToAddr`, `cvt_dbaddr` would change `dbAddr` so that it refers to the actual array rather then `VAL`.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

NOTES:

- Channel access calls db_name_to_addr, which is part of old database access. Db_name_to_addr calls dbNameToAddr. This is done when a client connects to the record.
- no_elements must be set to the maximum number of elements that will ever be stored in the array.

11.5.8 Get Array Information

```
get_array_info(
   struct dbAddr  *paddr,
   long   *no_elements,
   long   *offset);
```

This routine returns the current number of elements and the offset of the first value of the specified array. The offset field is meaningful if the array is actually a circular buffer.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified. It is permissible for `get_array_info` to change `pfield`. This feature can be used to implement double buffering.

When an array field is being written `get_array_info` is called before the field values are changed.

11.5.9 Put Array Information

```
put_array_info(
   struct dbAddr   *paddr,
   long   nNew);
```

This routine is called after new values have been placed in the specified array.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.5.10 Get Units

```
get_units(
   struct dbAddr  *paddr,
   char  *punits);
```

This routine sets units equal to the engineering units for the field.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.5.11 Get Precision

```
get_precision(
   struct dbAddr  *paddr,
   long   *precision);
```

This routine gets the precision, i.e. number of decimal places, which should be used to convert the field value to an ASCII string. `recGblGetPrec` should be called for fields not directly related to the value field.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.5.12 Get Enumerated String

```
get_enum_str(
   struct dbAddr  *paddr,
   char  *p);
```

This routine sets `*p` equal to the ASCII string for the field value. The field must have type `DBF_ENUM`.

Look at the code for the `bi` or `mbbi` records for examples.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.5.13 Get Strings for Enumerated Field

```
get_enum_strs(
   struct dbAddr   *paddr,
   struct dbr_enumStrs  *p);
```

This routine gives values to all fields of structure `dbr_enumStrs`.

Look at the code for the `bi` or `mbbi` records for examples.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.5.14 Put Enumerated String

```
put_enum_str(
   struct dbAddr  *paddr,
   char  *p);
```

Given an ASCII string, this routine updates the database field. It compares the string with the string values associated with each enumerated value and if it finds a match sets the database field equal to the index of the string which matched.

Look at the code for the `bi` or `mbbi` records for examples.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.5.15 Get Graphic Double Information

```
get_graphic_double(
   struct dbAddr  *paddr,
   struct dbr_grDouble  *p);   /* addr of return info*/
```

This routine fills in the graphics related fields of structure `dbr_grDouble`. `recGblGetGraphicDouble` should be called for fields not directly related to the value field.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.5.16 Get Control Double Information

```
get_control_double(
   struct dbAddr  *paddr,
   struct dbr_ctrlDouble  *p);  /* addr of return info*/
```

This routine gives values to all fields of structure `dbr_ctrlDouble`. `recGblGetControlDouble` should be called for fields not directly related to the value field.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.5.17 Get Alarm Double Information

```
get_alarm_double(
   struct dbAddr  *paddr,
   struct dbr_alDouble  *p);  /* addr of return info*/
```

This routine gives values to all fields of structure `dbr_alDouble`.

The database access routine, `dbGetFieldIndex` can be used to determine which field is being modified.

11.6 Global Record Support Routines

A number of global record support routines are available. These routines are intended for use by the record specific processing routines but can be called by any routine that wishes to use their services.

The name of each of these routines begins with ”`recGbl`”.

11.6.1 Alarm Status and Severity

Alarms may be raised in many different places during the course of record processing. The algorithm is to maximize the alarm severity, i.e. the highest severity outstanding alarm is raised. If more than one alarm of the same severity is found then the first one is reported. This means that whenever a code fragment wants to raise an alarm, it does so only if the alarm severity it will declare is greater then that already existing. Four fields (in database common) are used to implement alarms: `sevr`, `stat`, `nsev`, and `nsta`. The first two are the status and severity after the record is completely processed. The last two fields (`nsta` and `nsev`) are the status and severity values to set during record processing. Two routines are used for handling alarms. Whenever a routine wants to raise an alarm it calls `recGblSetSevr`. This routine will only change `nsta` and `nsev` if it will result in the alarm severity being increased. At the end of processing, the record support module must call `recGblResetAlarms`. This routine sets `stat`=`nsta`, `sevr`=`nsev`, `nsta`=0, and `nsev`=0. If `stat` or `sevr` has changed value since the last call it calls `db_post_event` for `stat` and `sevr` and returns a value of `DBE_ALARM`. If no change occured it returns 0. Thus after calling `recGblResetAlarms` everything is ready for raising alarms the next time the record is processed. The example record support module presented above shows how these macros are used.

```
recGblSetSevr(
   void   *precord,
   short   nsta,
   short   nsevr);
```

Returns: (`TRUE`, `FALSE`) if (did, did not) change `nsta` and `nsev`.

```
unsigned short recGblResetAlarms(void  *precord);
```

Returns: Initial value for `monitor_mask`

11.6.2 Alarm Acknowledgment

Database common contains two additional alarm related fields: `acks` (Highest severity unacknowledged alarm) and `ackt` (does transient alarm need to be acknowledged). These field are handled by `iocCore` and `recGblResetAlarms` and are not the responsibility of record support. These fields are intended for use by the alarm handler.

11.6.3 Generate Error: Process Variable Name, Caller, Message

SUGGESTION: use `errlogPrintf` instead of this for new code.

```
recGblDbaddrError(
   long   status,
   struct dbAddr  *paddr,
   char   *pcaller_name); /* calling routine name */
```

This routine interfaces with the system wide error handling system to display the following information: Status information, process variable name, calling routine.

11.6.4 Generate Error: Status String, Record Name, Caller

SUGGESTION: use `errlogPrintf` instead of this for new code.

```
recGblRecordError(
   long   status,
   void   *precord,   /* addr of record  */
   char   *pcaller_name);   /* calling routine name */
```

This routine interfaces with the system wide error handling system to display the following information: Status information, record name, calling routine.

11.6.5 Generate Error: Record Name, Caller, Record Support Message

SUGGESTION: use `errlogPrintf` instead of this for new code.

```
recGblRecsupError(
   long   status,
   struct   dbAddr   *paddr,
   char   *pcaller_name,   /* calling routine name */
   char   *psupport_name);   /* support routine name*/
```

This routine interfaces with the system wide error handling system to display the following information: Status information, record name, calling routine, record support entry name.

11.6.6 Get Graphics Double

```
recGblGetGraphicDouble(
   struct dbAddr  *paddr,
   struct dbr_grDouble  *pgd);
```

This routine can be used by the `get_graphic_double` record support routine to obtain graphics values for fields that it doesn't know how to set.

11.6.7 Get Control Double

```
recGblGetControlDouble(
   struct dbAddr  *paddr,
   struct dbr_ctrlDouble   *pcd);
```

This routine can be used by the `get_control_double` record support routine to obtain control values for fields that it doesn't know how to set.

11.6.8 Get Alarm Double

```
recGblGetAlarmDouble(
   struct dbAddr  *paddr,
   struct dbr_alDouble  *pcd);
```

This routine can be used by the `get_alarm_double` record support routine to obtain control values for fields that it doesn't know how to set.

11.6.9 Get Precision

```
recGblGetPrec(
   struct dbAddr  *paddr,
   long  *pprecision);
```

This routine can be used by the `get_precision` record support routine to obtain the precision for fields that it doesn't know how to set the precision.

11.6.10 Get Time Stamp

```
recGblGetTimeStamp(void *precord)
```

This routine gets the current time stamp and puts it in the record It does the following:

- If TSEL is not a constant link and TSEL refers to the TIME field of a record, the time is obtained from the record reference by TSEL and this put in field TIME. The routine then returns.
- If TSEL is not a constant link dbGetLink is called and the value put in field TSE.
- If TSE is equal to `epicsTimeEventDeviceTime` (-2) then noting is done, i.e. the routine just returns.
- `epicsTimeGetEvent` is called.

11.6.11 Forward link

```
recGblFwdLink(
   void *precord);
```

This routine can be used by process to request processing of forward links.

11.6.12 Initialize Constant Link

```
 int recGblInitConstantLink(
   struct link  *plink,
   short  dbfType,
   void   *pdest);
```

Initialize a constant link. This routine is usually called by `init_record` (or by associated device support) to initialize the field associated with a constant link. It returns(FALSE, TRUE) if it (did not, did) modify the destination.

Chapter 12: Device Support

12.1 Overview

In addition to a record support module, each record type can have an arbitrary number of device support modules. The purpose of device support is to hide hardware specific details from record processing routines. Thus support can be developed for a new device without changing the record support routines.

A device support routine has knowledge of the record definition. It also knows how to talk to the hardware directly or how to call a device driver which interfaces to the hardware. Thus device support routines are the interface between hardware specific fields in a database record and device drivers or the hardware itself.

Release 3.14.8 introduced the concept of extended device support, which provides an optional interface that a device support can implement to obtain notification when a record's address is changed at runtime. This permits records to be reconnected to a different kind of I/O device, or just to a different signal on the same device. Extended device support is described in more detail in Section 12.5 on page 188 below.

Database common contains two device related fields:

- **dtyp**: Device Type.
- **dset**: Address of Device Support Entry Table.

The field `dtyp` contains the index of the menu choice as defined by the device ASCII definitions. `iocInit` uses this field and the device support structures defined in `devSup.h` to initialize the field `dset`. Thus record support can locate its associated device support via the `dset` field.

Device support modules can be divided into two basic classes: synchronous and asynchronous. Synchronous device support is used for hardware that can be accessed without delays for I/O. Many register based devices are synchronous devices. Other devices, for example all GPIB devices, can only be accessed via I/O requests that may take large amounts of time to complete. Such devices must have associated asynchronous device support. Asynchronous device support makes it more difficult to create databases that have linked records.

If a device can be accessed with a delay of less then a few microseconds then synchronous device support is appropriate. If a device causes delays of greater than 100 microseconds then asynchronous device support is appropriate. If the delay is between these values your guess about what to do is as good as mine. Perhaps you should ask the hardware designer why such a device was created.

If a device takes a long time to accept requests there is another option than asynchronous device support. A driver can be created that periodically polls all its attached input devices. The device support just returns the latest polled value. For outputs, device support just notifies the driver that a new value must be written. the driver, during one of its polling phases, writes the new value. The EPICS Allen Bradley device/driver support is a good example.

12.2 Example Synchronous Device Support Module

```
/* Create the dset for devAiSoft */
long init_record();
```

```
long read_ai();
struct {
   long   number;
   DEVSUPFUN   report;
   DEVSUPFUN   init;
   DEVSUPFUN   init_record;
   DEVSUPFUN   get_ioint_info;
   DEVSUPFUN   read_ai;
   DEVSUPFUN   special_linconv;
}devAiSoft={
   6,
   NULL,
   NULL,
   init_record,
   NULL,
   read_ai,
   NULL
};
epicsExportAddress(dset,devAiSoft);

static long init_record(void *precord)
{
   aiRecord  *pai = (aiRecord *)precord;
   long status;

   /* ai.inp must be a CONSTANT, PV_LINK, DB_LINK or CA_LINK*/
   switch (pai->inp.type) {
      case (CONSTANT) :
         if(recGblInitConstantLink(&pai->inp,DBF_DOUBLE,&pai->val))
            pai->udf = FALSE;
         break;
      case (PV_LINK) :
      case (DB_LINK) :
      case (CA_LINK) :
         break;
      default :
         recGblRecordError(S_db_badField, (void *)pai,
            ”devAiSoft (init_record) Illegal INP field”);
      return(S_db_badField);
   }
   /* Make sure record processing routine does not perform any conversion*/
   pai->linr=0;
   return(0);
}

static long read_ai(void *precord)
{
   aiRecord*pai =(aiRecord *)precord;
   long  status;

   status=dbGetGetLink(&(pai->inp.value.db_link),
      (void *)pai,DBR_DOUBLE,&(pai->val),0,1);
   if (pai->inp.type!=CONSTANT && RTN_SUCCESS(status)) pai->udf = FALSE;
```

```
   return(2); /*don't convert*/
}
```

The example is `devAiSoft`, which supports soft analog inputs. The `INP` field can be a constant or a database link or a channel access link. Only two routines are provided (the rest are declared `NULL`). The `init_record` routine first checks that the link type is valid. If the link is a constant it initializes `VAL` If the link is a Process Variable link it calls `dbCaGetLink` to turn it into a Channel Access link. The `read_ai` routine obtains an input value if the link is a database or Channel Access link, otherwise it doesn't have to do anything.

12.3 Example Asynchronous Device Support Module

This example shows how to write an asynchronous device support routine. It does the following sequence of operations:

1. When first called `pact` is `FALSE`. It arranges for a callback (`myCallback`) routine to be called after a number of seconds specified by the `DISV` field.
2. It prints a message stating that processing has started, sets `pact` `TRUE`, and returns. The record processing routine returns without completing processing.
3. When the specified time elapses `myCallback` is called. It calls `dbScanLock` to lock the record, calls `process`, and calls `dbScanUnlock` to unlock the record. It calls the process entry of the record support module, which it locates via the `rset` field in `dbCommon`, directly rather than `dbProcess`. `dbProcess` would not call `process` because `pact` is `TRUE`.
4. When `process` executes, it again calls `read_ai`. This time `pact` is `TRUE`.
5. `read_ai` prints a message stating that record processing is complete and returns a status of 2. Normally a value of 0 would be returned. The value 2 tells the record support routine not to attempt any conversions. This is a convention (a bad convention!) used by the analog input record.
6. When `read_ai` returns the record processing routine completes record processing.

At this point the record has been completely processed. The next time process is called everything starts all over.

Note that this is somewhat of an artificial example since real code of this form would more likely use the callbackcallbackRequestProcessCallbackDelayed function to perform the required processing.

```
static void myCallback(CALLBACK *pcallback)
{
    struct dbCommon *precord;
    struct rset     *prset;

    callbackGetUser(precord,pcallback);
    prset=(struct rset *)(precord->rset);
    dbScanLock(precord);
    (*prset->process)(precord);
    dbScanUnlock(precord);
}

static long init_record(struct aiRecord *pai)
{
    CALLBACK *pcallback;
    switch (pai->inp.type) {
    case (CONSTANT) :
        pcallback = (CALLBACK *)(calloc(1,sizeof(CALLBACK)));
        callbackSetCallback(myCallback,pcallback);
        callbackSetUser(pai,pcallback);
```

```
        pai->dpvt = (void *)pcallback;
        break;
    default :
        recGblRecordError(S_db_badField,(void *)pai,
            "devAiTestAsyn (init_record) Illegal INP field");
        return(S_db_badField);
    }
    return(0);
}

static long read_ai(struct aiRecord *pai)
{
    CALLBACK *pcallback = (CALLBACK *)pai->dpvt;
    if(pai->pact) {
        pai->val += 0.1; /* Change VAL just to show we've done something. */
        pai->udf = FALSE; /* We modify VAL so we are responsible for UDF too. */
        printf("Completed asynchronous processing: %s\n",pai->name);
        return(2); /* don't convert*/
    }
    printf("Starting asynchronous processing: %s\n",pai->name);
    pai->pact=TRUE;
    callbackRequestDelayed(pcallback,pai->disv);
    return(0);
}

/* Create the dset for devAiTestAsyn */
struct {
    long        number;
    DEVSUPFUN   report;
    DEVSUPFUN   init;
    DEVSUPFUN   init_record;
    DEVSUPFUN   get_ioint_info;
    DEVSUPFUN   read_ai;
    DEVSUPFUN   special_linconv;
}devAiTestAsyn={
    6,
    NULL,
    NULL,
    init_record,
    NULL,
    read_ai,
    NULL
};
epicsExportAddress(dset,devAiTestAsyn);
```

12.4 Device Support Routines

This section describes the routines defined in the DSET. Any routine that does not apply to a specific record type must be declared `NULL`.

12.4.1 Generate Device Report

```
long report(
   int   interest);
```

This routine is responsible for reporting all I/O cards it has found. If `interest` is (0,1) then generate a (short, long) report. If a device support module is using a driver, it normally does not have to implement this routine because the driver generates the report.

12.4.2 Initialize Device Processing

```
long init(
   int   after);
```

This routine is called twice at IOC initialization time. Any action is device specific. This routine is called twice: once before any database records are initialized and once after all records are initialized but before the scan tasks are started. `after` has the value (0,1) (before, after) record initialization.

12.4.3 Initialize Specific Record

```
long init_record(
   void *precord);   /* addr of record*/
```

The record support `init_record` routine calls this routine.

12.4.4 Get I/O Interrupt Information

```
long get_ioint_info(
   int   cmd,
   struct dbCommon   *precord,
   IOSCANPVT   *ppvt);
```

This is called by the I/O interrupt scan task. If `cmd` is (0,1) then this routine is being called when the associated record is being (placed in, taken out of) an I/O scan list. See the chapter on scanning for details.

It should be noted that a previous type of I/O event scanning is still supported. It is not described in this document because, hopefully, it will go away in the near future. When it calls this routine the arguments have completely different meanings.

12.4.5 Other Device Support Routines

All other device support routines are record type specific.

12.5 Extended Device Support

This section describes the additional behaviour and routines required for a device support layer to support online changes to a record's hardware address.

12.5.1 Rationale

In releases prior to R3.14.8 it is possible to change the value of the INP or OUT field of a record but (unless a soft device support is in use) this generally has no effect on the behaviour of the device support at all. Some device supports have been written that check this hardware address field for changes every time they process, but they are in the minority and in any case they do not provide any means to switch between different device support layers at runtime since no software is present that can lookup a new value for the DSET field after iocInit.

The extended device interface has been carefully designed to retain maximal backwards compatibility with existing device and record support layers, and as a result it cannot just introduce new routines into the DSET:

- Different record types have different numbers of DSET routines
- Every device support layer defines its own DSET structure layout
- Some device support layers add their own routines to the DSET (GPIB, BitBus)

Since both basic and extended device support layers have to co-exist within the same IOC, some rules are enforced concerning whether the device address of a particular record is allowed to be changed:

1. Records that were connected at iocInit to a device support layer that does not implement the extended interface are never allowed to have address fields changed at runtime.
2. Extended device support layers are not required to implement both the `add_record` and `del_record` routines, thus some devices may only allow one-way changes.
3. The old device support layer is informed and allowed to refuse an address change before the field change is made (it does not get to see the new address).
4. The new device support layer is informed after the field change has been made, and it may refuse to accept the record. In this case the record will be set as permanently busy (PACT=true) until an address is accepted.
5. Record support layers can also get notified about this process by making their address field special, in which case the record type's special routine can refuse to accept the new address before it is presented to the device support layer. Special cannot prevent the old device support from being disconnected however.

If an address change is refused, the change to the INP or OUT field will cause an error or exception to be passed to the software performing the change. If this was a Channel Access client the result is to generate an exception callback.

To switch to a different device support layer, it is necessary to change the DTYP field before the INP or OUT field. The change to the DTYP field has no effect until the latter field change takes place.

If a record is set to I/O Interrupt scan but the new layer does not support this, the scan will be changed to Passive.

12.5.2 Initialization/Registration

Device support that implements the extended behaviour must provide an `init` routine in the Device Support Entry Table (see Section 12.4.2 on page 187). In the first call to this routine (pass 0) it registers the address of its Device Support eXtension Table (DSXT) in a call to `devExtend`.

The only exception to this registration requirement is when the device support uses a link type of CONSTANT. In this circumstance the system will automatically register an empty DSXT for that particular support layer (both the `add_record` and `del_record` routines pointed to by this DSXT do nothing and return zero). This exception allows existing soft channel device support layers to continue to work without requiring any modification, since the iocCore software already takes care of changes to PV_LINK addresses.

The following is an example of a DSXT and the initialization routine that registers it:

```
static struct dsxt myDsxt = {
    add_record, del_record
};

static long init(int pass) {
    if (pass==0) devExtend(&myDsxt);
    return 0;
}
```

A call to `devExtend` can only be made during the first pass of the device support initialization process, and registers the DSXT for that device support layer; if called at any other time it will log an error message and immediately return.

12.5.3 Device Support eXtension Table

The full definition of `struct dsxt` is found in devSup.h and currently looks like this:

```
typedef struct dsxt {
    long (*add_record)(struct dbCommon *precord);
    long (*del_record)(struct dbCommon *precord);
} dsxt;
```

There may be future additions to this table to support additional functionality; such extensions may only be made by changing the devSup.h header file and rebuilding EPICS Base and all support modules, thus neither record types nor device support are permitted to make any private use of this table.

The two function pointers are the means by which the extended device support is notified about the record instances it is being given or that are being moved away from its control. In both cases the only parameter is a pointer to the record concerned, which the code will have to cast to the appropriate pointer for the record type. The return value from the routines should be zero for success, or an EPICS error status code.

12.5.4 Add Record Routine

```
long add_record(
   struct dbCommon *precord);
```

This function is called to offer a new record to the device support. It is also called during iocInit, in between the pass 0 and pass 1 calls to the regular device support `init_record` routine (described in Section 12.4.3 on page 187 above). When converting an existing device support layer, this routine will usually be very similar to the old `init_record` routine, although in some cases it may be necessary to do a little more work depending on the particular record type involved. The extra code required in these cases can generally be copied straight from the record type implementation itself. This is necessary because the record type has no knowledge of the address change that is taking place, so the device support must perform any bitmask generation and/or readback value conversions itself. This document does not attempt to describe all the necessary processing for the various different standard record types, although the following (incomplete) list is presented as an aid to device support authors:

- mbbi/mbbo record types: Set SHFT, convert NOBT and SHFT into MASK
- bi/bo record types: Set SHFT, convert SHFT to MASK
- analog record types: Calculate ESLO and EOFF
- Output record types: Possibly read the current value from hardware and back-convert to VAL, or send the current record output value to the hardware. *This behaviour is not required or defined, and it's not obvious what should be done. There may be complications here with ao records using OROC and/or OIF=Incremental; solutions to this issue have yet to be considered by the community.*

If the `add_record` routine discovers any errors, say in the link address, it should return a non-zero error status value to reject the record. This will cause the record's PACT field to be set, preventing any further processing of this record until some other address change to it gets accepted.

12.5.5 Delete Record Routine

```
long del_record(
   struct dbCommon *precord);
```

This function is called to notify the device support of a request to change the hardware address of a record, and allow the device support to free up any resources it may have dedicated to this particular record.

Before this routine is called, the record will have had its SCAN field changed to Passive if it had been set to I/O Interrupt. This ensures that the device support's `get_ioint_info` routine is never called after the the call to `del_record` has returned successfully, although it may also lead to the possibility of missed interrupts if the address change is rejected by the `del_record` routine.

If the device support is unable to disconnect from the hardware for some reason, this routine should return a non-zero error status value, which will prevent the hardware address from being changed. In this event the SCAN field will be restored if it was originally set to I/O Interrupt.

After a successfull call to `del_record`, the record's DPVT field is set to NULL and PACT is cleared, ready for use by the new device support.

12.5.6 Init Record Routine

The `init_record` routine from the DSET (Section 12.4.3 on page 187) is called by the record type, and must still be provided since the record type's per-record initialization is run some time *after* the initial call to the DSXT's `add_record` routine. Most record types perform some initialization of record fields at this point, and an extended device support layer may have to fix anything that the record overwrites. The following (incomplete) list is presented as an aid to device support authors:

- mbbi/mbbo record types: Calculate MASK from SHFT
- analog record types: Calculate ESLO and EOFF
- Output record types: Perform readback of the initial raw value from the hardware.

Chapter 13: Driver Support

13.1 Overview

It is not necessary to create a driver support module in order to interface EPICS to hardware. For simple hardware device support is sufficient. At the present time most hardware support has both. The reason for this is historical. Before EPICS there was GTACS. During the change from GTACS to EPICS, record support was changed drastically. In order to preserve all existing hardware support the GTACS drivers were used without change. The device support layer was created just to shield the existing drivers form the record support changes.

Since EPICS now has both device and driver support the question arises: When do I need driver support and when don't I? Lets give a few reasons why drivers should be created.

- The hardware is actually a subnet, e.g. GPIB. In this case a driver should be provided for accessing the subnet. There is no reason to make the driver aware of EPICS except possibly for issuing error messages.
- The hardware is complicated. In this case supplying driver support helps modularized the software. The Allen Bradley driver, which is also an example of supporting a subnet, is a good example.
- An existing driver, maintained by others, is available. I don't know of any examples.
- The driver should be general purpose, i.e. not tied to EPICS. The CAMAC driver is a good example. It is used by other systems, such as CODA. This is perhaps the most important reason for driver support.
- For common devices, e.g. GPIB, CAN, CAMAC, etc. a generic driver layer should be created. This generic layer should be independent of EPICS and independent of low level interfaces. It should also define an inteface for low level drivers. This allows low level interfaces to be replaced without impacting IOC records, record support, or device support.

The only thing needed to interface a driver to EPICS is to provide a driver support module, which can be layered on top of an existing driver, and provide a database definition for the driver. The driver support module is described in the next section. The database definition is described in chapter "Database Definition".

13.2 Device Drivers

Device drivers are modules that interface directly with the hardware. They are provided to isolate device support routines from details of how to interface to the hardware. Device drivers have no knowledge of the internals of database records. Thus there is no necessary correspondence between record types and device drivers. For example the Allen Bradley driver provides support for many different types of signals including analog inputs, analog outputs, binary inputs, and binary outputs.

In general only device support routines know how to call device drivers. Since device support varies widely from device to device, the set of routines provided by a device driver is almost completely driver dependent. The only requirement is that routines `report` and `init` must be provided. Device support routines must, of course, know what routines are provided by a driver.

File `drvSup.h` describes the format of a driver support entry table. The driver support module must supply a driver entry table. An example definition is:

```
LOCAL long report();
LOCAL long init();
struct {
     long    number;
     DRVSUPFUN       report;
     DRVSUPFUN       init;
} drvAb={
     2,
     report,
     init
};
epicsExportAddress(drvet,drvGpib);
```

The above example is for the Allen Bradley driver. It has an associated ascii definition of:

```
driver(drvGpib)
```

Thus it is seen that the driver support module should supply two EPICS callable routines: `int` and `report`.

13.2.0.1 init

This routine, which has no arguments, is called by `iocInit`. The driver is expected to look for and initialize the hardware it supports. As an example the init routine for Allen Bradley is:

```
LOCAL long init()
{
 return(ab_driver_init());
}
```

13.2.0.2 report

The report routine is called by the `dbior`, an IOC test routine. It is responsible for producing a report describing the hardware it found at init time. It is passed one argument, level, which is a hint about how much information to display. An example, taken from Allen Bradley, is:

```
LOCAL long report(int level)
{
return(ab_io_report(level));
}
```

Guidelines for level are as follows:

Level=0	Display a one line summary for each device
Level=1	Display more information
Level=2	Display a lot of information. It is even permissible to prompt for what is wanted.

13.2.0.3 Hardware Configuration

Hardware configuration includes the following:

- VME/VXI address space
- VME Interrupt Vectors and levels
- Device Specific Information

The information contained in hardware links supplies some but not all configuration information. In particular it does not define the VME/VXI addresses and interrupt vectors. This additional information is what is meant by hardware configuration in this chapter.

The problem of defining hardware configuration information is an unsolved problem for EPICS. At one time configuration information was defined in `module_types.h` Many existing device/driver support modules still uses this method. It should **NOT** be used for any new support for the following reasons:

- There is no way to manage this file for the entire EPICS community.
- It does not allow arbitrary configuration information.
- It is hard for users to determine what the configuration information is.

The fact that it is now easy to include ASCII definitions for only the device/driver support used in each IOC makes the configuration problem much more manageable than previously. Previously if you wanted to support a new VME modules it was necessary to pick addresses that nothing in `module_types.h` was using. Now you only have to check modules you are actually using.

Since there are no EPICS defined rules for hardware configuration, the following minimal guidelines should be used:

- Never use `#define` to specify things like VME addresses. Instead use variables and assign default values. Allow the default values to be changed before iocInit is executed. The best way is to supply a global routine that can be invoked from the IOC startup file. Note that all arguments to such routines should be one of the following:
  ```
  int
  char *
  double
  ```
- Call the routines described in chapter “Device Support Library” whenever possible.

Chapter 14: Static Database Access

14.1 Overview

An IOC database is created on a Unix system via a Database Configuration Tool and stored in a Unix file. EPICS provides two sets of database access routines: Static Database Access and Runtime Database Access. Static database access can be used on Unix or IOC database files. Runtime database requires an initialized IOC databases. Static database access is described in this chapter and runtime database access in the next chapter.

Static database access provides a simplified interface to a database, i.e. much of the complexity is hidden. `DBF_MENU` and `DBF_DEVICE` fields are accessed via a common type called `DCT_MENU`. A set of routines are provided to simplify access to link fields. All fields can be accessed as character strings. This interface is called static database access because it can be used to access an uninitialized as well as an initialized database.

Before accessing database records, the files describing menus, record types, and devices must be read via `dbReadDatabase` or `dbReadDatabaseFP`. These routines, which are also used to load record instances, can be called multiple times.

Database Configuration Tools (DCTs) should manipulate an EPICS database only via the static database access interface. An IOC database is created on a host system via a database configuration tool and stored in a host file with a file extension of ".db". Three routines (`dbReadDatabase, dbReadDatabaseFP` and `dbWriteRecord`) access the host database file. These routines read/write a database file to/from a memory resident EPICS database. All other access routines manipulate the memory resident database.

An include file `dbStaticLib.h` contains all the definitions needed to use the static database access library. Two structures (`DBBASE` and `DBENTRY`) are used to access a database. The fields in these structures should not be accessed directly. They are used by the static database access library to keep state information for the caller.

14.2 Definitions

14.2.1 DBBASE

Multiple memory resident databases can be accessed simultaneously. The user must provide definitions in the form:

```
DBBASE *pdbbase;
```

NOTE: On an IOC pdbbase is a global variable, which is accessable if you include dbAccess.h

14.2.2 DBENTRY

A typical declaration for a database entry structure is:

```
DBENTRY *pdbentry;
pdbentry=dbAllocEntry(pdbbase);
```

Most static access to a database is via a DBENTRY structure. As many DBENTRYs as desired can be allocated.

The user should NEVER access the fields of DBENTRY directly. They are meant to be used by the static database access library.

Most static access routines accept an argument which contains the address of a DBENTRY. Each routine uses this structure to locate the information it needs and gives values to as many fields in this structure as possible. All other fields are set to NULL.

14.2.3 Field Types

Each database field has a type as defined in the next chapter. For static database access a new and simpler set of field types are defined. In addition, at runtime, a database field can be an array. With static database access, however, all fields are scalars. Static database access field types are called DCT field types.

The DCT field types are:

- **DCT_STRING**: Character string.
- **DCT_INTEGER**: Integer value
- **DCT_REAL**: Floating point number
- **DCT_MENU**: A set of choice strings
- **DCT_MENUFORM**: A set of choice strings with associated form.
- **DCT_INLINK**: Input Link
- **DCT_OUTLINK**: Output Link
- **DCT_FWDLINK**: Forward Link
- **DCT_NOACCESS**: A private field for use by record access routines

A DCT_STRING field contains the address of a NULL terminated string. The field types DCT_INTEGER and DCT_REAL are used for numeric fields. A field that has any of these types can be accessed via the dbGetString, dbPutString, dbVerify, and dbGetRange routines.

The field type DCT_MENU has an associated set of strings defining the choices. Routines are available for accessing menu fields. A menu field can also be accessed via the dbGetString, dbPutString, dbVerify, and dbGetRange routines.

The field type DCT_MENUFORM is like DCT_MENU but in addition the field has an associated link field. The information for the link field can be entered via a set of form manipulation fields.

DCT_INLINK (input), DCT_OUTLINK (output), and DCT_FWDLINK (forward) specify that the field is a link, which has an associated set of static access routines described in the next subsection. A field that has any of these types can also be accessed via the dbGetString, dbPutString, dbVerify, and dbGetRange routines.

14.3 Allocating and Freeing DBBASE

14.3.1 dbAllocBase

```
DBBASE *dbAllocBase(void);
```

This routine allocates and initializes a DBBASE structure. It does not return if it is unable to allocate storage.

`dbAllocBase` allocates and initializes a DBBASE structure. Normally an application does not need to call `dbAllocBase` because a call to `dbReadDatabase` or `dbReadDatabaseFP` automatically calls this routine if `pdbbase` is null. Thus the user only has to supply code like the following:

```
DBBASE  *pdbbase=0;
...
status = dbReadDatabase(&pdbbase,"sample.db",
      "<path>","<macro substitutions>");
```

The static database access library allows applications to work with multiple databases, each referenced via a different (DBBASE *) pointer. Such applications may find it necessary to call `dbAllocBase` directly.

`dbAllocBase` does not return if it is unable to allocate storage.

14.3.2 dbFreeBase

```
void dbFreeBase(DBBASE *pdbbase);
```

`dbFreeBase` frees the entire database reference by `pdbbase` including the DBBASE structure itself.

14.4 DBENTRY Routines

14.4.1 Alloc/Free DBENTRY

```
DBENTRY *dbAllocEntry(DBBASE *pdbbase);
void dbFreeEntry(DBENTRY *pdbentry);
```

These routines allocate, initialize, and free `DBENTRY` structures. The user can allocate and free `DBENTRY` structures as necessary. Each `DBENTRY` is, however, tied to a particular database.

`dbAllocEntry` and `dbFreeEntry` act as a pair, i.e. the user calls `dbAllocEntry` to create a new DBENTRY and calls `dbFreeEntry` when done.

14.4.2 dbInitEntry dbFinishEntry

```
void dbInitEntry(DBBASE *pdbbase,DBENTRY *pdbentry);
void dbFinishEntry(DBENTRY *pdbentry);
```

The routines `dbInitEntry` and `dbFinishEntry` are provided in case the user wants to allocate a `DBENTRY` structure on the stack. Note that the caller MUST call `dbFinishEntry` before returning from the routine that calls `dbInitEntry`. An example of how to use these routines is:

```
int xxx(DBBASE *pdbbase)
{
   DBENTRY dbentry;
   DBENTRY *pdbentry = &dbentry;
   ...
   dbInitEntry(pdbbase,pdbentry);
   ...
   dbFinishEntry(pdbentry);
}
```

14.4.3 dbCopyEntry
dbCopyEntry
Contents

```
DBENTRY *dbCopyEntry(DBENTRY *pdbentry);
void dbCopyEntryContents(DBENTRY *pfrom,DBENTRY *pto);
```

The routine `dbCopyEntry` allocates a new entry, via a call to `dbAllocEntry`, copies the information from the original entry, and returns the result. The caller must free the entry, via `dbFreeEntry` when finished with the DBENTRY.

The routine `dbCopyEntryContents` copies the contents of pfrom to pto. Code should never perform structure copies.

14.5 Read and Write Database

14.5.1 Read Database File

```
long dbReadDatabase(DBBASE **ppdbbase,const char *filename,
      char *path, char *substitutions);
long dbReadDatabaseFP(DBBASE **ppdbbase,FILE *fp,
      char *path, char *substitutions);
long dbPath(DBBASE *pdbbase,const char *path);
long dbAddPath(DBBASE *pdbbase,const char *path);
```

`dbReadDatabase` and `dbReadDatabaseFP` both read a file containing database definitions as described in chapter “Database Definitions”. If `*ppdbbase` is NULL, `dbAllocBase` is automatically invoked and the return address assigned to `*pdbbase`. The only difference between the two routines is that one accepts a file name and the other a "FILE *". Any combination of these routines can be called multiple times. Each adds definitions with the rules described in chapter “Database Definitions”.

The routines `dbPath` and `dbAddPath` specify paths for use by include statements in database definition files. These are not normally called by user code.

14.5.2 Write Database Definitons

```
long dbWriteMenu(DBBASE *pdbbase,char *filename,char *menuName);
long dbWriteMenuFP(DBBASE *pdbbase,FILE *fp,char *menuName);
long dbWriteRecordType(DBBASE *pdbbase,char *filename,char *recordTypeName);
long dbWriteRecordTypeFP(DBBASE *pdbbase,FILE *fp,char *recordTypeName);
long dbWriteDevice(DBBASE *pdbbase,char *filename);
long dbWriteDeviceFP(DBBASE *pdbbase,FILE *fp);
long dbWriteDriver(DBBASE *pdbbase,char *filename);
long dbWriteDriverFP(DBBASE *pdbbase,FILE *fp);
long dbWriteRegistrarFP(DBBASE *pdbbase,FILE *fp);
long dbWriteFunctionFP(DBBASE *pdbbase,FILE *fp);
long dbWriteVariableFP(DBBASE *pdbbase,FILE *fp);
long dbWriteBreaktable(DBBASE *pdbbase,const char *filename);
long dbWriteBreaktableFP(DBBASE *pdbbase,FILE *fp);
```

Each of these routines writes files in the same format accepted by `dbReadDatabase` and `dbReadDatabaseFP`. Two versions of each type are provided. The only difference is that one accepts a filename and the other a "`FILE *`". Thus only one of each type has to be described.

`dbWriteMenu` writes the description of the specified menu or, if `menuName` is NULL, the descriptions of all menus.

`dbWriteRecordType` writes the description of the specified record type or, if `recordTypeName` is NULL, the descriptions of all record types.

`dbWriteDevice` writes the description of all devices to stdout.

`dbWriteDriver` writes the description of all drivers to stdout.

`dbWriteRegistrarFP` writes the list of all registrars to the given open file (no filename version is provided).

`dbWriteFunctionFP` writes the list of all functions to the given open file (no filename version is provided).

`dbWriteVariableFP` writes the list of all variables to the given open file (no filename version is provided).

14.5.3 Write Record Instances

```
long dbWriteRecord(DBBASE *pdbbase,char * file,
   char *precordTypeName,int level);
long dbWriteRecordFP(DBBASE *pdbbase,FILE *fp,
   char *precordTypeName,int level);
```

Each of these routines writes files in the same format accepted by `dbReadDatabase` and `dbReadDatabaseFP`. Two versions of each type are provided. The only difference is that one accepts a filename and the other a “`FILE *`”. Thus only one of each type has to be described.

`dbWriteRecord` writes record instances. If `precordTypeName` is NULL, then the record instances for all record types are written, otherwise only the records for the specified type are written. `level` has the following meaning:

- 0 - Write only prompt fields that are different than the default value.
- 1 - Write only the fields which are prompt fields.
- 2 - Write the values of all fields.

14.6 Manipulating Record Types

14.6.1 Get Number of Record Types

```
int  dbGetNRecordTypes(DBENTRY *pdbentry);
```

This routine returns the number of record types in the database.

14.6.2 Locate Record Type

```
long dbFindRecordType(DBENTRY *pdbentry,
   char *recordTypeName);
long dbFirstRecordType(DBENTRY *pdbentry);
long dbNextRecordType(DBENTRY *pdbentry);
```

`dbFindRecordType` locates a particular record type. `dbFirstRecordType` locates the first, in alphabetical order, record type. Given that DBENTRY points to a particular record type, `dbNextRecordType` locates the next record type. Each routine returns 0 for success and a non zero status value for failure. A typical code segment using these routines is:

```
status = dbFirstRecordType(pdbentry);
while(!status) {
   /*Do something*/
status = dbNextRecordType(pdbentry)
}
```

14.6.3 Get Record Type Name

```
char *dbGetRecordTypeName(DBENTRY *pdbentry);
```

This routine returns the name of the record type that DBENTRY currently references. This routine should only be called after a successful call to `dbFindRecordType`, `dbFirstRecordType`, or `dbNextRecordType`. It returns NULL if DBENTRY does not point to a record description.

14.7 Manipulating Field Descriptions

The routines described in this section all assume that DBENTRY references a record type, i.e. that `dbFindRecordType`, `dbFirstRecordType`, or `dbNextRecordType` has returned success or that a record instance has been successfully located.

14.7.1 Get Number of Fields

```
int  dbGetNFields(DBENTRY *pdbentry,int dctonly);
```

Returns the number of fields for the record instance that DBENTRY currently references.

14.7.2 Locate Field

```
long dbFirstField(DBENTRY *pdbentry,int dctonly);
long dbNextField(DBENTRY *pdbentry,int dctonly);
```

These routines are used to locate fields. If any of these routines returns success, then DBENTRY references that field description.

14.7.3 Get Field Type

```
int  dbGetFieldType(DBENTRY *pdbentry);
```

This routine returns the integer value for a DCT field type, see Section 14.2.3 on page 196, for a description of the field types.

14.7.4 Get Field Name

```
char *dbGetFieldName(DBENTRY *pdbentry);
```

This routine returns the name of the field that DBENTRY currently references. It returns NULL if DBENTRY does not point to a field.

14.7.5 Get Default Value

```
char *dbGetDefault(DBENTRY *pdbentry);
```

This routine returns the default value for the field that DBENTRY currently references. It returns NULL if DBENTRY does not point to a field or if the default value is NULL.

14.7.6 Get Field Prompt

```
char *dbGetPrompt(DBENTRY *pdbentry);
int   dbGetPromptGroup(DBENTRY *pdbentry);
```

The `dbGetPrompt` routine returns the character string prompt value, which describes the field. `dbGetPromptGroup` returns the field group as described in guigroup.h.

14.8 Manipulating Record Attributes

A record attribute is a "psuedo" field definition attached to a record type. If a attribute value is assigned to a psuedo field name then all record instances of that record type appear to have that field with the defined value. All attribute fields are DCT_STRING fields.

Two field attributes are automatically created: RTYP and VERS. RTYP is set equal to ,the record type name. VERS is initialized to the value "none specified" but can be changed by record support.

14.8.1 dbPutRecord Attribute

```
long dbPutRecordAttribute(DBENTRY *pdbentry,
    char *name,char*value)
```

This creates or modifies attribute `name` with `value`.

14.8.2 dbGetRecord Attribute

```
long dbGetRecordAttribute(DBENTRY *pdbentry,char *name);
```

14.9 Manipulating Record Instances

With the exception of dbFindRecord, each of the routines described in this section require that DBENTRY references a valid record type, i.e. that `dbFindRecordType`, `dbFirstRecordType`, or `dbNextRecordType` has been called and returned success.

14.9.1 Get Number of Records

```
int  dbGetNRecords(DBENTRY *pdbentry);
```

Returns the number of record instances for the record type that DBENTRY currently references.

14.9.2 Locate Record

```
long dbFindRecord(DBENTRY *pdbentry,char *precordName);
long dbFirstRecord(DBENTRY *pdbentry);
long dbNextRecord(DBENTRY *pdbentry);
```

These routines are used to locate record instances. If any of these routines returns success, then DBENTRY references the record. `dbFindRecord` can be called without DBENTRY referencing a valid record type. `dbFirstRecord` only works if DBENTRY references a record type. The `dbDumpRecords` example given at the beginning of this chapter shows how these routines can be used.

`dbFindRecord` also calls `dbFindField` if the record name includes a field name, i.e. it ends in ".XXX". The routine `dbFoundField` returns (`TRUE`, `FALSE`) if the field (was, was not) found. If it was not found, then `dbFindField` must be called before individual fields can be used.

14.9.3 Get Record Name

```
char *dbGetRecordName(DBENTRY *pdbentry);
```

This routine only works properly if called after `dbFindRecord`, `dbFirstRecord`, or `dbNextRecord` has returned success.

14.9.4 Create/Delete/Free Record

```
long dbCreateRecord(DBENTRY *pdbentry,char *precordName);
long dbDeleteRecord(DBENTRY *pdbentry);
long dbFreeRecords(DBBASE *pdbbase);
```

`dbCreateRecord`, which assumes that `DBENTRY` references a valid record type, creates a new record instance and initializes it as specified by the record description. If it returns success, then `DBENTRY` references the record just created. `dbDeleteRecord` deletes a single record instance/. `dbFreeRecords` deletes all record instances.

14.9.5 Copy Record

```
long dbCopyRecord(DBENTRY *pdbentry, char *newRecordName
   int overWriteOK)
```

This routine copies the record instance currently referenced by DBENTRY. Thus it creates and new record with the name newRecordName that is of the same type as the original record and copies the original records field values to the new record. If newRecordName already exists and overWriteOK is true, then the original newRecordName is deleted and recreated. If dbCopyRecord completes successfully, DBENTRY references the new record.

14.9.6 Rename Record

```
long dbRenameRecord(DBENTRY *pdbentry, char *newname)
```

This routine renames the record instance currently referenced by DBENTRY. If dbRenameRecord completes successfully, DBENTRY references the renamed record.

14.9.7 Record Visibility

These routines are for use by graphical configuration tools.

```
long dbVisibleRecord(DBENTRY *pdbentry);
long dbInvisibleRecord(DBENTRY *pdbentry);
int dbIsVisibleRecord(DBENTRY *pdbentry);
```

dbVisibleRecord sets a record to be visible. dbInvisibleRecord sets a record invisible. dbIsVisibleRecord returns TRUE if a record is visible and FALSE otherwise.

14.9.8 Find Field

```
long dbFindField(DBENTRY *pdbentry,char *pfieldName);
int dbFoundField(DBENTRY *pdbentry);
```

Given that a record instance has been located, dbFindField finds the specified field. If it returns success, then DBENTRY references that field. dbFoundField returns (FALSE, TRUE) if (no field instance is currently available, a field instance is available).

14.9.9 Get/Put Field Values

```
char *dbGetString(DBENTRY *pdbentry);
long dbPutString(DBENTRY *pdbentry,char *pstring);
char *dbVerify(DBENTRY *pdbentry,char *pstring);
char *dbGetRange(DBENTRY *pdbentry);
int   dbIsDefaultValue(DBENTRY *pdbentry);
```

These routines are used to get or change field values. They work on all the database field types except DCT_NOACCESS but should **NOT** be used to prompt the user for information for DCT_MENU, DCT_MENUFORM, or DCT_LINK_xxx fields. dbVerify returns (NULL, a message) if the string is (valid, invalid). Please note that the strings returned are volatile, i.e. the next call to a routines that returns a string will overwrite the value returned by a previous call. Thus it is the caller's responsibility to copy the strings if the value must be kept.

DCT_MENU, DCT_MENUFORM and DCT_LINK_xxx fields can be manipulated via routines described in the following sections. If, however dbGetString and dbPutString are used, they do work correctly. For these field types dbGetString and dbPutString are intended to be used only for creating and restoring versions of a database.

14.10 Manipulating Menu Fields

These routines should only be used for `DCT_MENU` and `DCT_MENUFORM` fields. Thus they should only be called if `dbFindField`, `dbFirstField`, or `dbNextField` has returned success and the field type is `DCT_MENU` or `DCT_MENUFORM`.

14.10.1 Get Number of Menu Choices

```
int  dbGetNMenuChoices(DBENTRY *pdbentry);
```

This routine returns the number of menu choices for menu.

14.10.2 Get Menu Choice

```
char **dbGetMenuChoices(DBENTRY *pdbentry);
```

This routine returns the address of an array of pointers to strings which contain the menu choices.

14.10.3 Get/Put Menu

```
int  dbGetMenuIndex(DBENTRY *pdbentry);
long dbPutMenuIndex(DBENTRY *pdbentry,int index);
char *dbGetMenuStringFromIndex(DBENTRY *pdbentry,int index);
int dbGetMenuIndexFromString(DBENTRY *pdbentry,
      char *choice);
```

NOTE: These routines do not work if the current field value contains a macro definition.

`dbGetMenuIndex` returns the index of the menu choice for the current field, i.e. it specifies which choice to which the field is currently set. `dbPutMenuIndex` sets the field to the choice specified by the index.

`dbGetMenuStringFromIndex` returns the string value for a menu index. If the index value is invalid NULL is returned. `dbGetMenuIndexFromString` returns the index for the given string. If the string is not a valid choice a -1 is returned.

14.10.4 Locate Menu

```
dbMenu *dbFindMenu(DBBASE *pdbbase,char *name);
```

`dbFindMenu` is most useful for runtime use but is a static database access routine. This routine just finds a menu with the given name.

14.11 Manipulating Link Fields

14.11.1 Link Types

Links are the most complicated types of fields. A link can be a constant, reference a field in another record, or can refer to a hardware device. Two additional complications arise for hardware links. The first is that field DTYP, which is a menu field, determines if the INP or OUT field is a device link. The second is that the information that must be specified for a device link is bus dependent. In order to shelter database configuration tools from these complications the following is done for static database access.

- Static database access will treat DTYP as a DCT_MENUFORM field.
- The information for the link field related to the DCT_MENUFORM can be entered via a set of form manipulation routines associated with the DCT_MENUFORM field. Thus the link information can be entered via the DTYP field rather than the link field.
- The Form routines described in the next section can also be used with any link field.

Each link is one of the following types:

- **DCT_LINK_CONSTANT**: Constant value.
- **DCT_LINK_PV**: A process variable link.
- **DCT_LINK_FORM**: A link that can only be processed via the form routines described in the next chapter.

Database configuration tools can change any link between being a constant and a process variable link. Routines are provided to accomplish these tasks.

The routines dbGetString, dbPutString, and dbVerify can be used for link fields but the form routines can be used to provide a friendlier user interface.

14.11.2 All Link Fields

```
int  dbGetNLinks(DBENTRY *pdbentry);
long dbGetLinkField(DBENTRY *pdbentry,int index)
int  dbGetLinkType(DBENTRY *pdbentry);
```

These are routines for manipulating DCT_xxxLINK fields. dbGetNLinks and dbGetLinkField are used to walk through all the link fields of a record. dbGetLinkType returns one of the values: DCT_LINK_CONSTANT, DCT_LINK_PV, DCT_LINK_FORM, or the value -1 if it is called for an illegal field.

14.11.3 Constant and Process Variable Links

```
long dbCvtLinkToConstant(DBENTRY *pdbentry);
long dbCvtLinkToPvlink(DBENTRY *pdbentry);
```

These routines should be used for modifying DCT_LINK_CONSTANT or DCT_LINK_PV links. They should not be used for DCT_LINK_FORM links, which should be processed via the associated DCT_MENUFORM field described above.

14.12 Manipulating MenuForm Fields

These routines are used with a DCT_MENUFORM field (a DTYP field) to manipulate the associated DCT_INLINK or DCT_OUTLINK field. They can also be used on any DCT_INLINK, DCT_OUTLINK, or DCT_FWDLINK field.

14.12.1 Alloc/Free Form

```
int dbAllocForm(DBENTRY *pdbentry)
long dbFreeForm(DBENTRY *pdbentry)
```

`dbAllocForm` allocates storage needed to manipulate forms. The return value is the number of elements in the form. If the current field value contains a macro definition, the number of lines returned is 0.

14.12.2 Get/Put Form

```
char **dbGetFormPrompt(DBENTRY *pdbentry)
char **dbGetFormValue(DBENTRY *pdbentry)
long dbPutForm(DBENTRY *pdbentry, char **value)
```

`dbGetFormPrompt` returns a pointer to an array of pointers to character strings specifying the prompt string. `dbGetFormValue` returns the current values. `dbPutForm`, which can use the same array of values returned by `dbGetForm`, sets new values.

14.12.3 Verify Form

```
char **dbVerifyForm(DBENTRY *pdbentry,char **value)
```

`dbVerifyForm` can be called to verify user input. It returns `NULL` if no errors are present. If errors are present, it returns a pointer to an array of character strings containing error messages. Lines in error have a message and correct lines have a `NULL` string.

14.12.4 Get Related Field

```
char *dbGetRelatedField(DBENTRY *pdbentry)
```

This routine returns the field name of the related field for a DCT_MENUFORM field. If it is called for any other type of field it returns NULL.

14.12.5 Example

The following is code showing use of these routines:

```
char  **value;
char  **prompt;
char  **error;
int  n;

...
n = dbAllocForm(pdbentry);
if(n<=0) {<Error>}
prompt = dbGetFormPrompt(pdbentry);
value = dbGetFormValue(pdbentry);
for(i=0; i<n; i++) {
   printf(”%s (%s) : \n”,prompt[i],value[i]);
   /*The follwing accepts input from stdin*/
   scanf(”%s”,value[i]);
}
error = dbVerifyForm(pdbentry,value);
```

```
if(error) {
   for(i=0; i<n; i++) {
      if(error[i]) printf("Error: %s (%s) %s\n", prompt[i],
         value[i],error[i]);
   }
}else {
   dbPutForm(pdbentry,value)
}
dbFreeForm(pdbentry);
```

All value strings are `MAX_STRING_SIZE` in length.

A set of form calls for a particular `DBENTRY`, **MUST** begin with a call to `dbAllocForm` and end with a call to `dbFreeForm`. The values returned by `dbGetFormPrompt`, `dbGetFormValue`, and `dbVerifyForm` are valid only between the calls to `dbAllocForm` and `dbFreeForm`.

14.13 Manipulating Information Items

Information items are stored as a list attached to each individual record instance. All routines listed in this section require that the DBENTRY argument refer to a valid record instance.

14.13.1 Locate Item

```
long dbFirstInfo(DBENTRY *pdbentry);
long dbNextInfo(DBENTRY *pdbentry);
long dbFindInfo(DBENTRY *pdbentry,const char *name);
```

There are two ways to locate info items, by scanning through the list using first/next, or by asking for the item by name. These routines set `pdbentry` to refer to the info item and return 0, or return an error code if no info item is found.

14.13.2 Get Item Name

```
const char * dbGetInfoName(DBENTRY *pdbentry);
```

Returns the name of the info item referred to by `pdbentry`, or a NULL pointer if no item is referred to.

14.13.3 Get/Set Item String Value

```
const char * dbGetInfoString(DBENTRY *pdbentry);
long dbPutInfoString(DBENTRY *pdbentry,const char *string);
```

These routines provide access to the currently selected items' string value. When changing the string value using `dbPutInfoSting`, the character string provided will be copied, with additional memory being allocated as necessary. Users are advised not to make continuously repeated calls to `dbPutInfoString` at IOC runtime as this could fragment the free memory heap. The Put routine returns 0 if Ok or an error code; the Get routine returns NULL on error.

14.13.4 Get/Set Item Pointer Value

```
void * dbGetInfoPointer(DBENTRY *pdbentry);
long dbPutInfoPointer(DBENTRY *pdbentry, void *pointer);
```

Each info item includes space to store a single `void*` pointer as well as the value string. Applications using the info item may set this as often as they wish. The Put routine returns 0 if Ok or an error code; the Get routine returns NULL on error.

14.13.5 Create/Delete Item

```
long dbPutInfo(DBENTRY *pdbentry,const char *name,const char *string);
long dbDeleteInfo(DBENTRY *pdbentry);
```

A new info item can be created by calling `dbPutInfo`. If an item by that name already exists its value will be replaced with the new string, otherwise storage is allocated and the name and value strings copied into it. The function returns 0 on success, or an error code.

When calling `dbDeleteInfo`, the pdbentry must refer to the item to be removed (using `dbFindFirst`/`dbFindNext` or `dbFindInfo`). The function returns 0 on success, or an error code.

14.13.6 Convenience Routine

```
const char * dbGetInfo(DBENTRY *pdbentry,const char *name);
```

It is common to want to look up the value of a named info item in one call, and `dbGetInfo` is provided for this purpose. It returns a NULL pointer if no info item exists with the given name.

14.14 Find Breakpoint Table

```
brkTable *dbFindBrkTable(DBBASE *pdbbase,char *name)
```

This routine returns the address of the specified breakpoint table. It is normally used by the runtime breakpoint conversion routines so will not be discussed further.

14.15 Dump Routines

```
void dbDumpPath(DBBASE *pdbbase)
void dbDumpRecord(DBBASE *pdbbase,char *precordTypeName,int level);
void dbDumpMenu(DBBASE *pdbbase,char *menuName);
void dbDumpRecordType(DBBASE *pdbbase,char *recordTypeName);
void dbDumpField(DBBASE *pdbbase,char *recordTypeName,char *fname);
void dbDumpDevice(DBBASE *pdbbase,char *recordTypeName);
void dbDumpDriver(DBBASE *pdbbase);
void dbDumpRegistrar(DBBASE *pdbbase);
void dbDumpFunction(DBBASE *pdbbase);
void dbDumpVariable(DBBASE *pdbbase);
void dbDumpBreaktable(DBBASE *pdbbase,char *name);
void dbPvdDump(DBBASE *pdbbase,int verbose);
void dbReportDeviceConfig(DBBASE *pdbbase,FILE *report);
```

These routines are used to dump information about the database. `dbDumpRecord`, `dbDumpMenu`, `dbDumpDriver`, `dbDumpRegistrar` and `dbDumpVariable` just call the corresponding dbWritexxxFP routine specifying stdout for the file. `dbDumpRecordType`, `dbDumpField`, and `dbDumpDevice` give internal information useful on an ioc. These commands can be executed via iocsh. Just specify pdbbase as the first argument.

14.16 Examples

14.16.1 Expand Include

This example is like the `dbExpand` utility, except that it doesn't allow path or macro substitution options, It reads a set of database definition files and writes all definitions to stdout. All include statements appearing in the input files are expanded.

```
/* dbExpand.c */
#include <stdlib.h>
#include <stddef.h>
#include <stdio.h>
#include <epicsPrint.h>
#include <dbStaticLib.h>

DBBASE *pdbbase = NULL;


int main(int argc,char **argv)
{
   long     status;
   int      i;
   int      arg;

   if(argc<2) {
      printf("usage: expandInclude file1.db file2.db...\n");
      exit(0);
    }
   for(i=1; i<argc; i++) {
      status = dbReadDatabase(&pdbbase,argv[i],NULL,NULL);
      if(!status) continue;
      fprintf(stderr,"For input file %s",argv[i]);
      errMessage(status,"from dbReadDatabase");
   }
   dbWriteMenuFP(pdbbase,stdout,0);
   dbWriteRecordTypeFP(pdbbase,stdout,0);
   dbWriteDeviceFP(pdbbase.stdout);
   dbWriteDriverFP(pdbbase.stdout);
   dbWriteRecordFP(pdbbase,stdout,0,0);
   return(0);
}
```

14.16.2 dbDumpRecords

NOTE: This example is similar but not identical to the actual `dbDumpRecords` routine.

The following example demonstrates how to use the database access routines. The example shows how to locate each record and display each field.

```
void dbDumpRecords(DBBASE *pdbbase)
{
```

```
   DBENTRY  *pdbentry;
   long  status;

   pdbentry = dbAllocEntry(pdbbase);
   status = dbFirstRecordType(pdbentry);
   if(status) {printf("No record descriptions\n");return;}
   while(!status) {
      printf("record type: %s",dbGetRecordTypeName(pdbentry));
      status = dbFirstRecord(pdbentry);
      if(status) printf("  No Records\n");
      else printf("\n  Record:%s\n",dbGetRecordName(pdbentry));
      while(!status) {
         status = dbFirstField(pdbentry,TRUE);
         if(status) printf("    No Fields\n");
         while(!status) {
            printf("    %s:%s",dbGetFieldName(pdbentry),
               dbGetString(pdbentry));
            status=dbNextField(pdbentry,TRUE);
         }
         status = dbNextRecord(pdbentry);
      }
      status = dbNextRecordType(pdbentry);
   }
   printf("End of all Records\n");
   dbFreeEntry(pdbentry);
}
```

Chapter 15: Runtime Database Access

15.1 Overview

This chapter describes routines for manipulating and accessing an initialized IOC database.

This chapter is divided into the following sections:

- Database related include files. All of interest are listed and those of general interest are discussed briefly.
- Runtime database access overview.
- Description of each runtime database access routine.
- Runtime modification of link fields.
- Lock Set Routines
- Database to Channel Access Routines
- Old Database Access. This is the interface still used by Channel Access and thus by Channel Access clients.

15.2 Database Include Files

Directory `base/include` contains a number of database related include files. Of interest to this chapter are:

- **dbDefs.h**: Miscellaneous database related definitions
- **dbFldTypes.h**: Field type definitions
- **dbAccess.h**: Runtime database access definitions.
- **link.h**: Definitions for link fields.

15.2.1 dbDefs.h

This file contains a number of database related definitions. The most important are:

- **PVNAME_SZ**: The number of characters allowed in the record name.
- **MAX_STRING_SIZE**: The maximum string size for string fields or menu choices.
- **DB_MAX_CHOICES**: The maximum number of choices for a choice field.

15.2.2 dbFldTypes.h

This file defines the possible field types. A field's type is perhaps its most important attribute. Changing the possible field types is a fundamental change to the IOC software, because many IOC software components are aware of the field types.

The field types are:

- **DBF_STRING**: 40 character ASCII string
- **DBF_CHAR**: Signed character

- **DBF_UCHAR**: Unsigned character
- **DBF_SHORT**: Short integer
- **DBF_USHORT**: Unsigned short integer
- **DBF_LONG**: Long integer
- **DBF_ULONG**: Unsigned long integer
- **DBF_FLOAT**: Floating point number
- **DBF_DOUBLE**: Double precision float
- **DBF_ENUM**: An enumerated field
- **DBF_MENU**: A menu choice field
- **DBF_DEVICE**: A device choice field
- **DBF_INLINK**: Input Link
- **DBF_OUTLINK**: Output Link
- **DBF_FWDLINK**: Forward Link
- **DBF_NOACCESS**: A private field for use by record access routines

A field of type `DBF_STRING`, ..., `DBF_DOUBLE` can be a scalar or an array. A `DBF_STRING` field contains a `NULL` terminated ascii string. The field types `DBF_CHAR`, ..., `DBF_DOUBLE` correspond to the standard C data types.

`DBF_ENUM` is used for enumerated items, which is analogous to the C language enumeration. An example of an enum field is field `VAL` of a multi bit binary record.

The field types `DBF_ENUM`, `DBF_MENU`, and `DBF_DEVICE` all have an associated set of ASCII strings defining the choices. For a `DBF_ENUM`, the record support module supplies values and thus are not available for static database access. The database access routines locate the choice strings for the other types.

`DBF_INLINK` and `DBF_OUTLINK` specify link fields. A link field can refer to a signal located in a hardware module, to a field located in a database record in the same IOC, or to a field located in a record in another IOC. A `DBF_FWDLINK` can only refer to a record in the same IOC. Link fields are described in a later chapter.

`DBF_INLINK` (input), `DBF_OUTLINK` (output), and `DBF_FWDLINK` (forward) specify that the field is a link structure as defined in `link.h`. There are three classes of links:

1. Constant - The value associated with the field is a floating point value initialized with a constant value. This is somewhat of a misnomer because constant link fields can be modified via `dbPutField` or `dbPutLink`.
2. Hardware links - The link contains a data structure which describes a signal connected to a particular hardware bus. See `link.h` for a description of the bus types currently supported.
3. Process Variable Links - This is one of three types:
   a. PV_LINK: The process variable name.
   b. DB_LINK: A reference to a process variable in the same IOC.
   c. CA_LINK: A reference to a variable located in another IOC.

DCT always creates a `PV_LINK`. When the IOC is initialized each `PV_LINK` is converted either to a `DB_LINK` or a `CA_LINK`.

`DBF_NOACCESS` fields are for private use by record processing routines.

15.2.3 dbAccess.h

This file is the interface definition for the run time database access library, i.e. for the routines described in this chapter.

An important structure defined in this header file is `DBADDR`

```
typedef struct dbAddr{
   struct dbCommon *precord;/* address of record*/
```

```
   void     *pfield;    /* address of field*/
   void     *pfldDes;   /* address of struct fldDes*/
   void     *asPvt;     /* Access Security Private*/
   long     no_elements; /* number of elements (arrays)*/
   short    field_type; /* type of database field*/
   short    field_size; /* size (bytes) of the field*/
   short    special;    /* special processing*/
   short    dbr_field_type; /*optimal database request type*/
}DBADDR;
```

- **precord**: Address of record. Note that its type is a pointer to a structure defining the fields common to all record types. The common fields appear at the beginning of each record. A record support module can cast `precord` to point to the specific record type.
- **pfield**: Address of the field within the record. Note that `pfield` provides direct access to the data value.
- **pfldDes**: This points to a structure containing all details concerning the field. See Chapter "Database Structures" for details.
- **asPvt**: A field used by access security.
- **no_elements**: A string or numeric field can be either a scalar or an array. For scalar fields `no_elements` has the value 1. For array fields it is the maximum number of elements that can be stored in the array.
- **field_type**: Field type.
- **field_size**: Size of one element of the field.
- **special**: Some fields require special processing. This specifies the type. Special processing is described later in this manual.
- **dbr_field_type**: This specifies the optimal database request type for this field, i.e. the request type that will require the least CPU overhead.

NOTE: `pfield`, `no_elements`, `field_type`, `field_size`, `special`, and `dbr_field_type` can all be set by record support (`cvt_dbaddr`). Thus `field_type`, `field_size`, and `special` can differ from that specified by `pfldDes`.

15.2.4 link.h

This header file describes the various types of link fields supported by EPICS.

15.3 Runtime Database Access Overview

With the exception of record and device support, all access to the database is via the channel or database access routines. Even record support routines access other records only via database or channel access. Channel Access, in turn, accesses the database via database access.

Perhaps the easiest way to describe the database access layer is to list and briefly describe the set of routines that constitute database access. This provides a good look at the facilities provided by the database.

Before describing database access, one caution must be mentioned. The only way to communicate with an IOC database from outside the IOC is via Channel Access. In addition, any special purpose software, i.e. any software not described in this document, should communicate with the database via Channel Access, not database access, even if it resides in the same IOC as the database. Since Channel Access provides network independent access to a database, it must ultimately

call database access routines. The database access interface was changed in 1991, but Channel Access was never changed. Instead a module was written which translates old style database access calls to new. This interface between the old and new style database access calls is discussed in the last section of this chapter.

The database access routines are:

- **dbNameToAddr**: Locate a database variable.

- **dbGetField**: Get values associated with a database variable.
- **dbGetLink**: Get value of field referenced by database link (Macro)
- **dbGetLinkValue**: Get value of field referenced by database link (Subroutine)
- **dbGet**: Routine called by `dbGetLinkValue` and `dbGetField`

- **dbPutField**: Change the value of a database variable.
- **dbPutLink**: Change value referenced by database link (Macro)
- **dbPutLinkValue**: Change value referenced by database link (Subroutine)
- **dbPut**: Routine called by `dbPutxxx` functions.
-
- **putNotifyInit**: Initialize "struct putNotify"
- **putNotifyCleanup**: Cleanup "struct putNotify"
- **dbPutNotify**: A database put with notification on completion
- **dbNotifyCancel**: Cancel `dbPutNotify`
- **dbNotifyAdd**: Add a new record for to notify set.
- **dbNotifyCompletion**: Announce that put notify is complete.

- **dbBufferSize**: Determine number of bytes in request buffer.
- **dbValueSize**: Number of bytes for a value field.
- **dbGetRset**: Get pointer to Record Support Entry Table
- **dbIsValueField**: Is this field the VAL field.
- **dbGetFieldIndex**: Get field index. The first field in a record has index 0.
- **dbGetNelement:** Get number of elements in the field
- **dbIsLinkConnected**: Is the link field connected.
- **dbGetPdbAddrFromLink**: Get address of DBADDR.
- **dbGetLinkDBFtype**: Get field type of link.
- **dbGetControlLimits**: Get Control Limits.
- **dbGetGraphicLimits**: Get Graphic Limits.
- **dbGetAlarmLimits**: Get Alarm Limits
- **dbGetPrecision**: Get Precision
- **dbGetUnits**: Get Units
- **dbGetNelements**: Get Number of Elements
- **dbGetSevr**: Get Severity
- **dbGetTimeStamp**: Get Time Stamp

- **dbPutAttribute** Give a value to a record attribute.

- **dbScanPassive**: Process record if it is passive.
- **dbScanLink**: Process record referenced by link if it is passive.
- **dbProcess**: Process Record

- **dbScanFwdLink**: Scan a forward link.

15.3.1 Database Request Types and Options

Before describing database access structures, it is necessary to describe database request types and request options. When `dbPutField` or `dbGetField` are called one of the arguments is a database request type. This argument has one of the following values:

- **DBR_STRING**: Value is a `NULL` terminated string
- **DBR_CHAR**: Value is a signed char
- **DBR_UCHAR**: Value is an unsigned char
- **DBR_SHORT**: Value is a short integer
- **DBR_USHORT**: Value is an unsigned short integer
- **DBR_LONG**: Value is a long integer
- **DBR_ULONG**: Value is an unsigned long integer
- **DBR_FLOAT**: Value is an IEEE floating point value
- **DBR_DOUBLE**: Value is an IEEE double precision floating point value
- **DBR_ENUM**: Value is a short which is the enum item
- **DBR_PUT_ACKT**: Value is an unsigned short for setting the `ACKT`.
- **DBR_PUT_ACKS**: Value is an unsigned short for global alarm acknowledgment.

The request types `DBR_STRING`,..., `DBR_DOUBLE` correspond exactly to valid data types for database fields. `DBR_ENUM` corresponds to database fields that represent a set of choices or options. In particular it corresponds to the fields types `DBF_ENUM`, `DBF_DEVICE`, and `DBF_MENU`. The complete set of database field types are defined in `dbFldTypes.h`. `DBR_PUT_ACKT` and `DBR_PUT_ACKS` are used to perform global alarm acknowledgment.

`dbGetField` also accepts argument options which is a mask containing a bit for each additional type of information the caller desires. The complete set of options is:

- **DBR_STATUS**: returns the alarm status and severity
- **DBR_UNITS**: returns a string specifying the engineering units
- **DBR_PRECISION**: returns a long integer specifying floating point precision.
- **DBR_TIME**: returns the time
- **DBR_ENUM_STRS**: returns an array of strings
- **DBR_GR_LONG**: returns graphics info as long values
- **DBR_GR_DOUBLE**: returns graphics info as double values
- **DBR_CTRL_LONG**: returns control info as long values
- **DBR_CTRL_DOUBLE**: returns control info as double values
- **DBR_AL_LONG**: returns alarm info as long values
- **DBR_AL_DOUBLE**: returns alarm info as double values

15.3.2 Options
Example

The file `dbAccess.h` contains macros for using options. A brief example should show how they are used. The following example defines a buffer to accept an array of up to ten float values. In addition it contains fields for options `DBR_STATUS` and `DBR_TIME`.

```
struct buffer {
   DBRstatus
```

```
      DBRtime
      float  value[10];
   } buffer;
```

The associated `dbGetField` call is:

```
   long options,number_elements,status;
       ...
   options = DBR_STATUS | DBR_TIME;
   number_elements = 10;
   status = dbGetField(paddr,DBR_FLOAT,&buffer,&options,&number_elements);
```

Consult `dbAccess.h` for a complete list of macros.

Structure `dbAddr` contains a field `dbr_field_type`. This field is the database request type that most closely matches the database field type. Using this request type will put the smallest load on the IOC.

Channel Access provides routines similar to `dbGetField`, and `dbPutField`. It provides remote access to `dbGetField`, `dbPutField`, and to the database monitors described below.

15.3.3 ACKT and ACKS

The request types `DBR_PUT_ACKT` and `DBR_PUT_ACKS` are used for global alarm acknowledgment. The alarm handler uses these requests. For each of these types the user (normally channel access) passes an unsigned short value. This value represents:

DBR_PUT_ACKT - Do transient alarms have to be acknowledged? (0,1) means (no, yes).

`DBR_PUT_ACKS` - The highest alarm severity to acknowledge. If the current alarm severity is less then or equal to this value the alarm is acknowledged.

15.4 Database Access Routines

15.4.1 dbNameToAddr

Locate a process variable, format:

```
   long dbNameToAddr(
      char  *pname, /*ptr to process variable name */
      struct dbAddr  *paddr);
```

The most important goal of database access can be stated simply: Provide quick access to database records and fields within records. The basic rules are:

- Call `dbNameToAddr` once and only once for each field to be accessed.
- Read field values via `dbGetField` and write values via `dbPutField`.

The routines described in this subsection are used by channel access, sequence programs, etc. Record processing routines, however, use the routines described in the next section rather then `dbGetField` and `dbPutField`.

Given a process variable name, this routine locates the process variable and fills in the fields of structure `dbAddr`. The format for a process variable name is:

```
   "<record_name>.<field_name>"
```

For example the value field of a record with record name `sample_name` is:

"`sample_name.VAL`".

The record name is case sensitive. Field names always consist of all upper case letters.

`dbNameToAddr` locates a record via a process variable directory (PVD). It fills in a structure (`dbAddr`) describing the field. `dbAddr` contains the address of the record and also the field. Thus other routines can locate the record and field without a search. Although the PVD allows the record to be located via a hash algorithm and the field within a record via a binary search, it still takes about 80 microseconds (25MHz 68040) to located a process variable. Once located the `dbAddr` structure allows the process variable to be accessed directly.

15.4.2 Get Routines

15.4.2.1 dbGetField

Get values associated with a process variable, format:

```
long dbGetField(
   struct dbAddr  *paddr,
   short  dbrType,  /* DBR_xxx */
   void   *pbuffer,  /*addr of returned data */
   long   *options,  /*addr of options */
   long   *nRequest,  /*addr of number of elements */
   void   *pfl);  /*used by monitor routines */
```

Thus routine locks, calls `dbGet`, and unlocks.

15.4.2.2 dbGetLink and dbGetLinkValue

Get value from the field referenced by a database link, format:

```
long dbGetLink(
   struct db_link  *pdbLink,/*addr of database link*/
   short  dbrType,/* DBR_xxx*/
   void  *pbuffer,/*addr of returned data*/
   long  *options,/*addr of options*/
   long  *nRequest);/*addr of number of elements desired*/

NOTES:
   1) options can be NULL if no options are desired.
   2) nRequest can be NULL for a scalar.
```

`dbGetLink` is actually a macro that calls `dbGetLinkValue`. The macro skips the call for constant links. User code should never call `dbGetLinkValue`.

This routine is called by database access itself and by record support and/or device support routines in order to get values for input links. The value can be obtained directly from other records or via a channel access client. This routine honors the link options (process and maximize severity). In addition it has code that optimizes the case of no options and scalar.

15.4.2.3 dbGet

Get values associated with a process variable, format:

```
long dbGet(
   struct dbAddr*paddr,
   short dbrType, /* DBR_xxx*/
```

```
      void  *pbuffer,/*addr of returned data
      long  *options,/*addr of options*/
      long  *nRequest,/*addr of number of elements*/
      void  *pfl);   /*used by monitor routines*/
```

Thus routine retrieves the data referenced by `paddr` and converts it to the format specified by `dbrType`.

”`options`” is a read/write field. Upon entry to `dbGet`, `options` specifies the desired options. When `dbGetField` returns, `options` specifies the options actually honored. If an option is not honored, the corresponding fields in buffer are filled with zeros.

”`nRequest`” is also a read/write field. Upon entry to `dbGet` it specifies the maximum number of data elements the caller is willing to receive. When `dbGet` returns it equals the actual number of elements returned. It is permissible to request zero elements. This is useful when only option data is desired.

”`pfl`” is a field used by the Channel Access monitor routines. All other users must set `pfl=NULL`.

`dbGet` calls one of a number of conversion routines in order to convert data from the `DBF` types to the `DBR` types. It calls record support routines for special cases such as arrays. For example, if the number of field elements is greater then 1 and record support routine `get_array_info` exists, then it is called. It returns two values: the current number of valid field elements and an offset. The number of valid elements may not match `dbAddr.no_elements`, which is really the maximum number of elements allowed. The offset is for use by records which implement circular buffers.

15.4.3 Put Routines

15.4.3.1 dbPutField

Change the value of a process variable, format:

```
long dbPutField(
   structdbAddr *paddr,
   short dbrType, /* DBR_xxx*/
   void  *pbuffer,/*addr of data*/
   long  nRequest);/*number of elements to write*/
```

This routine is responsible for accepting data in one of the `DBR_xxx` formats, converting it as necessary, and modifying the database. Similar to `dbGetField`, this routine calls one of a number of conversion routines to do the actual conversion and relies on record support routines to handle arrays and other special cases.

It should be noted that routine `dbPut` does most of the work. The actual algorithm for `dbPutField` is:

1. If the `DISP` field is `TRUE` then, unless it is the `DISP` field itself which is being modified, the field is not written.
2. The record is locked.
3. `dbPut` is called.
4. If the `dbPut` is successful then:
   If this is the `PROC` field or if both of the following are `TRUE`: 1) the field is a process passive field, 2) the record is passive.
   a. If the record is already active ask for the record to be reprocessed when it completes.
   b. Call `dbScanPassive` after setting `putf` `TRUE` to show the process request came from `dbPutField`.
5. The record is unlocked.

15.4.3.2 dbPutLink and dbPutLinkValue

Change the value referenced by a database link, format:

```
long dbPutLink(
```

```
      structdb_link  *pdbLink,/*addr of database link*/
      short dbrType, /* DBR_xxx*/
      void  *pbuffer,/*addr of data to write*/
      long  nRequest);/*number of elements to write*/
```

`dbPutLink` is actually a macro that calls `dbPutLinkValue`. The macro skips the call for constant links. User code should never call `dbPutLinkValue`.

This routine is called by database access itself and by record support and/or device support routines in order to put values into other database records via output links.

For Channel Access links it calls `dbCaPutLink`.

For database links it performs the following functions:

1. Calls `dbPut`.
2. Implements maximize severity.
3. If the field being referenced is `PROC` or if both of the following are true: 1) `process_passive` is `TRUE` and 2) the record is passive then:
   a. If the record is already active because of a `dbPutField` request then ask for the record to be reprocessed when it completes.
   b. otherwise call `dbScanPassive`.

15.4.3.3 dbPut

Put a value to a database field, format:

```
   long dbPut(
      struct dbAddr  *paddr,
      short dbrType, /* DBR_xxx*/
      void  *pbuffer,/*addr of data*/
      long  nRequest);/*number of elements to write*/
```

This routine is responsible for accepting data in one of the `DBR_xxx` formats, converting it as necessary, and modifying the database. Similar to `dbGet`, this routine calls one of a number of conversion routines to do the actual conversion and relies on record support routines to handle arrays and other special cases.

15.4.4 Put Notify Routines

`dbPutNotify` is a request to notify the caller when all records that are processed as a result of a put complete processing. Complications occur because of record linking and asynchronous records. A put can cause an entire chain of records to process. If any record is an asynchronous record then record completion means asynchronous completion.

The following rules are implemented:

1. The user code must allocate a putNotify control block and. Before calling dbPutNotify the user must set fields paddr, pbuffer, nRequest, and dbrType. paddr is the value returned by dbNameToAddr. The field userPvt is never accessed by dbNotify and is for the user.. If a putNotify is already in use, i.e. a dbPutNotify has been issued and the userCallbach has not been called, it is illegal to issue a new dbPutNotify with the same putNotify control block. Any such attempt will cause an assert failure.
2. The userCallback routine will be always be called unless `dbNotifyCancel` is called. The userCallback is called when the dbPutNotify is complete. The user is then free to reuse or delete the putNotify control block. The user supplied callback is called when all processing is complete or when an error is detected. If everything completes synchronously the callback routine will be called BEFORE `dbPutNotify` returns.The userCallback is called without anything locked

3. If the user calls dbNotifyCancel then the userCallback will NOT be called after dbNotifyCancel returns. It may get called while dbNotifycancel is active. If it is active dbNotifyCancel will not return until userCallback completes. Thus after dbNotifyCancel returns the user may reuse or delete the putNotify control block. The putNotify control block MUST NOT be deleted by userCallback.
4. If another putNotify is already active on the record associated with the putNotify, the new putNotify is put on a restart list and automatically restarted.
5. If the record associated with the putNotify is already active for some other reason, the putNotify takes ownership of the record and starts the put request when the record completes processing.
6. In general a set of records may be processed as a result of a single `dbPutNotify`. If a record in the set is found to be active, either because PACT is true or because a putNotify already owns the record, then that record is not made part of the set of records that must complete before the putNotify request completes.

15.4.4.1 putNotifyInit

This is called by iocInit.

Format:

```
void putNotifyInit(void);
```

15.4.4.2 dbPutNotify

Perform a database put and notify when record processing is complete.

Format:

```
void dbPutNotify(putNotify *pputnotify);

where

typedef enum {
   putNotifyOK,
   putNotifyCanceled,
   putNotifyError
   putNotifyPutDisabled
}putNotifyStatus;


typedef struct putNotify{
   /*The following must be set by the user*/
   void     (*userCallback)(struct putNotify *);
   struct dbAddr*paddr; /*dbAddr set by dbNameToAddr*/
   void     *pbuffer;   /*address of data*/
   long     nRequest;   /*number of elements to be written*/
   short    dbrType;    /*database request type*/
   void     *usrPvt;    /*for private use of user*/
   /*The following is status of request.Set by dbPutNotify*/
   putNotifyStatus status;
   /*fields private to database access*/
   ...
}putNotify;
```

The caller must allocate a `putNotify` structure and set the fields:

```
userCallback - Routine that is called upon completion
paddr - address of a dbAddr. Returned by dbNameToAddr.
```

```
pbuffer - address of data
nRequest - number of data elements
dbrType - database request type
usrPvt - a void * field that caller can use as needed.
```

The status value in putNotify.status is one of

- **putNotifyOK** Success
- **putNotifyCanceled** User issued a dbNotifyCancel.
- **putNotifyError** Either dbPut of dbProcess returned an error.
- **putNotifyPutDisabled** Puts have been disabled for the record.

The user callback is always called unless `dbNotifyCancel` is called before the put notify competes. It may be called while dbPutNotify or dbNotifyCancel is active.

15.4.4.3 dbNotifyCancel

Cancel an outstanding `dbPutNotify`.

Format:

```
void dbNotifyCancel(putNotify *pputnotify);
```

This cancels an active `dbPutNotify`.

15.4.4.4 dbNotifyAdd

This routine is called by database access itself. It should never be called by user code.

15.4.4.5 dbNotifyCompletion

This routine is called by database access itself. It should never be called by user code.

15.4.5 Utility Routines

15.4.5.1 dbBufferSize

Determine the buffer size for a `dbGetField` request, format:

```
long dbBufferSize(
   short dbrType, /* DBR_xxx*/
   long  options, /* options mask*/
   long  nRequest);/* number of elements*/
```

This routine returns the number of bytes that will be returned to `dbGetField` if the request type, options, and number of elements are specified as given to `dbBufferSize`. Thus it can be used to allocate storage for buffers.

NOTE: This should become a Channel Access routine

15.4.5.2 dbValueSize

Determine the size a value field, format:

```
dbValueSize(short  dbrType);/* DBR_xxx*/
```

This routine returns the number of bytes for each element of type `dbrType`.

NOTE: This should become a Channel Access routine

15.4.5.3 dbGetRset

Get address of a record support entry table.

Format:

```
struct rset *dbGetRset(DBADDR *paddr);
```

This routine returns the address of the record support entry table for the record referenced by the `DBADDR`.

15.4.5.4 dbIsValueField

Is this field the VAL field of the record?

Format:

```
int dbIsValueField(struct dbFldDes *pdbFldDes);
```

This is the routine that makes the `get_value` record support routine obsolete.

15.4.5.5 dbGetFieldIndex

Get field index.

Format:

```
int dbGetFieldIndex(DBADDR *paddr);
```

Record support routines such as `special` and `cvt_dbaddr` need to know which field the `DBADDR` references. The include file describing the record contains define statements for each field. `dbGetFieldIndex` returns the index that can be matched against the define statements (normally via a switch statement).

15.4.5.6 dbGetNelements

Get number of elements in a field.

Format:

```
long dbGetNelements(struct link *plink,long *nelements);
```

This sets `*nelements` to the number of elements in the field referenced by plink.

15.4.5.7 dbIsLinkConnected

Is the link connected.

Format:

```
int dbIsLinkConnected(struct link *plink);
```

This routine returns (TRUE, FALSE) if the link (is, is not) connected.

15.4.5.8 dbGetPdbAddrFromLink

Get address of DBADDR from link.

Format:

```
DBADDR *dbGetPdbAddrFromLink(struct link *plink);
```

This macro returns the address of the DBADDR for a database link and NULL for all other link types.

15.4.5.9 dbGetLinkDBFtype

Get field type of a link.

Format:

```
int dbGetLinkDBFtype(struct link *plink);
```

15.4.5.10 dbGetControlLimits

Get Control Limits for link.

Format:

```
long dbGetControlLimits(struct link *plink,double *low, double *high);
```

15.4.5.11 dbGetGraphicLimits

Get Graphic Limits for link.

Format:

```
long dbGetGraphicLimits(struct link *plink,double *low, double *high);
```

15.4.5.12 dbGetAlarmLimits

Get Alarm Limits for link.

Format:

```
long dbGetAlarmLimits(struct link *plink,
   double lolo,double *low, double *high,double hihi);
```

15.4.5.13 dbGetPrecision

Get Precision for link.

Format:

```
long dbGetPrecision(struct link *plink,short *precision);
```

15.4.5.14 dbGetUnits

Get Units for link.

Format:

```
long dbGetUnits(struct link *plink,char *units,int unitsSize);
```

15.4.5.15 dbGetSevr

Get Severity for link.

Format:

```
long dbGetSevr(struct link *plink,short *sevr);
```

15.4.5.16 dbGetTimeStamp

Get Time Stamp for record containing link.

Format:

```
long dbGetTimeStamp(struct link *plink,TS_STAMP *pstamp);
```

15.4.6 Attribute Routine

15.4.6.1 dbPutAttribute

Give a value to a record attribute.

```
long dbPutAttribute(char *recordTypename,
    char *name,char*value);
```

This sets the record attribute `name` for record type `recordTypename` to `value.` For example the following would set the version for the ai record.

```
dbPutAttribute("ai","VERS","V800.6.95")
```

15.4.7 Process Routines

15.4.7.1 dbScanPassive
dbScanLink
dbScanFwdLink

Process record if it is passive, format:

```
long dbScanPassive(
   struct dbCommon  *pfrom,
   struct dbCommon  *pto);   /* addr of record*/
long dbScanLink(
   struct dbCommon *pfrom,
   struct dbCommon *pto);
void dbScanFwdLink(struct link *plink);
```

`dbScanPassive` and `dbScanLink` are given the record requesting the scan, which may be `NULL`, and the record to be processed. If the record is passive and `pact=FALSE` then `dbProcess` is called. Note that these routine are called by `dbGetLink`, `dbPutField`, and by `recGblFwdLink.`

`dbScanFwdLink` is given a link that must be a forward link field. It follows the rules for scanning a forward link. That is for DB_LINKs it calls dbScanPassive and for CA_LINKS it does a dbCaPutLink if the PROC field of record is being addressed.

15.4.7.2 dbProcess

Request that a database record be processed, format:

```
long dbProcess(struct dbCommom  *precord);
```

Request that record be processed. Record processing is described in detail below.

15.5 Runtime Link Modification

Database links can be changed at run time but only via a channel access client, i.e. via calls to `dbPutField` but not to `dbPutLink`. The following restrictions apply:

- Only `DBR_STRING` is allowed.
- If a link is being changed to a different hardware link type then the `DTYP` field must be modified before the link field.

- The syntax for the string field is exactly the same as described for link fields in chapter “Database Definition”

NOTE: For this release modification to/from hardware links has not been tested. In addition modification to record/device support will be needed in order to properly support dynamic modification of hardware links.

15.6 Channel Access Monitors

There are facilities within the Channel Access communication infrastructure which allow the value of a process variable to be monitored by a channel access client. It is a responsibility of record support (and db common) to notify the channel access server when the internal state of a process variable has been modified. State changes can include changes in the value of a process variable and also changes in the alarm state of a process variable. The routine “db_post_events()” is called to inform the channel access server that a process variable state change event has occurred.

```
   #include <caeventmask.h>

int db_post_events(void *precord, void *pfield,
   unsigned intselect);
```

The first argument, “precord”, should be passed a pointer to the record which is posting the event(s). The second argument, “pfield”, should be passed a pointer to the field in the record that contains the process variable that has been modified. The third argument, “select”, should be passed an event select mask. This mask can be any logical or combination of {DBE_VALUE, DBE_LOG, DBE_ALARM}. A description of the purpose of each flag in the event select mask follows.

- DBE_VALUE This indicates that a significant change in the process variable’s value has occurred. A significant change is often determined by the magnitude of the monitor “dead band” field in the record.
- DBE_LOG This indicates that a change in the process variable’s value significant to archival clients has occurred. A significant change to archival clients is often determined by the magnitude of the archive “dead band” field in the record.
- DBE_ALARM This indicates that a change in the process variable’s alarm state has occurred.

The function “db_post_events()” returns 0 if it is successful and -1 if it fails. It appears to be common practice within EPICS record support to ignore the status from “db_post_events()”. At this time “db_post_events()” always returns 0 (success). because so many records at this time depend on this behavior it is unlikely that it will be changed in the future.

The function “db_post_events()” is written so that record support will never be blocked attempting to post an event because a slow client is not able to process events fast enough. Each call to “db_post_events()” causes the current value, alarm status, and time stamp for the field to be copied into a ring buffer. The thread calling “db_post_events()” will not be delayed by any network or memory allocation overhead. A lower priority thread in the server is responsible for transferring the events in the event queue to the channel access clients that may be monitoring the process variable.

Currently, when an event is posted for a DBF_STRING field or a field containing array data the value is NOT saved in the ring buffer and the client will receive whatever value happens to be in the field when the lower priority thread transfers the event to the client. This behavior may be improved in the future.

15.7 Lock Set Routines

User code only calls `dbScanLock` and `dbScanUnlock`. All other routines are called by `iocCore`.

15.7.0.1 dbScanLock

Lock a lock set:

```
long void dbScanLock(struct dbCommon *precord);
```

Lock the lock set to which the specified record belongs.

15.7.0.2 dbScanUnlock

Unlock a lock set:

```
long void dbScanUnlock(struct dbCommon *precord);
```

Lock the lock set to which the specified record belongs

15.7.0.3 dbLockGetLockId

Get lock set id:

```
long dbLockGetLockId(struct dbCommon *precord);
```

Each lock set is assigned a unique ID. This routine retrieves it. This is most useful to determine if two records are in the same lock set.

15.7.0.4 dbLockInitRecords

Determine lock sets for each record in database.

```
void dbLockInitRecords(dbBase *pdbbase);
```

Called by `iocInit`.

15.7.0.5 dbLockSetMerge

Merge records into same lock set.

```
void dbLockSetMerge(struct dbCommon *pfirst,
   struct dbCommon *psecond);
```

If specified records are not in same lock set the lock sets are merged. Called by dbLockInitRecords and also when links are modified by `dbPutField`.

15.7.0.6 dbLockSetSplitSl

Recompute lock sets for given lock set

```
void dbLockSetSplit(struct dbCommon *psource);
```

This is called when `dbPutField` modifys links.

15.7.0.7 dbLockSetGblLock

Global lock for modifying links.

```
void dbLockSetGblLock(void);
```

Only one task at a time can modify link fields. This routine provides a global lock to prevent conflicts.

15.7.0.8 dbLockSetGblUnlock

Unlock the global lock.

```
void dbLockSetGblUnlock(void);
```

15.7.0.9 dbLockSetRecordLock

If record is not already scan locked lock it.

```
void dbLockSetRecordLock(struct dbCommon *precord);
```

15.8 Channel Access Database Links

The routines described here are used to create and manipulate Channel Access connections from database input or output links. At IOC initialization an attempt is made to convert all process variable links to database links. For any link that fails, it is assumed that the link is a Channel Access link, i.e. a link to a process variable defined in another IOC. The routines described here are used to manage these links. User code never needs to call these routines. They are automatically called by iocInit and database access.

At `iocInit` time a task `dbCaLink` is spawned. This task is a channel access client that issues channel access requests for all channel access links in the database. For each link a channel access search request is issued. When the search succeeds a channel access monitor is established. The monitor is issued specifying `ca_field_type` and `ca_element_count`. A buffer is also allocated to hold monitor return data as well as severity. When `dbCaGetLink` is called data is taken from the buffer, converted if necessary, and placed in the location specified by the `pbuffer` argument.

When the first `dbCaPutLink` is called for a link an output buffer is allocated, again using `ca_field_type` and `ca_element_count`. The data specified by the pbuffer argument is converted and stored in the buffer. A request is then made to `dbCaLink` task to issue a `ca_put`. Subsequent calls to `dbCaPutLink` reuse the same buffer.

15.8.1 Basic Routines

Except for dbCaPutLinkCallback, these routines are normally only called by database access, i.e. they are not called by record support modules.

15.8.1.1 dbCaLinkInit

Called by `iocInit` to initialize the `dbCa` library

```
void dbCaLinkInit(void);
```

15.8.1.2 dbCaAddLink

Add a new channel access link

```
void dbCaAddLink(struct link *plink);
```

15.8.1.3 dbCaAddLinkCallback

```
void dbCaAddLinkCallback(struct link *plink,
         dbCaCallback connect,dbCaCallback monitor,void *userPvt);
```

`connect` will be called whenever the link connects or disconnects. `monitor` will be called whenever a monitor event occurs. `connect` and or `monitor` may be null.

15.8.1.4 dbCaRemoveLink

Remove channel access link.

```
void dbCaRemoveLink(struct link *plink);
```

15.8.1.5 dbCaGetLink

Get link value

```
long dbCaGetLink(struct link *plink,short dbrType,
   void *pbuffer,unsigned short *psevr,long *nRequest);
```

15.8.1.6 dbCaPutLink

Put link value

```
long dbCaPutLink(struct link *plink,short dbrType,
   void *buffering nRequest);
```

15.8.1.7 dbCaPutLinkCallback

This is meant for use by device or record support that wants a put to complete before completing record processing.

```
long dbCaPutLinkCallback(struct link *plink,short dbrType,
   const void *pbuffer,long nRequest,dbCaPutCallback callback);
```

<base>/src/dev/devSoft/devAoSoftCallback.c provides an example of how to use this finction. It contains:

```
static long write_ao(aoRecord *pao)
{
    struct link *plink = &pao->out;
    long status;

    if(pao->pact) return(0);
    if(plink->type!=CA_LINK) {
        status = dbPutLink(&pao->out,DBR_DOUBLE,&pao->oval,1);
        return(status);
    }
    status = dbCaPutLinkCallback(plink,DBR_DOUBLE,&pao->oval,1,
                (dbCaCallback)dbCaCallbackProcess,plink);
    if(status) {
        recGblSetSevr(pao,LINK_ALARM,INVALID_ALARM);
        return(status);
    }
    pao->pact = TRUE;
    return(0);
}
```

What happens is the following:

When the record is processed write_ao is called with pact=0.

If the link is not a CA_LINK it just calls dbPutLink. It leaves pact 0. Thus record support completes.

If it is a CA_LINK it calls dbCaPutLinkCallback and sets pact true. Thus record is asynchronous.

If the record is asynchrnous then sometime later dbCaCallbackProcess is called. It calls the process routine of record support, which calls write_ao with pact true. write_ao just returns success. Record support then completes the second phase of record processing.

There is a possibility that the link is changed between the two phases of record processing. If this happens the user supplied callback will still get called exactly once but the link may have been modified.

15.8.2 Attributes of Link

The routines in this section are meant for use by device support to find out information about link fields. They must be called with dbScanLock held, i.e. normally they are called by the read or write method provided by device support.

15.8.2.1 dbCaIsLinkConnected

Is Channel Connected

```
int dbCaIsLinkConnected(struct link *plink)
```

This routine returns (TRUE, FALSE) if the link (is, is not) connected.

15.8.2.2 dbCaGetNelements

Get Number of Elements

```
long dbCaGetNelements(struct link *plink,long *nelements);
```

This call, which returns an error if the link is not connected, sets the native number of elements.

15.8.2.3 dbCaGetSevr

Get Alarm Severity

```
long dbCaGetSevr(struct link *plink,short *severity);
```

This call, which returns an error if the link is not connected, sets the alarm severity.

15.8.2.4 dbCaGetTimeStamp

Get Time Stamp

```
long dbCaGetTimeStamp(struct link *plink,TS_STAMP *pstamp));
```

This call, which returns an error if the link is not connected, sets pstamp to the time obtained by the last CA monitor.

15.8.2.5 dbCaGetLinkDBFtype

Get link type

```
int dbCaGetLinkDBFtype(struct link *plink);
```

This call, which returns an error if the link is not connected, returns the field type.

15.8.2.6 dbCaGetAttributes

Get Attributes

```
long dbCaGetAttributes(struct link *plink,
   void (*callback)(void *usrPvt),void *usrPvt);
```

When ever dbCa receives a connection it issues a CA get request to obtain the control, graphic, and alarm limits and to obtain the precision and units. By calling dbCaGetAttributes the caller can be notified when this get completes.

15.8.2.7 dbCaGetControlLimits

Get Control Limits

```
long dbCaGetControlLimits(struct link *plink,double *low, double *high);
```

This call returns an error if the link is not connected or if the CA get request for limits, etc has not completed. If it returns success it has set the control limits.

15.8.2.8 dbCaGetGraphicLimits

Get graphic Limits

```
long dbCaGetGraphicLimits(struct link *plink,double *low, double *high);
```

This call returns an error if the link is not connected or if the CA get request for limits, etc has not completed. If it returns success it has set the graphic limits.

15.8.2.9 dbCaGetAlarmLimits

Get Alarm Limits

```
long dbCaGetAlarmLimits(struct link *plink,
   double *lolo, double *low, double *high, double *hihi);
```

This call returns an error if the link is not connected or if the CA get request for limits, etc has not completed. If it returns success it has set the alarm limits.

15.8.2.10 dbCaGetPrecision

Get Precision

```
long dbCaGetPrecision(struct link *plink,short *precision);
```

This call returns an error if the link is not connected or if the CA get request for limits, etc has not completed. If it returns success it has set the precision.

15.8.2.11 dbCaGetUnits

Get Units

```
long dbCaGetUnits(struct link *plink,char *units,int unitsSize);
```

This call returns an error if the link is not connected or if the CA get request for limits, etc has not completed. If it returns success it has set the units.

Chapter 16: EPICS General Purpose Tasks

16.1 Overview

This chapter describes two sets of EPICS supplied general purpose tasks: 1) Callback, and 2) Task Watchdog.

Often when writing code for an IOC there is no obvious task under which to execute. A good example is completion code for an asynchronous device support module. EPICS supplies the callback tasks for such code.

If an IOC tasks "crashes" there is normally no one monitoring the vxWorks shell to detect the problem. EPICS provides a task watchdog task which periodically checks the state of other tasks. If it finds that a monitored task has terminated or suspended it issues an error message and can also call other routines which can take additional actions. For example a subroutine record can arrange to be put into alarm if a monitored task crashes.

Since IOCs normally run autonomously, i.e. no one is monitoring the vxWorks shell, IOC code that issues `printf` calls generates errors messages that are never seen. In addition the vxWorks implementation of fprintf requires much more stack space then `printf` calls. Another problem with vxWorks is the `logMsg` facility. `logMsg` generates messages at higher priority then all other tasks except the shell. EPICS solves all of these problems via an error message handling facility. Code can call any of the routines `errMessage`, `errPrintf`, or `errlogPrintf`. Any of these result in the error message being generated by a separate low priority task. The calling task has to wait until the message is handled but other tasks are not delayed. In addition the message can be sent to a system wide error message file.

16.2 General Purpose Callback Tasks

16.2.1 Overview

EPICS provides three general purpose IOC callback tasks. The only difference between the tasks is scheduling priority: Low, Medium, and High. The low priority task runs at a priority just higher than Channel Access, the medium at a priority about equal to the median of the periodic scan tasks, and the high at a priority higher than the event scan task.The callback tasks provide a service for any software component that needs a task under which to run. The callback tasks use the task watchdog (described below). They use a rather generous stack and can thus be used for invoking record processing. For example the I/O event scanner uses the general purpose callback tasks.

The following steps must be taken in order to use the general purpose callback tasks:

1. Include callback definitions:

```
#include <callback.h>
```

2. Provide storage for a structure that is a private structure for the callback tasks:

```
CALLBACK mycallback;
```

It is permissible for this to be part of a larger structure, e.g.

```
struct {
   ...
   CALLBACK mycallback;
   ...
} ...
```

3. Calls (actually macros) to initialize fields in `CALLBACK`:

```
callbackSetCallback(VOIDFUNCPTR func, CALLBACK *pcb);
```

This defines the caller's callback routine. The first argument is the address of a function returning `VOID`. The second argument is the address of the `CALLBACK` structure.

```
callbackSetPriority(int, CALLBACK *pcb);
```

The first argument is the priority, which can have one of the values: `priorityLow`, `priorityMedium`, or `priorityHigh`. These values are defined in `callback.h`. The second argument is again the address of the `CALLBACK` structure.

```
callbackSetUser(void *, CALLBACK *pcb);
```

This call is used to save a value that can be retrieved via the macro:

```
callbackGetUser(void *,CALLBACK *pcb);
```

If your callback function exists to process a single record inside calls to `dbScanLock`/`dbScanUnlock`, you can use this shortcut which provides the callback routine for you:

```
callbackSetProcess(CALLBACK *pcb, int prio, void *prec);
```

4. Whenever a callback request is desired just call one of the following:

```
callbackRequest(CALLBACK *pcb);
callbackRequestProcessCallback(CALLBACK *pcb, int prio, void *prec);
```

Either can be called from interrupt level code. The callback routine is passed a single argument, which is the same argument that was passed to `callbackRequest`, i.e., the address of the `CALLBACK` structure. The second routine is a shortcut for calling first `callbackSetProcess` and then `callbackRequest`. There are also delayed versions of these routines available now, see below for details.

16.2.2 Syntax

The following calls are provided:

```
void callbackInit(void);

void callbackSetCallback(void *pcallbackFunction,
   CALLBACK *pcallback);
void callbackSetPriority(int priority, CALLBACK *pcallback);
void callbackSetUser(void *user, CALLBACK *pcallback);
```

```
void callbackGetUser(void *user, CALLBACK *pcallback);
void callbackSetProcess(CALLBACK *pcallback, int Priority, void *prec);

void callbackRequest(CALLBACK *);
void callbackRequestProcessCallback(CALLBACK *pCallback,
   int Priority, void *prec);
void callbackRequestDelayed(CALLBACK *pCallback, double seconds);
void callbackRequestProcessCallbackDelayed(
    CALLBACK *pCallback, int Priority, void *prec, double seconds);
void callbackCancelDelayed(CALLBACK *pcallback);
int callbackSetQueueSize(int size);
```

Notes:

- `callbackInit` is performed automatically when EPICS initializes and IOC. Thus user code never calls this function.
- `callbackSetCallback`, `callbackSetPriority`, `callbackSetUser`, and `callbackGetUser` are actually macros.
- Both `callbackRequest` and `callbackRequestProcessCallback` can be called from interrupt handler routines.
- The delayed version of the `callbackRequest` routines wait the specified amout of time before scheduling the callback.
- `callbackCancelDelayed` can be used to cancel a delayed callback.
- `callbackRequestProcessCallback` is designed for the completion phase of asynchronous record processing. It issues the calls:

  ```
  callbackSetCallback(ProcessCallback, pCallback);
  callbackSetPriority(Priority, pCallback);
  callbackSetUser(pRec, pCallback);
  callbackRequest(pCallback);
  ```

  `ProcessCallback`, which is designed for asynchronous device completion applications, consists of the following code:

  ```
  static void ProcessCallback(CALLBACK *pCallback)
  {
     dbCommon    *pRec;
     struct rset *prset;

     callbackGetUser(pRec, pCallback);
     prset = (struct rset *)pRec->rset;
     dbScanLock(pRec);
     (*prset->process)(pRec);
     dbScanUnlock(pRec);
  }
  ```

16.2.3 Example

An example use of the callback tasks.

```
#include <callback.h>
```

```
static structure {
   char      begid[80];
   CALLBACK callback;
   char     endid[80];
}myStruct;

void myCallback(CALLBACK *pcallback)
{
   struct myStruct *pmyStruct;
   callbackGetUser(pmyStruct,pcallback)
   printf("begid=%s endid=%s\n",&pmyStruct->begid[0],
      &pmStruct->endid[0]);
}
example(char *pbegid, char*pendid)
{
   strcpy(&myStruct.begid[0],pbegid);
   strcpy(&myStruct.endid[0],pendid);
   callbackSetCallback(myCallback,&myStruct.callback);
   callbackSetPriority(priorityLow,&myStruct.callback);
   callbackSetUser(&myStruct,&myStruct.callback);
   callbackRequest(&myStruct.callback);
}
```

The example can be tested by issuing the following command to the vxWorks shell:

```
example("begin","end")
```

This simple example shows how to use the callback tasks with your own structure that contains the `CALLBACK` structure at an arbitrary location.

16.2.4 Callback Queue

The callback requests put the requests on a vxWorks ring buffer. Thus buffer is set by default to hold 2000 requests. This value can bechanged by calling `callbackSetQueueSize` before `incInit` in the startup file. The syntax is:

```
int callbackSetQueueSize(int size)
```

16.3 Task Watchdog

EPICS provides a task that acts as a watchdog for other tasks. Any task can request to be watched, and most of the IOC tasks do this. A status monitoring subsystem in the IOC can register to be notified about any changes that occur. The watchdog task runs periodically and checks each task in its task list. If any task is suspended, an error message is displayed and any notifications made. The task watchdog provides the following features:

1. Include module:

   ```
   #include <taskwd.h>
   ```

2. Request by a task to be monitored:

   ```
   taskwdInsert (epicsThreadId tid, TASKWDFUNC callback, VOID *usr);
   ```

   This adds the task with the specified `tid` to the list of tasks to be watched, and makes any requested notifications that a new task has been registered. If `tid` is given as zero, the `epicsThreadId` of the calling thread is used instead. If `callback` is not NULL and the task later becomes suspended, the callback routine will be called with the single argument `usr`.

3. Remove task from list:

   ```
   taskwdRemove(epicsThreadId tid);
   ```

   This routine must be called before the monitored task exits. It makes any requested notifications and removes the task from the list of tasks being watched. If `tid` is given as zero, the `epicsThreadId` of the calling thread is used instead.

4. Request to be notified of changes:

   ```
   typedef struct {
       void (*insert)(void *usr, epicsThreadId tid);
       void (*notify)(void *usr, epicsThreadId tid, int suspended);
       void (*remove)(void *usr, epicsThreadId tid);
   } taskwdMonitor;

   taskwdMonitorAdd(const taskwdMonitor *funcs, void *usr);
   ```

   This call provides a set of callbacks for the task watchdog to call when a task is registered or removed or when any task gets suspended. The `usr` pointer given at registration is passed to the callback routine along with the `tid` of the thread the notification is about. In many cases the `insert` and `remove` callbacks will be called from the context of the thread itself, although this is not guaranteed (the registration could be made by a parent thread for instance). The `notify` callback also indicates whether the task went into or out of suspension; it is called in both cases, unlike the callbacks registered with `taskwdInsert` and `taskwdAnyInsert`.

5. Rescind notification request:

   ```
   taskwdMonitorDel(const taskwdMonitor *funcs, void *usr);
   ```

   This call removes a previously registered notification. Both `funcs` and `usr` must match the values given to `taskwdMonitorAdd` when originally registered.

6. Print a report:

```
taskwdShow(int level);
```

If `level` is zero, the number of tasks and monitors registered is displayed. For higher values the registered task names and their current states are also shown in tabular form.

7. The following routines are provided for backwards compatibility purposes, but are now deprecated:

```
taskwdAnyInsert(void *key, TASKWDANYFUNC callback, VOID *usr);
```

The callback routine will be called whenever any of the tasks being monitored by the task watchdog become suspended. `key` must have a unique value because the task watchdog system uses this value to determine which entry to remove when `taskwdAnyRemove` is called.

```
taskwdAnyRemove(void *key);
```

`key` is the same value that was passed to `taskwdAnyInsert`.

Chapter 17: Database Scanning

17.1 Overview

Database scanning is the mechanism for deciding when to process a record. Five types of scanning are possible:

- **Periodic**: A record can be processed periodically. A number of time intervals are supported.
- **Event**: Event scanning is based on the posting of an event by another component of the software via a call to the routine `post_event`.
- **I/O Event**: The original meaning of this scan type is a request for record processing as a result of a hardware interrupt. The mechanism supports hardware interrupts as well as software generated events.
- **Passive**: Passive records are processed only via requests to `dbScanPassive`. This happens when database links (Forward, Input, or Output), which have been declared "Process Passive" are accessed during record processing. It can also happen as a result of `dbPutField` being called (This normally results from a Channel Access put request).
- **Scan Once**: In order to provide for caching puts, The scanning system provides a routine `scanOnce` which arranges for a record to be processed one time.

This chapter explains database scanning in increasing order of detail. It first explains database fields involved with scanning. It next discusses the interface to the scanning system. The last section gives a brief overview of how the scanners are implemented.

17.2 Scan Related Database Fields

The following fields are normally defined via DCT. It should be noted, however, that it is quite permissible to change any of the scan related fields of a record dynamically. For example, a display manager screen could tie a menu control to the `SCAN` field of a record and allow the operator to dynamically change the scan mechanism.

17.2.1 SCAN

This field, which specifies the scan mechanism, has an associated menu of the following form:

Passive: Passively scanned.
Event: Event Scanned. The field `EVNT` specifies event number
I/O Event scanned.
10 Second: Periodically scanned - Every 10 seconds
...
.1 Second: Periodically scanned - Every .1 seconds

17.2.2 PHAS

This field determines processing order for records that are in the same scan set. For example all records periodically scanned at a 2 second rate are in the same scan set. All Event scanned records with the same EVNT are in the same scan set, etc. For records in the same scan set, all records with PHAS=0 are processed before records with PHAS=1, which are processed before all records with PHAS=2, etc.

In general it is not a good idea to rely on PHAS to enforce processing order. It is better to use database links.

17.2.3 EVNT - Event Number

This field only has meaning when SCAN is set to Event scanning, in which case it specifies the event number. In order for a record to be event scanned, EVNT must be in the range 0,...255. It should also be noted that some EPICS software components will not request event scanning for event 0. One example is the eventRecord record support module. Thus the application developer will normally want to define events in the range 1,...,255.

17.2.4 PRIO - Scheduling Priority

This field can be used by any software component that needs to specify scheduling priority, e.g. the event and I/O event scan facility uses this field.

17.3 Scan Related Software Components

17.3.1 menuScan.dbd

This file contains definitions for a menu related to field SCAN. The definitions are of the form:

```
menu(menuScan) {
   choice(menuScanPassive,"Passive")
   choice(menuScanEvent,"Event")
   choice(menuScanI_O_Intr,"I/O Intr")
   choice(menuScan10_second,"10 second")
   choice(menuScan5_second,"5 second")
   choice(menuScan2_second,"2 second")
   choice(menuScan1_second,"1 second")
   choice(menuScan_5_second,".5 second")
   choice(menuScan_2_second,".2 second")
   choice(menuScan_1_second,".1 second")
}
```

The first three choices must appear first and in the order shown. The remaining definitions are for the periodic scan rates, which must appear in the order slowest to fastest (the order directly controls the thread priority assigned to the particular scan rate, and faster scan rates should be assigned higher thread priorities). At IOC initialization, the menu choice strings are read at scan initialization. The number of periodic scan rates and the period of each rate is determined from the menu choice strings. Thus periodic scan rates can be changed by changing menuScan.dbd and loading this version via dbLoadDatabase. The only requirement is that each periodic choice string must begin with a numeric value specified in units of seconds.

17.3.2 dbScan.h

All software components that interact with the scanning system must include this file.

The most important definitions in this file are:

```
#define SCAN_PASSIVE       menuScanPassive
#define SCAN_EVENT         menuScanEvent
#define SCAN_IO_EVENT      menuScanI_O_Intr
#define SCAN_1ST_PERIODIC  (menuScanI_O_Intr + 1)

/*definitions for I/O Interrupt Scanning */
typedef struct io_scan_list *IOSCANPVT;

long scanInit(void);
void scanRun(void);
void scanPause(void);

void post_event(int event);
void scanAdd(struct dbCommon *);
void scanDelete(struct dbCommon *);
double scanPeriod(int scan);
void scanOnce(struct dbCommon *precord);
int scanOnceSetQueueSize(int size);

int scanppl(void);    /* print periodic lists*/
int scanpel(void);    /* print event lists*/
int scanpiol(void);   /* print io_event list*/

void scanIoInit(IOSCANPVT *);
void scanIoRequest(IOSCANPVT);
```

The first set of definitions defines the various scan types. The next definition `IOSCANPVT` is used when interfacing with the I/O interrupt scanner. The remaining definitions define the public scan access routines. These are described in the following subsections.

17.3.3 Initializing And Controlling Database Scaning

```
scanInit(void);
```

The routine `scanInit` is called by `iocInit`. It initializes the scanning system.

```
scanRun(void);
scanPause(void);
```

These routines start and stop all the scan tasks respectively. They are used by the `iocInit`, `iocRun` and `iocPause` commands.

17.3.4 Adding And Deleting Records From Scan List

The following routines are called each time a record is added or deleted from a scan list.

```
scanAdd(struct dbCommon *);
scanDelete(struct dbCommon *);
```

These routines are called by `scanInit` at IOC initialization time in order to enter all records created via DCT into the correct scan list. The routine `dbPut` calls `scanDelete` and `scanAdd` each time a scan related field is changed (each scan related field is declared to be `SPC_SCAN` in `dbCommon.dbd`). `scanDelete` is called before the field is modified and `scanAdd` after the field is modified.

17.3.5 Obtaining the scan period from the SCAN field

```
double scanPeriod(int scan);
```

The argument is an offset into the set of enum choices for menuScan.h. Most users will just use the SCAN field of a database record. It returns the scan period in seconds. The result will be 0.0 if scan doesn't refer to a periodic rate.

17.3.6 Declaring Database Event

Whenever any software component wants to declare a database event, it just calls:

```
post_event(event)
```

This can be called by virtually any IOC software component. For example sequence programs can call it. The record support module for `eventRecord` calls it.

17.3.7 Interfacing to I/O Event Scanning

Interfacing to the I/O event scanner is done via some combination of device and driver support.

1. Include `<dbScan.h>`
2. For each separate event source the following must be done:
   a. Declare an `IOSCANPVT` variable, e.g.
      ```
      static IOSCANPVT ioscanpvt;
      ```
   b. Call `scanIoInit`, e.g.
      ```
      scanIoInit(&ioscanpvt);
      ```
3. Provide the device support `get_ioint_info` routine. This routine has the format:
   ```
   long get_ioint_info(
      int  cmd,
      struct dbCommon  *precord,
         IOSCANPVT  *ppvt);
   ```
   This routine is called each time the record pointed to by `precord` is added or deleted from an I/O event scan list. `cmd` has the value (0,1) if the record is being (added to, deleted from) an I/O event list. This routine must give a value to `*ppvt`.
4. Whenever an I/O event is detected call `scanIoRequest`, e.g.
   ```
   scanIoRequest(ioscanpvt)
   ```
   This routine can be called from interrupt level. The request is actually directed to one of the standard callback tasks. The actual one is determined by the `PRIO` field of `dbCommon`.

The following code fragment shows an event record device support module that supports I/O event scanning:

```
#include  <vxWorks.h>
#include  <types.h>
#include  <stdioLib.h>
#include  <intLib.h>
#include  <dbDefs.h>
```

```
#include  <dbAccess.h>
#include  <dbScan.h>
#include  <recSup.h>
#include  <devSup.h>
#include  <eventRecord.h>
/* Create the dset for devEventXXX */
long init();
long get_ioint_info();
struct {
   long  number;
   DEVSUPFUN  report;
   DEVSUPFUN  init;
   DEVSUPFUN  init_record;
   DEVSUPFUN  get_ioint_info;
   DEVSUPFUN  read_event;
}devEventTestIoEvent={
   5,
   NULL,
   init,
   NULL,
   get_ioint_info,
   NULL};
static IOSCANPVT ioscanpvt;
static void int_service(IOSCANPVT ioscanpvt)
{
    scanIoRequest(ioscanpvt);
}

static long init()
{
    scanIoInit(&ioscanpvt);
    intConnect(<vector>,(FUNCPTR)int_service,ioscanpvt);
    return(0);
}
static long get_ioint_info(
   int   cmd,
   struct eventRecord   *pr,
   IOSCANPVT   *ppvt)
{
    *ppvt = ioscanpvt;
    return(0);
}
```

17.4 Implementation Overview

The code for the entire scanning system resides in `dbScan.c`, i.e. periodic, event, and I/O event. This section gives an overview of how the code in `dbScan.c` is organized. The listing of `dbScan.c` must be studied for a complete understanding of how the scanning system works.

17.4.1 Definitions And Routines Common To All Scan Types

Everything is built around two basic structures:

```
struct scan_list {
   FAST_LOCK  lock;
   ELLLIST  list;
   short   modified;
   long   ticks;   /*used only for periodic scan sets*/
};

struct scan_element{
   ELLNODE  node;
   struct scan_list  *pscan_list;
   struct dbCommon   *precord;
}
```

Later we will see how `scan_lists` are determined. For now just realize that `scan_list.list` is the head of a list of records that belong to the same scan set (for example, all records that are periodically scanned at a 1 second rate are in the same scan set). The node field in `scan_element` contain the list links. The normal vxWorks `lstLib` routines are used to access the list. Each record that appears in some scan list has an associated `scan_element`. The `SPVT` field which appears in `dbCommon` holds the address of the associated `scan_element`.

The `lock`, `modified`, and `pscan_list` fields allow `scan_elements`, i.e. records, to be dynamically removed and added to scan lists. If `scanList`, the routine which actually processes a scan list, is studied it can be seen that these fields allow the list to be scanned very efficiently if no modifications are made to the list while it is being scanned. This is, of course, the normal case.

The `dbScan.c` module contains several private routines. The following access a single scan set:

- **printList**: Prints the names of all records in a scan set.
- **scanList**: This routine is the heart of the scanning system. For each record in a scan set it does the following:
  ```
  dbScanLock(precord);
  dbProcess(precord);
  dbScanUnlock(precord);
  ```
  It also has code to recognize when a scan list is modified while the scan set is being processed.
- **addToList**: This routine adds a new element to a scan list.
- **deleteFromList**: This routine deletes an element from a scan list.

17.4.2 Event Scanning

Event scanning is built around the following definitions:

```
#define MAX_EVENTS 256
typedef struct event_scan_list {
     CALLBACK        callback;
     scan_list       scan_list;
}event_scan_list;
static event_scan_list
      *pevent_list[NUM_CALLBACK_PRIORITIES][MAX_EVENTS];
```

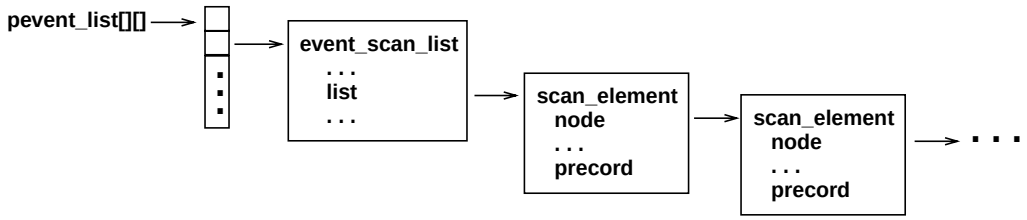


Figure 17-1: Scan List Memory Layout

`pevent_list` is a 2d array of pointers to `scan_lists`. Note that the array allows for 256 events, i.e. one for each possible event number. In other words, each event number and priority has its own scan list. No `scan_list` is actually created until the first request to add an element for that event number. The event scan lists have the memory layout illustrated in Figure 17-1.

17.4.2.1 post_event

```
post_event(int event)
```

This routine is called to request event scanning. It can be called from interrupt level. It looks at each `event_scan_list` referenced by `pevent_list`[*][`event`] (one for each callback priority) and if any elements are present in the `scan_list` a `callbackRequest` is issued. The appropriate callback task calls routine `eventCallback`, which just calls `scanList`.

17.4.3 I/O Event Scanning

I/O event scanning is built around the following definitions:

```
struct io_scan_list {
   CALLBACK   callback;
   struct scan_list   scan_list;
   struct io_scan_list   *next;
}
static struct io_scan_list
    *iosl_head[NUM_CALLBACK_PRIORITIES]
      = {NULL,NULL,NULL};
```

The array `iosl_head` and the field `next` are only kept so that `scanpiol` can be implemented and will not be discussed further. I/O event scanning uses the general purpose callback tasks to perform record processing, i.e. no task is spawned for I/O event. The callback field of `io_scan_list` is used to communicate with the callback tasks.

The following routines implement I/O event scanning:

17.4.3.1 scanIoInit

```
scanIoInit (IOSCANPVT  *ppioscanpvt)
```

This routine is called by device or driver support. It is called once for each interrupt source. `scanIoInit` allocates and initializes an array of `io_scan_list` structures; one for each callback priority and puts the address in `pioscanpvt`. Remember that three callback priorities are supported (low, medium, and high). Thus for each interrupt source the structures are illustrated in Figure 17-1:

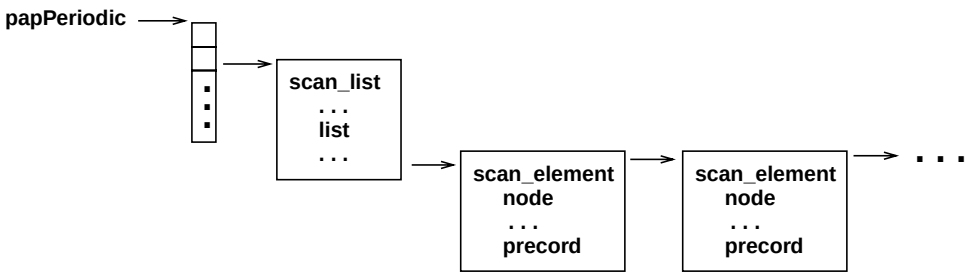


Figure 17-1: Structure after iocInit

When `scanAdd` or `scanDelete` are called, they call the device support routine `get_ioint_info` which returns `pioscanpvt`. The `scan_element` is added or deleted from the correct scan list.

17.4.3.2 scanIoRequest

```
scanIoRequest (IOSCANPVT pioscanpvt)
```

This routine is called to request I/O event scanning. It can be called from interrupt level. It looks at each `io_scan_list` referenced by `pioscanpvt` (one for each callback priority) and if any elements are present in the `scan_list` a `callbackRequest` is issued. The appropriate callback task calls routine `ioeventCallback`, which just calls `scanList`.

17.4.4 Periodic Scanning

Periodic scanning is built around the following definitions:

```
static int nPeriodic;
static struct scan_list **papPeriodic;
static int *periodicTaskId;
```

`nPeriodic`, which is determined at `iocInit` time, is the number of periodic rates. `papPeriodic` is a pointer to an array of pointers to `scan_lists`. There is an array element for each scan rate. Thus the structure illustrated in Figure 17-1 exists after `iocInit`.

A periodic scan task is created for each scan rate. The following routines implement periodic scanning:

17.4.4.1 initPeriodic

```
initPeriodic()
```

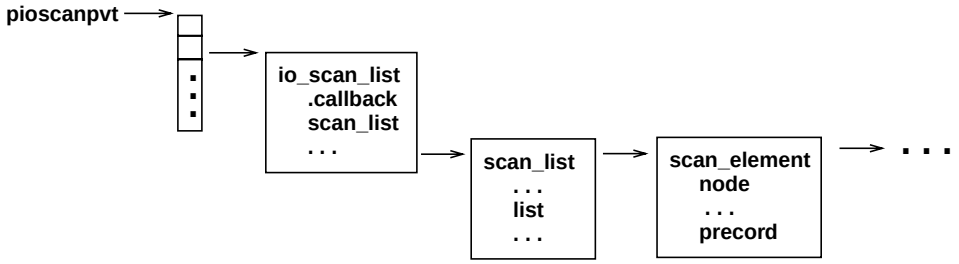


Figure 17-1: Interrupt Source Structure

This routine first determines the scan rates. It does this by accessing the `SCAN` field of the first record it finds. It issues a call to `dbGetField` with a `DBR_ENUM` request. This returns the menu choices for `SCAN`. From this the periodic rates are determined. The array of pointers referenced by `papPeriodic` is allocated. For each scan rate a `scan_list` is allocated and a `periodicTask` is spawned.

17.4.4.2 periodicTask

```
periodicTask (struct scan_list *psl)
```

This task just performs an infinite loop of calling `scanList` and then calling `taskDelay` to wait until the beginning of the next time interval.

17.4.5 Scan Once

17.4.5.1 scanOnce

```
void scanOnce (dbCommon *precord)
```

A task `onceTask` waits for requests to issue a `dbProcess` request. The routine `scanOnce` puts the address of the record to be processed in a ring buffer and wakes up `onceTask`.

This routine can be called from interrupt level.

17.4.5.2 SetQueueSize

`scanOnce` places its request on a vxWorks ring buffer.This is set by default to 1000 entries. It can be changed by executing the following command in the vxWorks startup file.

```
int scanOnceSetQueueSize(int size);
```

Chapter 18: IOC Shell

18.1 Introduction

The EPICS IOC shell is a simple command interpreter which provides a subset of the capabilities of the vxWorks shell. It is used to interpret startup scripts (st.cmd) and to execute commands entered at the console terminal. In most cases vxWorks startup scripts can be interpreted by the IOC shell without modification. The following sections of this chapter describe the operation of the IOC shell from the user's and programmer's points of view.

18.2 IOC Shell Operation

The IOC shell reads lines of input, expands environment variable parameters, breaks the line into commands and arguments then calls functions corresponding to the decoded command. Commands and arguments are separated by one or more `space' characters. Characters interpreted as spaces include the actual space character and the tab character as well as commas and open and close parentheses. Thus, the command line

```
dbLoadRecords("db/dbExample1.db","user=mrk")
```

would be interpreted by the IOC shell as the `dbLoadRecords` command with arguments `db/dbExample1.db` and `user=mrk`.

Unrecognized commands result in a diagnostic message but are otherwise ignored. Missing arguments are given a default value (0 for numeric arguments, NULL for string arguments). Extra arguments are ignored.

Unlike the vxWorks shell, string arguments do not have to be enclosed in quotes unless they contain one or more of the space characters, in which case one of the quoting mechanisms described in the following section must be used.

18.2.1 Environment variable parameter expansion

Lines of input not beginning with a comment character (#) are searched for character sequences of the form ${*name*} or $(*name*). Such sequences are replaced with the value of the environment variable *name* before any other processing takes place. Expansion is recursive so, for example,

```
epics> epicsEnvSet v1 \${v2}
epics> epicsEnvSet v2 \${v3}
epics> epicsEnvSet v3 somePV
epics> dbpr ${v1}
```

will print information about the `somePV` process variable — the `${v1}` argument to the dbpr command expands to `${v2}` which expands to `${v3}` which expands to `somePV`. The backslashes in the definitions are needed to postpone the expansion, otherwise it would be done before the values of v1 and v2 are set.

18.2.2 Quoting

Quoting is used to remove the special meaning normally assigned to certain characters and can be used to include space or quote characters in arguments. Quoting can not be used to extend a command over more than one input line.

There are three quoting mechanisms: the backslash character, single quotes, and double quotes. A backslash (\) preserves the literal value of the following character. Enclosing characters in single or double quotes preserves the literal value of each character (except a backslash) within the quotes, except that parameter expansion still occurs within double quotes. A single quote may occur between double quotes and a double quote may occur between single quotes.

18.2.3 Command-line editing and history

The IOC shell can use the readline or tecla library to obtain input from the console terminal. This provides full command-line editing as well as easy access to previous commands through the command-line history capabilties provided by these libraries. For full details, refer to the readline or tecla library documentation. Command and argument completion is not supported.

If neither the readline nor tecla library is used the only command-line editing and history capabilities will be those supplied by the underlying operating system. The console keyboard driver in Windows, for example, provides its own command-line editing and history commands. On vxWorks the ledLib command-line input libraries are used.

18.2.4 Redirection

The IOC shell recognizes a subset of UNIX shell I/O redirection operators. The redirection operators may precede, or appear anywhere within, or follow a command. Redirections are processed in the order they appear, from left to right. Failure to open or create a file causes the redirection to fail and the command to be ignored.

Redirection of input causes the file whose name results from the expansion of *filename* to be opened for reading on file descriptor *n*, or the standard input (file descriptor 0) if *n* is not specified. The general format for redirecting input is:

```
[n]<filename
```

As a special case, the IOC shell recognizes a standard input redirection appearing by itself (i.e. with no command) as a request to read commands from *filename* until an exit command or EOF is encountered. The IOC shell then resumes reading commands from the current source. Commands read from *filename* are not added to the readline command history. The level of nesting is limited only by the maximum number of files that can be open simultaneously.

Redirection of output causes the file whose name results from the expansion of *filename* to be opened for writing on file descriptor *n*, or the standard output (file descriptor 1) if *n* is not specified. If the file does not exist it is created; if it does exist it is truncated to zero size. The general format for redirecting output is:

```
[n]>filename
```

The general format for appending output is:

```
[n]>>filename
```

Redirection of output in this fashion causes the *filename* to be opened for appending on file descriptor *n*, or the standard output (file descriptor 1) if *n* is not specified. If the file does not exist it is created.

18.2.5 Utility Commands

The IOC shell recognizes the following commands as well as the commands described in chapter 6 (Database Design) and chapter 9 (IOC Test Facilities) among others. In addition, the commands described in the sequencer documentation are recognized.

Command	Description
help [command ...]	Display synopsis of specified commands. Wild-card matching is applied so '`help db*`' displays a synopsis of all commands beginning with the letters 'db'. With no arguments display a list of all commands.
#	A `#' in the first column of a line indicates the beginning of a comment which continues to the end of the line
exit	Stop reading commands. When the top-level command interpreter encounters an exit command or end-of-file (EOF) it returns to its caller.
cd *directory*	Change working directory to *directory.*
pwd	Print the name of the working directory.
var [*name* [*value*]]	If both arguments are present, assign the *value* to the *name*d variable. If only the *name* argument is present, print the current value of that variable. If neither argument is present, print the value of all variables registered with the shell. Variables are registered in application database definitions using the *variable* keyword as described in Section 6.9 on page 102.
show [-*level*] [*task* ...]	Show information about specified tasks. If no *task* arguments are present, show information on all tasks. The *level* argument controls the amount of information printed. The default *level* is 0. The *task* arguments can be task names or task i.d. numbers.
system *command_string*	Send *command_string* to the system command interpreter for execution. This command is present only if some application database definition file contains `registrar(iocshSystemCommand)` and if the system provides a suitable command interpreter (vxWorks does not).
epicsEnvSet *name value*	Set environment variable *name* to the specified *value*.
epicsEnvShow [*name]*	If no *name* is specified the names and values of all environment variables will be shown. If a *name* is specified the value of that environment variable will be shown.
epicsParamShow	Show names and values of all EPICS configuration parameters.
iocLogInit	Initialize IOC logging.
epicsThreadSleep *sec*	Pause execution of IOC shell for *sec* seconds.

The `var` command is intended for simple applications such as setting the value of debugging flags. Applications which require more complex expression handling should use the *cexp* package.

A `spy` command to show periodic activity reports is available on RTEMS as part of the RTEMS_UTILS support module. The following changes must be made to add this command to an application.

- Add an RTEMS_UTILS entry to the application configure/RELEASE file.
- Add `spy.dbd` to the list of application dbd files and `rtemsutils` to the list of application libraries in the application Makefile.

18.2.6 ENVIRONMENT VARIABLES

The IOC shell uses the following environment variables to control its operation.

Variable	Description
IOCSH_PS1	Prompt string. Default is "epics> ".
IOCSH_HISTSIZE	Number of previous command lines to remember. If the IOCSH_HISTSIZE environment variable is not present the value of the HISTSIZE environment variable is used. In the absence of both environment variables, 10 command lines will be remembered.
TERM, INPUTRC	These and other environment variables are used by the readline and termcap libraries and are described in the documentation for those libraries.

18.3 IOC Shell Programming

The declarations described in this section are included in the `iocsh.h` header file.

18.3.1 Invoking the IOC shell

The prototypes for calling the IOC shell command interpreter are:

```
int iocsh(const char *pathname);
int iocshCmd(const char *cmd);
```

The pathname argument to the `iocsh` function is the name of the file from which commands are to be read. If the *pathname* argument is NULL, commands are read from the standard input and prompts are issued to the standard output. Commands are read until an `exit` command is encountered or until end-of-file is reached, at which point iocsh returns a value of 0. If the specified file can not be opened iocsh returns -1.

The IOC shell can be invoked from the vxWorks shell, either from within a vxWorks startup script or from vxWorks command-line interpreter, using

```
iocsh "script"
```

to read from an IOC shell script. It can also be invoked from the vxWorks command-line interpreter with no argument in which case the IOC shell takes over the duties of command-line interaction.

The `iocshCmd` function takes a single IOC shell command and executes it. The function may be called from any thread, but many of the commands are not necessarily thread-safe so this should only be used with care. The function is most useful to execute a single IOC shell command from a vxWorks startup script or command line, like this:

```
iocshCmd "iocsh command string"
```

The stdio stream redirection and environment variable expansion processes described above are performed on the string as part of the execution process.

18.3.2 Registering Commands

Commands must be registered before they can be recognized by the IOC shell. Registration is achieved by calling the registration function:

```
void iocshRegister(const iocshFuncDef *piocshFuncDef, iocshCallFunc func);
```

The first argument is a pointer to a data structure which describes the command and any arguments it may take. The second argument is a pointer to a function which will be called by iocsh when the corresponding command is encountered.

The command is described by the `iocshFuncDef` structure:

```
struct iocshFuncDef {
    const char *name;
    int nargs;
    const iocshArg * const *arg;
};
```

The name element is the name of the command. The arg element is a pointer to an array of pointers to structures each of which defines a single argument. The nargs element declares the number of entries in the array of pointers to the argument descriptions. If nargs is zero, arg can be NULL. The structures which define each of the arguments is:

```
struct iocshArg {
    const char *name;
    iocshArgType type;
}iocshArg;
```

The name element is used by the help command to print a synopsis for the command. The type element describes the type of the argument and takes one of the following values:

Type Specifier	Description
iocshArgInt	The argument will be converted to an integer value.
iocshArgDouble	The argument will be converted to a double-precision floating point value.
iocshArgString	The argument will be left as a string. The memory used to hold the string is ‘owned’ by iocsh and will be reused once the handler function returns.
iocshArgPersistentString	A copy of the argument will be made and a pointer to the copy will be passed to the handler. The called function can release this copy by using the pointer as an argument to free().
iocshArgPdbbase	The argument must be pdbbase.
iocshArgArgv	An arbitrary number of arguments is expected. Subsequent iocshArg structures will be ignored.

The `handler' function which is called when its corresponding command is recognized should be of the form:

```
void showCallFunc(const iocshArgBuf *args);
```

The argument to the handler function is a pointer to an array of unions. The number of elements in this array is equal to the number of arguments specified in the structure describing the command. The type and name of the union element which contains the argument value depends on the `type' element of the corresponding argument descriptor:

Type Specifier	Type	Union element
iocshArgInt	int	args[i].ival
iocshArgDouble	double	args[i].dval
iocshArgString iocshArgPersistentString	char *	args[i].sval
iocshArgPdbbase	void *	args[i].vval
iocshArgArgv	int char **	args[i].aval.ac args[i].aval.av

If an `iocshArgArgv` argument type is present it is often the first and only argument specified for the command. In this case, `args[0].aval.av[0]` will be the name of the command, `args[0].aval.av[1]` will be the first argument, and so on.

18.3.3 Registrar Command Registration

Commands are normally registered with the IOC shell in a registrar function. The application's database description file uses the `registrar` keyword to specify a function which will be called from the EPICS initialization code during the application startup process. This function then calls `iocshRegister` to register its commands with the iocsh.

The following code fragments shows how this can be performed for an example driver.

```
#include <iocsh.h>
#include <epicsExport.h>

/* drvXxx code, FuncDef and CallFunc definitions ... */

static void drvXxxRegistrar(void)
{
    iocshRegister(&drvXxxConfigureFuncDef, drvXxxConfigureCallFunc);
}
epicsExportRegistrar(drvXxxRegistrar);
```

To include this driver in an application a developer would then add

```
registrar(drvXxxRegistrar)
```

to an application database description file.

18.3.4 Automatic Command Registration

A C++ static constructor can also be used to register IOC shell commands before the EPICS application begins. The following example shows how the `epicsThreadSleep` command could be described and registered.

```
#include <iocsh.h>

static const iocshArg epicsThreadSleepArg0 = { "seconds",iocshArgDouble};
static const iocshArg *const epicsThreadSleepArgs[1] =
    {&epicsThreadSleepArg0};
static const iocshFuncDef epicsThreadSleepFuncDef =
    {"epicsThreadSleep",1,epicsThreadSleepArgs};
static void epicsThreadSleepCallFunc(const iocshArgBuf *args)
{
    epicsThreadSleep(args[0].dval);
}

static int doRegister(void)
{
    iocshRegister(epicsThreadSleepFuncDef, epicsThreadSleepCallFunc);
    return 1;
}
static int done = doRegister();
```

Chapter 19: libCom

This chapter and the next describe the facilities provided in `<base>/src/libCom`. This chapter describes facilities which are platform independent. The next chapter describes facilities which have different implementations on different platforms.

19.1 bucketLib

`bucketLib.h` describes a hash facility for integers, pointers, and strings. It is used by the Channel Access Server. It is currently undocumented.

19.2 calc

`postfix.h` defines several macros and the routines used by the calculation record type calcRecord, access security, and other code, to compile and evaluate mathematical expressions. The syntax of the infix expressions accepted is described in Section 19.2.1 on page 256 below.

```
long postfix(const char *psrc, char *ppostfix, short *perror);
long calcArgUsage(const char *ppostfix, unsigned long *pinputs,
      unsigned long *pstores);
const char * calcErrorStr(short error);
long calcPerform(double *parg, double *presult, const char *ppostfix);
```

The postfix() routine converts an expression from infix to postfix notation. It is the callers's responsibility to make sure that *ppostfix* points to sufficient storage to hold the postfix expression; the macro `INFIX_TO_POSTFIX_SIZE(n)` can be used to calculate an appropriate buffer from the length of the infix string. There is no longer a maximum length to the input expression that can be accepted, although there are internal limits to the complexity of the expressions that can be converted and evaluated. If postfix() returns a non-zero value it will have placed an error code at the location pointed to by *perror*. The error codes used are defined in `postfix.h` as a series of macros with names starting `CALC_ERR_`, but a string representation of the error code is more useful and can be obtained by passing the value to the calcErrorStr() routine, which returns a static error message string explaining the error.

Software using the calc subsystem may need to know what expression arguments are used and/or modified by a particular expression. It can now discover this from the postfix string by calling calcArgUsage(), which takes two pointers *pinputs* and *pstores* to a pair of unsigned long bitmaps which return that information to the caller (passing a NULL value for either of these pointers is legal). The least signficant bit (bit 0) of the bitmap at **pinputs* will be set if the expression depends on the argument A, and so on through bit 11 for the argument L. Similarly, bit 0 of the bitmap at **pstores* will be set if the expression assigns a value to the argument A. An argument that is not used until after a value has been assigned to it will not be set in the *pinputs* bitmap, thus the bits can be used to determine whether a value needs to be supplied for their associated argument or not (for the purposes of evaluating the expression at least; other considerations make it desirable to still fetch all input values in the case of the CALC record). The return value from calcArgUsage() will be non-zero if the *ppostfix* expression was illegal, otherwise 0.

The postfix expression is evaluated by calling the calcPerform() routine, which returns the status values 0 for OK, or non-zero if an error is discovered during the evaluation process.

The arguments to calcPerform() are:

parg - Pointer to an array of double values for the arguments A-L that can appear in the expression. Note that the argument values may be modified if the expression uses the assignment operator.
presult - Where to put the calculated result, which may be a NaN or Infinity.
ppostfix - The postfix expression created by postfix().

19.2.1 Infix Expression Syntax

The infix expressions that can be used are very similar to the C expression syntax, but with some additions and subtle differences in operator meaning and precedence. The string may contain a series of expressions separated by a semi-colon character `';'` any one of which may actually provide the calculation result; however all of the other expressions included must assign their result to a variable. All alphabetic elements described below are case independent, so upper and lower case letters may be used and mixed in the variable and function names as desired. Spaces may be used anywhere within an expression except between the characters that make up a single expression element.

19.2.1.1 Numeric Literals

The simplest expression element is a numeric literal, any (positive) number expressed using the standard floating point syntax that can be stored as a double precision value. This now includes the values `Infinity` and `NaN` (not a number). Note that negative numbers are actually encoded as a positive literal to which the unary negate operator is applied.

Examples:

```
1
2.718281828459
Inf
```

19.2.1.2 Constants

There are three trigonometric constants available to any expression which return a value:

- `pi` returns the value of the mathematical constant π.
- `D2R` evaluates to π/180 which, when used as a multiplier, converts an angle from degrees to radians.
- `R2D` evaluates to 180/π which as a multiplier converts an angle from radians to degrees.

19.2.1.3 Variables

Variables are used to provide inputs to an expression, and are named using the single letters `A` through `L` inclusive or now the keyword `VAL` which refers to the previous result of this calculation. The software that makes use of the expression evaluation code should document how the individual variables are given values; for the calc record type the input links INPA through INPL can be used to obtain these from other record fields, and `VAL` refers to the the VAL field (which can be overwritten from outside the record via Channel Access or a database link).

19.2.1.4 Variable Assignment Operator

Recently added is the ability to assign the result of a sub-expression to any of the single letter variables, which can then be used in another sub-expression. The variable assignment operator is the character pair `:=` and must immediately follow the name of the variable to receive the expression value. Since the infix string must return exactly one value, every expression string must have exactly one sub-expression that is not an assignment, which can appear anywhere in the string. Sub-expressions within the string are separated by a semi-colon character.

Examples:

```
B; B:=A
i:=i+1; a*sin(i*D2R)
```

19.2.1.5 Arithmetic Operators

The usual binary arithmetic operators are provided: `+ - *` and `/` with their usual relative precedence and left-to-right associativity, and `-` may also be used as a unary negate operator where it has a higher precedence and associates from right to left. There is no unary plus operator, so numeric literals cannot begin with a + sign.

Examples:

```
a*b + c
a/-4 - b
```

Three other binary operators are also provided: `%` is the integer modulo operator, and the synonymous operators `**` and `^` raise their left operand to the power of the right operand. `%` has the same precedence and associativity as `*` and `/`, while the power operators associate left-to-right and have a precedence in between `*` and unary minus.

Examples:

```
e:=a%10; d:=a/10%10; c:=a/100%10; b:=a/1000%10; b*4096+c*256+d*16+e
sqrt(a**2 + b**2)
```

19.2.1.6 Algebraic Functions

Various algebraic functions are available which take parameters inside parentheses. The parameter seperator is a comma.

- Absolute value: `abs(a)`
- Exponential e^a: `exp(a)`
- Logarithm, base 10: `log(a)`
- Natural logarithm (base e): `ln(a)` *or* `loge(a)`
- *n* parameter maximum value: `max(a, b, ...)`
- *n* parameter minimum value: `min(a, b, ...)`
- Square root: `sqr(a)` *or* `sqrt(a)`

19.2.1.7 Trigonometric Functions

Standard circular trigonometric functions, with angles expressed in radians:

- Sine: `sin(a)`
- Cosine: `cos(a)`
- Tangent: `tan(a)`
- Arcsine: `asin(a)`
- Arccosine: `acos(a)`
- Arctangent: `atan(a)`
- 2 parameter arctangent: `atan2(a, b)` — *Note that these arguments are the reverse of the ANSI C function, so while C would return* arctan(a/b) *the calc expression engine returns* arctan(b/a)

19.2.1.8 Hyperbolic Trigonometry

The basic hyperbolic functions are provided, but no inverse functions (which are not provided by the ANSI C math library either).

- Hyperbolic sine: `sinh(a)`
- Hyperbolic cosine: `cosh(a)`
- Hyperbolic tangent: `tanh(a)`

19.2.1.9 Numeric Functions

The numeric functions perform operations related to the floating point numeric representation and truncation or rounding.

- Round up to next integer: `ceil(a)`
- Round down to next integer: `floor(a)`
- Round to nearest integer: `nint(a)`
- Test for infinite result: `isinf(a)`
- Test for any non-numeric values: `isnan(a, ...)`
- Test for all finite, numeric values: `finite(a, ...)`
- Random number between 0 and 1: `rndm`

19.2.1.10 Boolean Operators

These operators regard their arguments as true or false, where 0.0 is false and any other value is true.

- Boolean and: `a && b`
- Boolean or: `a || b`
- Boolean not: `!a`

19.2.1.11 Bitwise Operators

The bitwise operators convert their arguments to an integer (by truncation), perform the appropriate bitwise operation and convert back to a floating point value. Note that unlike in C, `^` is *not* a bitwise exclusive-or operator.

- Bitwise and: `a & b` *or* `a and b`
- Bitwise or: `a | b` *or* `a or b`
- Bitwise exclusive or: `a xor b`
- Bitwise not (ones complement): `~a` *or* `not a`
- Bitwise left shift: `a << b`
- Bitwise right shift: `a >> b`

19.2.1.12 Relational Operators

Standard numeric comparisons between two values:

- Less than: `a < b`
- Less than or equal to: `a <= b`
- Equal to: `a = b` *or* `a == b`
- Greater than or equal to: `a >= b`
- Greater than: `a > b`
- Not equal to: `a != b` *or* `a # b`

19.2.1.13 Conditional Operator

Expressions can use the C conditional operator, which has a lower precedence than all of the other operators except for the assignment operator.

- *condition* `?` *true result* `:` *false result*

Example:

```
a < 360 ? a+1 : 0
```

19.2.1.14 Parentheses

Sub-expressions can be placed within parentheses to override operator precence rules. Parentheses can be nested to any depth, but the intermediate value stack used by the expression evaluation engine is limited to 80 results (which would require an expression at least 321 characters long to reach).

19.3 cppStd

This subdirectory of libCom is intended for facilities such as class and function templates that implement parts of the ISO standard C++ library where such facilities are not available or not efficient on all the target platforms on which EPICS is supported. EPICS does not make use of the C++ container templates because the large number of memory allocation and deletion operations that these use causes memory pool fragmentation on some platforms, threatening the lifetime of an individual IOC.

19.3.1 epicsAlgorithm

`epicsAlgorithm.h` contains a few templates that are also available in the C++ standard header `algorithm`, but are provided here in a much smaller file – `algorithm` contains many templates for sorting and searching. If all you need from there is std::min(), std::max() and/or std::swap() your code will compile faster if you include `epicsAlgorithm.h` and use epicsMin(), epicsMax() and epicsSwap() instead.

template <class T>	Meaning
const T& epicsMin(const T& *a*, const T& *b*)	Returns the smaller of *a* or *b* compared using *a*<*b*. Handles NaNs correctly.
const T& epicsMax(const T& *a*, const T& *b*)	Returns the larger of *a* or *b* compared using *a*<*b*. Handles NaNa correctly.
void epicsSwap(T& *a*, T& *b*)	Swaps the values of *a* and *b*; T must have a copy-constructor and operator=.

19.4 epicsExit

```
void epicsExit(int status);
void epicsExitCallAtExits(void);
void epicsAtExit(void (*epicsExitFunc)(void *arg), void *arg);
void epicsExitCallAtThreadExits(void);
int  epicsAtThreadExit(void (*epicsExitFunc)(void *arg), void *arg);
```

This is an extended replacement for the Posix `exit` and `atexit` routines, which also provides a pointer argument to pass to the exit handlers. This facility was created because of problems on vxWorks and windows with the implementation of `atexit`, i.e. neither of these systems implement `exit` and `atexit` according to the POSIX standard.

Method	Meaning
epicsExit	This calls epicsExitCallAtExits and then passes status on to exit.
epicsExitCallAtExits	This calls each of the functions registered by prior calls to epicsAtExit, in reverse order of their registration. Most applications will not call this routine directly.

Method	Meaning
epicsAtExit	Register a function and an associated context parameter, to be called with the given parameter when epicsExitCallAtExits is invoked.
epicsExitCallAtThreadExits	This calls each of the functions that were registered by the current thread calling epicsAtThreadExit, in reverse order of the function registration. This routine is called automatically when an epicsThread's main entry method returns, but will not be run if the thread is stopped by other means.
epicsAtThreadExit	Register a function and an associated context parameter. The function will be called with the given parameter when epicsExitCallAtThreadExits is invoked by the current thread.

19.5 cvtFast

`cvtFast.h` provides routines for converting various numeric types into an ascii string. They offer a combination of speed and convenience not available with sprintf().

```
/* These functions return the number of ASCII characters generated */
int cvtFloatToString(float value, char *pstr, unsigned short precision);
int cvtDoubleToString(double value, char *pstr, unsigned short prec);
int cvtFloatToExpString(float value, char *pstr, unsigned short prec);
int cvtDoubleToExpString(double value, char *pstr, unsigned short prec);
int cvtFloatToCompactString(float value, char *pstr, unsigned short prec);
int cvtDoubleToCompactString(double value, char *pstr, unsigned short prec);
int cvtCharToString(char value, char *pstring);
int cvtUcharToString(unsigned char value, char *pstr);
int cvtShortToString(short value, char *pstr);
int cvtUshortToString(unsigned short value, char *pstr);
int cvtLongToString(epicsInt32 value, char *pstr);
int cvtUlongToString(epicsUInt32 value, char *pstr);
int cvtLongToHexString(epicsInt32 value, char *pstr);
int cvtLongToOctalString(epicsInt32 value, char *pstr);
unsigned long cvtBitsToUlong(
        epicsUInt32 src,
        unsigned bitFieldOffset,
        unsigned bitFieldLength);
unsigned long cvtUlongToBits(
        epicsUInt32 src,
        epicsUInt32 dest,
        unsigned bitFieldOffset,
        unsigned bitFieldLength);
```

19.6 cxxTemplates

This directory contains the following C++ template headers:

- `resourceLib.h` - A C++ hash facility that implements the same functionality as bucketLib

- `tsBTree.h` - Binary tree.
- `tsDLList.h` - Double Linked List
- `tsFreeList.h` - Free List for efficient new/delete
- `tsMinMax.h` - min and max.
- `tsSLList.h` - Single Linked List

Currently these are only being used by Channel Access Clients and the portable Channel Access Server. It has not been decided if any of these will remain in libCom.

19.7 dbmf

`dbmf.h` (Database Macro/Free) describes a facility that prevents memory fragmentation when memory is allocated and then freed a short time later.

Routines within iocCore like dbLoadDatabase() have the following attributes:

- They repeatedly call malloc() followed soon afterwards by a call to free() the temporarily allocated storage.
- Between those calls to malloc() and free(), an additional call to malloc() is made that does NOT have an associated free().

In some environments, e.g. vxWorks, this behavior causes severe memory fragmentation.

The dbmf facility stops the memory fragmentation. It should NOT be used by code that allocates storage and then keeps it for a considerable period of time before releasing. Such code can use the freeList library described below.

```
int dbmfInit(size_t size, int chunkItems);
void *dbmfMalloc(size_t bytes);
void dbmfFree(void* bytes);
void dbmfFreeChunks(void);
int dbmfShow(int level);
```

Routine	Meaning
dbmfInit()	Initialize the facility. Each time malloc() must be called `size*chunkItems` bytes are allocated. `size` is the maximum size request from dbmfMalloc() that will be allocated from the dbmf pool. If dbmfInit() was not called before one of the other routines then it is automatically called with `size=64` and `chuckItems=10`.
dbmfMalloc()	Allocate memory. If `bytes` is > `size` then malloc() is used to allocate the memory.
dbmfFree()	Free the memory allocated by dbmfMalloc().
dbmfFreeChunks()	Free all chunks that have contain only free items.
dbmfShow()	Show the status of the dbmf memory pool.

19.8 ellLib

`ellLib.h` describes a double linked list library. It provides functionality similar to the vxWorks lstLib library. See the vxWorks documentation for details. There is an ellXXX() routine to replace most vxWorks lstXXX() routines.

```
typedef struct ELLNODE {
  struct ELLNODE  *next;
  struct ELLNODE  *previous;
}ELLNODE;

typedef struct ELLLIST {
  ELLNODE  node;
  int   count;
void ellInit (ELLLIST *pList);
int ellCount (ELLLIST *pList);
ELLNODE *ellFirst (ELLLIST *pList);
ELLNODE *ellLast (ELLLIST *pList);
ELLNODE *ellNext (ELLNODE *pNode);
ELLNODE *ellPrevious (ELLNODE *pNode);
void ellAdd (ELLLIST *pList, ELLNODE *pNode);
void ellConcat (ELLLIST *pDstList, ELLLIST *pAddList);
void ellDelete (ELLLIST *pList, ELLNODE *pNode);
void ellExtract (ELLLIST *pSrcList, ELLNODE *pStartNode,
    ELLNODE *pEndNode, ELLLIST *pDstList);
ELLNODE *ellGet (ELLLIST *pList);
void ellInsert (ELLLIST *plist, ELLNODE *pPrev, ELLNODE *pNode);
ELLNODE *ellNth (ELLLIST *pList, int nodeNum);
ELLNODE *ellNStep (ELLNODE *pNode, int nStep);
int ellFind (ELLLIST *pList, ELLNODE *pNode);
void ellFree (ELLLIST *pList);
void ellVerify (ELLLIST *pList);
```

19.9 epicsRingBytes

`epicsRingBytes.h` contains

```
epicsRingBytesId epicsRingBytesCreate(int nbytes);
void epicsRingBytesDelete(epicsRingBytesId id);
int epicsRingBytesGet(epicsRingBytesId id, char *value,int nbytes);
int epicsRingBytesPut(epicsRingBytesId id, char *value,int nbytes);
void epicsRingBytesFlush(epicsRingBytesId id);
int epicsRingBytesFreeBytes(epicsRingBytesId id);
int epicsRingBytesUsedBytes(epicsRingBytesId id);
int epicsRingBytesSize(epicsRingBytesId id);
int epicsRingBytesIsEmpty(epicsRingBytesId id);
int epicsRingBytesIsFull(epicsRingBytesId id);
```

Method	Meaning
epicsRingBytesCreate()	Create a new ring buffer of size *nbytes*. The returned epicsRingBytesId is passed to the other ring methods.
epicsRingBytesDelete()	Delete the ring buffer and free any associated memory.
epicsRingBytesGet()	Move up to *nbytes* from the ring buffer to *value*. The number of bytes actually moved is returned.
epicsRingBytesPut()	Move up to *nbytes* from *value* to the ring buffer. The number of bytes actually moved is returned.
epicsRingBytesFlush()	Make the ring buffer empty.
epicsRingBytesFreeBytes()	Return the number of free bytes in the ring buffer.
epicsRingBytesUsedBytes()	Return the number of bytes currently stored in the ring buffer.
epicsRingBytesSize()	Return the size of the ring buffer, i.e., *nbytes* specified in the call to epicsRingBytesCreate().
epicsRingBytesIsEmpty()	Return (true, false) if the ring buffer is currently empty.
epicsRingBytesIsFull()	Return (true, false) if the ring buffer is currently empty.

epicsRingBytes has the following properties:

- For a ring buffer with a single writer it is not necessary to lock epicsRingBytesPut() calls.
- For a ring buffer with a single reader it is not necessary to lock epicsRingBytesGet() calls.
- epicsRingBytesFlush() should only be used when both gets and puts are locked out.
- Readers and writers must be prepared to deal with transfers smaller than the requested size.

19.10 epicsRingPointer

`epicsRingPointer.h` describes a C++ and a C facility for a commonly used type of ring buffer.

19.10.1 C++ Interface

EpicsRingPointer provides methods for creating and using ring buffers (first in first out circular buffers) that store pointers. It is designed so that a writer thread and reader thread can access the ring simultaneously without requiring mutual exclusion.

```
template <class T>
class epicsRingPointer {
public:
    epicsRingPointer(int size);
    ~epicsRingPointer();
    bool push(T *p);
    T* pop();
    void flush();
    int getFree() const;
    int getUsed() const;
    int getSize() const;
```

```
    bool isEmpty() const;
    bool isFull() const;

private: // Prevent compiler-generated member functions
    // default constructor, copy constructor, assignment operator
    epicsRingPointer();
    epicsRingPointer(const epicsRingPointer &);
    epicsRingPointer& operator=(const epicsRingPointer &);

private: // Data
    ...
};
```

An epicsRingPointer cannot be assigned to, copy-constructed, or constructed without giving the *size* argument. The C++ compiler will object to some of the statements below:

```
epicsRingPointer rp0();   // Error: default constructor is private
epicsRingPointer rp1(10); // OK
epicsRingPointer rp2(t1); // Error: copy constructor is private
epicsRingPointer *prp;    // OK, pointer
*prp = rp1;               // Error: assignment operator is private
prp = &rp1;               // OK, pointer assignment and address-of
```

Method	Meaning
epicsRingPointer()	Constructor. The size is the maximum number of elements (pointers) that can be stored in the ring.
~epicsRingPointer()	Destructor.
push()	Push a new entry on the ring. It returns (false,true) is (failure, success). Failure means the ring was full. If a single writer is present it does not have to use a lock while performing the push. If multiple writers are present they must use a common lock while issuing the push.
pop()	Take a element off the ring. It returns 0 (null) if the ring was empty. If a single reader is present it does not have to lock while issuing the pop. If multiple readers are present they must use a common lock while issuing the pop.
flush()	Remove all elements from the ring. If this operation is performed then all access to the ring should be locked.
getFree()	Return the amount of empty space in the ring, i.e. how many additional elements it can hold.
getUsed()	Return the number of elements stored on the ring
getSize()	Return the size of the ring, i.e. the value of *size* specified when the ring was created.
isEmpty()	Returns true if the ring is empty, else false.
isFull()	Returns true if the ring is full, else false.

19.10.2 C interface

```
typedef void *epicsRingPointerId;
    epicsRingPointerId epicsRingPointerCreate(int size);
```

```
    void epicsRingPointerDelete(epicsRingPointerId id);
    /*epicsRingPointerPop returns 0 if the ring was empty */
    void * epicsRingPointerPop(epicsRingPointerId id) ;
    /*epicsRingPointerPush returns (0,1) if p (was not, was) put on ring*/
    int epicsRingPointerPush(epicsRingPointerId id,void *p);
    void epicsRingPointerFlush(epicsRingPointerId id);
    int epicsRingPointerGetFree(epicsRingPointerId id);
    int epicsRingPointerGetUsed(epicsRingPointerId id);
    int epicsRingPointerGetSize(epicsRingPointerId id);
    int epicsRingPointerIsEmpty(epicsRingPointerId id);
    int epicsRingPointerIsFull(epicsRingPointerId id);
```

Each C function corresponds to one of the C++ methods.

19.11 epicsTimer

`epicsTimer.h` describes a C++ and a C timer facility.

19.11.1 C++ Interface

19.11.1.1 epicsTimerNotify and epicsTimer

```
class epicsTimerNotify {
public:
    enum restart_t { noRestart, restart };
    class expireStatus {
    public:
        expireStatus ( restart_t );
        expireStatus ( restart_t, const double &expireDelaySec );
        bool restart () const;
        double expirationDelay () const;
    private:
        double delay;
    };
    virtual ~epicsTimerNotify ();
    // return noRestart OR return expireStatus ( restart, 30.0 /* sec */ );
    virtual expireStatus expire ( const epicsTime & currentTime ) = 0;
    virtual void show ( unsigned int level ) const;
};

class epicsTimer {
public:
    virtual void destroy () = 0; // requires existence of timer queue
    virtual void start ( epicsTimerNotify &, const epicsTime & ) = 0;
    virtual void start ( epicsTimerNotify &, double delaySeconds ) = 0;
    virtual void cancel () = 0;
    struct expireInfo {
        expireInfo ( bool active, const epicsTime & expireTime );
        bool active;
        epicsTime expireTime;
```

```
    };
    virtual expireInfo getExpireInfo () const = 0;
    double getExpireDelay ();
    virtual void show ( unsigned int level ) const = 0;
protected:
    virtual ~epicsTimer () = 0; // use destroy
};
```

Method	Meaning
epicsTimerNotify expire()	Code using an epicsTimer must include a class that inherits from epicsTimerNotify. The derived class must implement the method expire(), which is called by the epicsTimer when the associated timer expires. epicsTimerNotify defines a class expireStatus which makes it easy to implement both one shot and periodic timers. A one-shot expire() returns with the statement: `return(noRestart);` A periodic timer returns with a statement like: `return(restart,10.0);` where is second argument is the delay until the next callback.
epicsTimer	epicsTimer is an abstract base class. An epics timer can only be created by calling `createTimer`, which is a method of `epicsTimerQueue`.
destroy	This is provided instead of a destructor. This will automatically call cancel before freeing all resources used by the timer.
start()	Starts the timer to expire either at the specified time or the specified number of seconds in the future. If the timer is already active when start is called, it is first canceled.
cancel()	If the timer is scheduled, cancel it. If it is not scheduled do nothing. Note that if the expire() method is already running, this call delays until the expire() completes.
getExpireInfo	Get `expireInfo`, which says if timer is active and if so when it expires.
getExpireDelay()	Return the number of seconds until the timer will expire. If the timer is not active it returns DBL_MAX
show()	Display info about object.

19.11.1.2 epicsTimerQueue

```
class epicsTimerQueue {
public:
    virtual epicsTimer & createTimer () = 0;
    virtual void show ( unsigned int level ) const = 0;
protected:
    virtual ~epicsTimerQueue () = 0;
};
```

Method	Meaning
createTimer()	This is a "factory" method to create timers which use this queue.
show()	Display info about object

19.11.1.3 epicsTimerQueueActive

```
class epicsTimerQueueActive : public epicsTimerQueue {
public:
    static epicsTimerQueueActive & allocate (
        bool okToShare, unsigned threadPriority = epicsThreadPriorityMin + 10 );
    virtual void release () = 0;
protected:
    virtual ~epicsTimerQueueActive () = 0;
};
```

Method	Meaning
allocate()	This is a "factory" method to create a timer queue. If okToShare is (true,false) then a (shared, separate) thread will manage the timer requests.If the okToShare constructor parameter is true then if a timer queue is already running at the specified priority then it will be referenced for shared use by the application, and an independent timer queue will not be created. Editorial note: It is useful for two independent timer queues to run at the same priority if there are multiple processors, or if there is an application with well behaved timer expire functions that needs to be independent of applications with computationally intensive, mutex locking, or IO blocking timer expire functions.
release()	Release the queue, i.e. the calling facility will no longer use the queue. The caller MUST ensure that it does not own any active timers. When the last facility using the queue calls release, all resources used by the queue are freed.

19.11.1.4 epicsTimerQueueNotify and epicsTimerQueuePassive

These two classes manage a timer queue for single threaded applications. Since it is single threaded, the application is responsible for requesting that the queue be processed.

```
class epicsTimerQueueNotify {
public:
    // called when a new timer is inserted into the queue and the
    // delay to the next expire has changed
    virtual void reschedule () = 0;
    // if there is a quantum in the scheduling of timer intervals
    // return this quantum in seconds. If unknown then return zero.
    virtual double quantum () = 0;
 protected:
    virtual ~epicsTimerQueueNotify () = 0;
   };

class epicsTimerQueuePassive {
public:
    static epicsTimerQueuePassive & create ( epicsTimerQueueNotify & );
    virtual ~epicsTimerQueuePassive () = 0;
    // process returns the delay to the next expire
    virtual double process (const epicsTime & currentTime) = 0;
};
```

Method	Meaning
epicsTimerQueueNotify reschedule()	The virtual function epicsTimerQueueNotify::reschedule() is called when the delay to the next timer to expire on the timer queue changes.
epicsTimerQueueNotify quantum	The virtual function epicsTimerQueueNotify::quantum() returns the timer expire interval scheduling quantum in seconds. This allows different types of timer queues to use application specific timer expire delay scheduling policies. The implementation of epicsTimerQueueActive employs epicsThreadSleep() for this purpose, and therefore epicsTimerQueueActive::quantum() returns the returned value from epicsThreadSleepQuantum(). Other types of timer queues might choose to schedule timer expiration using specialized hardware interrupts. In this case epicsTimerQueueNotify::quantum() might return a value reflecting the precision of a hardware timer. If unknown, then epicsTimerQueueNotify::quantum() should return zero.
epicsTimerQueuePassive	epicsTimerQueuePassive is an abstract base class so cannot be instantiated directly, but contains a static member function to create a concrete passive timer queue object of a (hidden) derived class.
create()	A "factory" method to create a non-threaded timer queue. The calling software also passes an object derived from epicsTimerQueueNotify to receive reschedule() callbacks.
~epicsTimerQueuePassive()	Destructor. The caller MUST ensure that it does not own any active timers, i.e. it must cancel any active timers before deleting the epicsTimerQueuePassive object.
process()	This calls expire() for all timers that have expired. The facility that creates the queue MUST call this. It returns the delay until the next timer will expire.

19.11.2 C Interface

```
typedef struct epicsTimerForC * epicsTimerId;
typedef void ( *epicsTimerCallback ) ( void *pPrivate );

/* thread managed timer queue */
typedef struct epicsTimerQueueActiveForC * epicsTimerQueueId;
epicsTimerQueueId epicsTimerQueueAllocate(
    int okToShare, unsigned int threadPriority );
void epicsTimerQueueRelease ( epicsTimerQueueId );
epicsTimerId epicsTimerQueueCreateTimer ( epicsTimerQueueId queueid,
        epicsTimerCallback callback, void *arg );
void epicsTimerQueueDestroyTimer ( epicsTimerQueueId queueid, epicsTimerId id );
void epicsTimerQueueShow ( epicsTimerQueueId id, unsigned int level );

/* passive timer queue */
typedef struct epicsTimerQueuePassiveForC * epicsTimerQueuePassiveId;
typedef void ( *epicsTimerQueueNotifyReschedule ) ( void *pPrivate );
typedef double ( * epicsTimerQueueNotifyQuantum ) ( void * pPrivate );
epicsTimerQueuePassiveId epicsTimerQueuePassiveCreate(
    epicsTimerQueueNotifyReschedule,epicsTimerQueueNotifyQuantum,
    void *pPrivate );
void epicsTimerQueuePassiveDestroy ( epicsTimerQueuePassiveId );
epicsTimerId epicsTimerQueuePassiveCreateTimer (epicsTimerQueuePassiveId queueid,
     epicsTimerCallback pCallback, void *pArg );
void epicsTimerQueuePassiveDestroyTimer (
    epicsTimerQueuePassiveId queueid,epicsTimerId id );
```

```
double epicsTimerQueuePassiveProcess ( epicsTimerQueuePassiveId );
void epicsTimerQueuePassiveShow(epicsTimerQueuePassiveId id,unsigned int level);
/* timer */
void epicsTimerStartTime(epicsTimerId id, const epicsTimeStamp *pTime);
void epicsTimerStartDelay(epicsTimerId id, double delaySeconds);
void epicsTimerCancel ( epicsTimerId id );
double epicsTimerGetExpireDelay ( epicsTimerId id );
void epicsTimerShow ( epicsTimerId id, unsigned int level );
```

The C interface provides most of the facilities as the C++ interface. It does not support the periodic timer features. The typedefs epicsTimerQueueNotifyReschedule and epicsTimerQueueNotifyQuantum are the "C" interface equivalents to epicsTimerQueueNotify:: reschedule() and epicsTimerQueueNotify::quantum().

19.11.3 Example

This example allocates a timer queue and two objects which have a timer that uses the queue. Each object is requested to schedule itself. The expire() callback just prints the name of the object. After scheduling each object the main thread just sleeps long enough for each expire to occur and then just returns after releasing the queue.

```
#include <stdio.h>
#include "epicsTimer.h"

class something : public epicsTimerNotify {
public:
    something(const char* nm,epicsTimerQueueActive &queue)
    : name(nm), timer(queue.createTimer()) {}
    virtual ~something() { timer.destroy();}
    void start(double delay) {timer.start(*this,delay);}
    virtual expireStatus expire(const epicsTime & currentTime) {
        printf("%s\n",name);
        currentTime.show(1);
        return(noRestart);
    }
private:
    const char* name;
    epicsTimer &timer;
};

void epicsTimerExample()
{
    epicsTimerQueueActive &queue = epicsTimerQueueActive::allocate(true);
    {
        something first("first",queue);
        something second("second",queue);

        first.start(1.0);
        second.start(1.5);
        epicsThreadSleep(2.0);
    }
    queue.release();
}
```

19.11.4 C Example

This example shows how C programs can use EPICS timers.

```
#include <stdio.h>
#include <epicsTimer.h>
#include <epicsThread.h>

static void
handler (void *arg)
{
    printf ("%s timer tripped.\n", (char *)arg);
}

int
main(int argc, char **argv)
{
    epicsTimerQueueId timerQueue;
    epicsTimerId first, second;

    /*
     * Create the queue of timer requests
     */
    timerQueue = epicsTimerQueueAllocate(1,epicsThreadPriorityScanHigh);

    /*
     * Create the timers
     */
    first = epicsTimerQueueCreateTimer(timerQueue, handler, "First");
    second = epicsTimerQueueCreateTimer(timerQueue, handler, "Second");

    /*
     * Start a timer
     */
    printf("First timer should trip in 3 seconds.\n");
    epicsTimerStartDelay(first, 3.0);
    epicsThreadSleep(5.0);
    printf("First timer should have tripped by now.\n");

    /*
     * Try starting and then cancelling a request
     */
    printf("Second timer should trip in 3 seconds.\n");
    epicsTimerStartDelay(first, 3.0);
    epicsTimerStartDelay(second, 3.0);
    epicsThreadSleep(1.0);
    epicsTimerCancel(first);
    epicsThreadSleep(5.0);
    printf("Second timer should have tripped, first timer should not have
tripped.\n");

    /*
     * Clean up a single timer
     */
```

```
    epicsTimerQueueDestroyTimer(timerQueue, first);

    /*
     *  Clean up an entire queue of timers
     */
    epicsTimerQueueRelease(timerQueue);
    return 0;
```

19.12 fdmgr

File Descriptor Manager. `fdManager.h` describes a C++ implementation. `fdmgr.h` describes a C implementation. Neither is currently documented.

19.13 freeList

`freeList.h` describes routines to allocate and free fixed size memory elements. Free elements are maintained on a free list rather then being returned to the heap via calls to free. When it is necessary to call malloc(), memory is allocated in multiples of the element size.

```
void freeListInitPvt(void **ppvt, int size, int nmalloc);
void *freeListCalloc(void *pvt);
void *freeListMalloc(void *pvt);
void freeListFree(void *pvt, void*pmem);
void freeListCleanup(void *pvt);
size_t freeListItemsAvail(void *pvt);
```

where

pvt - For internal use by the freelist library. Caller must provide storage for a "void *pvt"
size - Size in bytes of each element. Note that all elements must be same size
nmalloc - Number of elements to allocate when regular malloc() must be called.

19.14 gpHash

`gpHash.h` describes a general purpose hash table for character strings. The hash table contains *tableSize* entries. Each entry is a list of members that hash to the same value. The user can maintain separate directories which share the same table by having a different *pvt* value for each directory.

```
typedef struct{
    ELLNODE     node;
    const char  *name;          /*address of name placed in directory*/
    void        *pvtid;         /*private name for subsystem user*/
    void        *userPvt;       /*private for user*/
} GPHENTRY;

/*tableSize must be power of 2 in range 256 to 65536*/
void gphInitPvt(void **ppvt,int tableSize);
```

```
GPHENTRY *gphFind(void *pvt,const char *name,void *pvtid);
GPHENTRY *gphAdd(void *pvt,const char *name,void *pvtid);
void gphDelete(void *pvt,const char *name,void *pvtid);
void gphFreeMem(void *pvt);
void gphDump(void *pvt);
void gphDumpFP(FILE *fp,void *pvt);
```

where

pvt - For internal use by the gpHash library. Caller must provide storage for a "void *pvt"
name - The character string that will be hashed and added to table.
pvtid - The name plus value of this pointer constitute a unique entry.

19.15 logClient

Together with the program iocLogServer this provides generic support for logging text messages from an IOC or other program to a file on the log server host machine.

A log client runs on the IOC. It accepts string messages and forwards them over a TCP connection to its designated log server (normally running on a host machine).

A log server accepts connections from multiple clients and writes the messages it receives into a rotating file. A log server program ('iocLogServer') is also part of EPICS base.

Configuration of the iocLogServer, as well as the standard iocLogClient that internally uses this library, are described in Section 10.7 on page 165.

The header file logClient.h exports the following types and routines:

```
typedef void *logClientId;
```

An abstract data type, representing a log client.

```
logClientId logClientCreate (
      struct in_addr server_addr, unsigned short server_port);
```

Create a new log client. Will block the calling task for a maximum of 2 seconds trying to connect to a server with the given ip address and port. If a connection cannot be established, an error message is printed on the console, but the log client will keep trying to connect in the background. This is done by a background task, that will also periodically (every 5 seconds) flush pending messages out to the server.

```
void logClientSend (logClientId id, const char *message);
```

Send the given message to the given log client. Messages are not immediately sent to the log server. Instead they are sent whenever the cache overflows, or logClientFlush() is called.

```
void logClientFlush (logClientId id);
```

Immediately send all outstanding messages to the server.

```
void logClientShow (logClientId id, unsigned level);
```

Print information about the log clients internal state to stdout.

For backward compatibility with older versions of the logClient library, the header file also includes iocLog.h, which exports the definitions for the standard iocLogClient for error logging. See Chapter 10.7.2.

Also for backward compatibility, the following deprecated routines are exported.

```
logClientId logClientInit (void);
```

Create a log client that uses the standard ioc log client environment variables (EPICS_IOC_LOG_INET and EPICS_IOC_LOG_PORT) as input to logClientCreate and also registers the log client with the errlog task using errlogAddListener.

```
void logClientSendMessage (logClientId id, const char *message);
```

Check the global variable iocLogDisable before calling logClientSend.

19.16 macLib

`macLib.h` describes a general purpose macro substitution library. It is used for all macro substitution in base.

```
long macCreateHandle(
    MAC_HANDLE  **handle,       /* address of variable to receive pointer */
                                /* to new macro substitution context */
    char        *pairs[]        /* pointer to NULL-terminated array of */
                                /* {name,value} pair strings; a NULL */
                                /* value implies undefined; a NULL */
                                /* argument implies no macros */
);

void macSuppressWarning(
    MAC_HANDLE  *handle,        /* opaque handle */
    int         falseTrue       /*0 means ussue, 1 means suppress*/
);

/*following returns #chars copied, <0 if any macros are undefined*/
long macExpandString(
    MAC_HANDLE  *handle,        /* opaque handle */
    char        *src,           /* source string */
    char        *dest,          /* destination string */
    long        maxlen          /* maximum number of characters to copy */
                                /* to destination string */
);


/*following returns length of value */
long macPutValue(
    MAC_HANDLE  *handle,        /* opaque handle */
    char        *name,          /* macro name */
    char        *value          /* macro value */
);

/*following returns #chars copied (<0 if undefined) */
long macGetValue(
    MAC_HANDLE  *handle,        /* opaque handle */
    char        *name,          /* macro name or reference */
    char        *value,         /* string to receive macro value or name */
                                /* argument if macro is undefined */
    long        maxlen          /* maximum number of characters to copy */
                                /* to value */
);
```

```
long macDeleteHandle(MAC_HANDLE *handle);
long macPushScope(MAC_HANDLE *handle);
long macPopScope(MAC_HANDLE *handle);
long macReportMacros(MAC_HANDLE *handle);

/* Function prototypes (utility library) */

/*following returns #defns encountered; <0 = ERROR */
long macParseDefns(
     MAC_HANDLE *handle,        /* opaque handle; can be NULL if default */
                                /* special characters are to be used */
    char        *defns,         /* macro definitions in "a=xxx,b=yyy" */
                                /* format */
    char        **pairs[]       /* address of variable to receive pointer */
                                /* to NULL-terminated array of {name, */
                                /* value} pair strings; all storage is */
                                /* allocated contiguously */
);

/*following returns #macros defined; <0 = ERROR */
long macInstallMacros(MAC_HANDLE *handle,
    char        *pairs[]        /* pointer to NULL-terminated array of */
                                /* {name,value} pair strings; a NULL */
                                /* value implies undefined; a NULL */
                                /* argument implies no macros */
);

/*Expand string using environment variables as macro definitions */
epicsShareFunc char *         /* expanded string; NULL if any undefined macros */
epicsShareAPI macEnvExpand(
    char *str                   /* string to be expanded */
);
```

NOTE: The directory <base>/src/libCom/macLib contains two files `macLibNOTES` and `macLibREADME` that explain this library.

19.17 misc

19.17.1 aToIPAddr

The function prototype for this routine appears in `osiSock.h`

```
int aToIPAddr(const char *pAddrString, unsigned short defaultPort,
              struct sockaddr_in *pIP);
```

aToIPAddr() fills in the structure pointed to by the *pIP* argument with the Internet address and port number specified by the *pAddrString* argument.

Three forms of *pAddrString* are accepted:

1. n.n.n.n:p
   The Internet address of the host, specified as four numbers separated by periods.
2. xxxxxxxx:p
   The Internet address number of the host, specified as a single number.
3. hostname:p
   The Internet host name of the host.

In all cases the ':p' may be omitted in which case the port number is set to the value of the *defaultPort* argument. All numbers are read in base 16 if they begin with '0x' or '0X', in base 8 if they begin with '0', and in base 10 otherwise.

19.17.2 adjustment

`adjustment.h` describes a single function:

```
size_t adjustToWorstCaseAlignment(size_t size);
```

adjustToWorstCaseAlignment() returns a value >= *size* that an exact multiple of the worst case alignment for the architecture on which the routine is executed.

19.17.3 cantProceed

`cantProceed.h` describes routines that are provided for code that can't proceed when an error occurs.

```
void cantProceed(const char *errorMessage);
void *callocMustSucceed(size_t count, size_t size,const char *errorMessage);
void *mallocMustSucceed(size_t size, const char *errorMessage);
```

cantProceed() issues the error message and suspends the current task - it will never return. callocMustSucceed() and mallocMustSucceed() can be used in place of `calloc()` and `malloc()`. If size or count are zero, or the memory allocation fails, they output a message and call cantProceed().

19.17.4 dbDefs

`dbDefs.h` contains definitions that are still used in base but should not be. Hopefully these all go away some day. This has been the hope for about ten years.

19.17.5 epicsConvert

`epicsConvert.h` currently describes:

```
float epicsConvertDoubleToFloat(double value);
```

`epicsConvertDoubleToFloat` converts a double to a float. If the double value can not be represented as a float then the assigned value is +-FLTMIN or +- FLT_MAX. A floating exception is never raised.

19.17.6 epicsString

`epicsString.h` currently describes:

```
int dbTranslateEscape(char *dst, const char *src);
int epicsStrCaseCmp(const char *s1, const char *s2);
int epicsStrnCaseCmp(const char *s1, const char *s2, int n);
```

```
char *epicsStrDup(const char *s);
int epicsStrPrintEscaped(FILE *fp, const char *s, int n);
int epicsStrSnPrintEscaped(char *outbuf, int outsize,
                           const char *inbuf,int inlen);
int epicsStrGlobMatch(const char *str, const char *pattern);
char *epicsStrtok_r(char *s, const char *delim, char **lasts);
```

`dbTranslateEscape` copies the string *src* to *dst* while substituting escape sequences. It returns the length of the resultant string (which may contain null bytes). The caller must ensure that the buffer *dst* is large enough, but the destination string can never be longer than the source and it is legal for *dst* and *src* to be the same and thus perform translations in-place.

`epicsStrCaseCmp` and `epicsStrnCaseCmp` implement `strcasecmp` and `strncasecmp`, respectively, which are not available on all operating systems. They operate like `strcmp` and `strncmp`, but are case insensitive.

`epicsStrDup` implements `strdup`, which is not available on all operating systems. It allocates sufficient memory for a copy of the string *s*, does the copy, and returns a pointer to it. The pointer may subsequently be used as an argument to the function free(). If insufficient memory is available cantProceed() is called.

`epicsStrPrintEscaped` prints the contents of buffer substituting C-style escape sequences for non printable characters. In a sense it is the opposite of dbTranslateEscape. `epicsStrSnPrintEscaped` performs the same substitutions but stores the result in the specified output buffer. It returns the number of characters stored in the output buffer or a value greater than or equal to `outsize` if the output has been truncated to fit in the specified size. The following non-printable characters are printed as C-style character constants:

```
'\a', '\b', '\f', '\n', '\r', '\t', '\v', '\\', '\'', '\"'
```

All other non-printable characters are printed as:

```
'\ooo'
```

Where `ooo` comprises three octal digits (0-7).

`epicsStrGlobMatch` returns non-zero if the *str* matches the shell wild-card *pattern*.

`epicsStrtok_r` implements `strtok_r`, which is not available on all operating systems.

19.17.7 epicsTypes

`epicsTypes.h` provides typedefs for architecture independent data types.

```
typedef char            epicsInt8;
typedef unsigned char   epicsUInt8;
typedef short           epicsInt16;
typedef unsigned short  epicsUInt16;
typedef epicsUInt16     epicsEnum16;
typedef int             epicsInt32;
typedef unsigned        epicsUInt32;
typedef float           epicsFloat32;
typedef double          epicsFloat64;
typedef unsigned long   epicsIndex;
typedef epicsInt32      epicsStatus;
```

So far the definitions provided in this header file have worked on all architectures. In addition to the above definitions `epicsTypes.h` has a number of definitions for displaying the types and other useful definitions. See the header file for details.

19.17.8 locationException

A C++ template for use as an exception object, used inside Channel Access. Not documented here.

19.17.9 shareLib.h

This is the header file for the "decorated names" that appear in header files, e.g.

```
#define epicsExportSharedSymbols
epicsShareFunc int epicsShareAPI a_func(int arg);
```

Thse are needed to properly create DLLs on windows. Read the comments in the shareLib.h file for a detailed description of where they should be used. Note that the `epicsShareAPI` decorator is deprecated for all new EPICS APIs and is being removed from APIs that are only used within the IOC.

19.17.10 truncateFile.h

```
enum TF_RETURN {TF_OK=0, TF_ERROR=1};
TF_RETURN truncateFile (const char *pFileName, unsigned size);
```

where

pFileName - name (and optionally path) of file

truncateFile() truncates the file to the specified size. truncate() is not used because it is not portable. It returns TF_OK if the file is less than size bytes or if it was successfully truncated. It returns TF_ERROR if the file could not be truncated.

19.17.11 unixFileName.h

Defines macros OSI_PATH_LIST_SEPARATOR and OSI_PATH_SEPARATOR

19.17.12 epicsUnitTest.h

The unit test routines make it easy for a test program to generate output that is compatible with the Test Anything Protocol and can thus be used with Perl's automated Test::Harness as well as generating human-readable output. The routines detect whether they are being run automatically and print a summary of the results at the end if not.

```
void testPlan(int tests);
int  testOk(int pass, const char *fmt, ...);
#define testOk1(cond) testOk(cond, "%s", #cond)
void testPass(const char *fmt, ...);
void testFail(const char *fmt, ...);
int  testOkV(int pass, const char *fmt, va_list pvar);
void testSkip(int skip, const char *why)
void testTodoBegin(const char *why);
void testTodoEnd();
int  testDiag(const char *fmt, ...);
void testAbort(const char *fmt, ...);
int  testDone(void);

typedef int (*TESTFUNC)(void);
epicsShareFunc void testHarness(void);
epicsShareFunc void runTestFunc(const char *name, TESTFUNC func);
```

```
#define runTest(func) runTestFunc(#func, func)
```

A test program starts with a call to testPlan(), announcing how many tests are to be conducted. If this number is not known a value of zero can be used during development, but it is recommended that the correct value be substituted after the test program has been completed.

Individual test results are reported using any of testOk(), testOk1(), testOkV(), testPass() or testFail(). The testOk() call takes and also returns a logical pass/fail result (zero means failure, any other value is success) and a printf-like format string and arguments which describe the test. The convenience macro testOk1() is provided which stringifies its single condition argument, reducing the effort needed to write test programs. The individual testPass() and testFail() routines can be used when the test program takes a different path on success than on failure. The testOkV() routine is a varargs form of testOk() included for internal purposes which may prove useful in some cases.

If some program condition or failure makes it impossible to run some tests, the testSkip() routine can be used to indicate how many tests are being omitted from the run, thus keeping the test counts correct; the constant string why is displayed as an explanation to the user (this string is not printf-like).

If some tests are expected to fail because functionality in the module under test has not yet been implemented, these tests should still be executed, wrapped between calls to testTodoBegin() (which takes a constant string indicating why these tests are not expected to succeed) and testTodoEnd(). This modifies the counting of the results so these tests will not be recorded as failures.

Additional information can be supplied using the testDiag() routine, which displays the relevent information as a comment in the result output. None of the strings passed to any testXxx() routine should contain a newline '\n' character, newlines will be added by the test routines as part of the Test Anything Protocol. For multiple lines of diagnostic output, call testDiag() as many times as necessary.

If at any time the test program is unable to continue for some catastrophic reason, calling testAbort() with an appropriate message will ensure that the test harness understands this; testAbort() does not return, but calls the ANSI C routine abort() to cause the program to stop immediately.

After all of the tests have been completed, the return value from testDone() can be used as the return status code from the program's main() routine.

On vxWorks and RTEMS, an alternative test harness can be used to run a series of tests in order and summarize the results from them all at the end just like the Perl harness does. The routine testHarness() is called once a the beginning of the test harness program. Each test program is run by passing its main routine name to the runTest() macro which expands into a call to the runTestFunc() routine. The last test program or the harness program itself must finish by calling epicsExit() which triggers the test summary mechanism to generate its result outputs (from an epicsAtExit callback routine).

To make it easier to create a single test program that can be built for both the embedded and workstation operating system harnesses, the header file `testMain.h` provides a convenience macro MAIN() that adjusts the name of the test program according to the platform it is running on, main() on workstations and a regular function name on embedded systems.

The following is a simple example of a test program using the epicsUnitTest routines:

```
#include <math.h>
#include "epicsUnitTest.h"
#include "testMain.h"

MAIN(mathTest)
{
    testPlan(3);
    testOk(sin(0.0) == 0.0, "Sine starts");
    testOk(cos(0.0) == 1.0, "Cosine continues");
    if (!testOk1(M_PI == 4.0*atan(1.0)))
        testDiag("4*atan(1) = %g", 4.0*atan(1.0));
```

```
    return testDone();
}
```

The output from running the above program looks like this:

```
1..3
ok  1 - Sine starts
ok  2 - Cosine continues
ok  3 - M_PI == 4.0*atan(1.0)

    Results
    =======
       Tests: 3
      Passed:  3 = 100%
```

Chapter 20: libCom OSI libraries

20.1 Overview

Most code in base is operating system independent, i.e. the code is exactly the same for all supported operating systems. This is accomplished by providing epics defined libraries for facilities that are different on the various systems. The code is called Operating System Independent or OSI. OSI libraries have multiple implementations, which are Operating System Dependent or OSD.

20.1.1 OSI source directory

Directory `<base>/src/libCom/osi` contains the code for the operating system independent libraries. The structure of this directory is:

```
osi/
   epics*.h
   *.cpp  - A few generic c++ implementations
   os/
       Linux/
       Darwin/
       RTEMS/
       WIN32/
       default/
       posix/
       solaris/
       vxWorks/
```

Code for additional operating systems may also be present.

20.1.2 Rules for building OSI code

The osi directory contains header files with names starting with `epics`. These headers provide definitions for user code. Each of the directories `under osi/<arch>` contain architecture-specific code in filenames starting with `osd`. In most cases both a header and source file are present.

Installing header files residing under `src/libCom/osi` into `<base>/include`

- Header files in `osi` are installed into `<base>/include`
- Header files in a subdirectory below `osi/os` are installed into `<base>/include/os/<arch>.` The search order for locating the specific file to be installed is:
    - `libCom/osi/os/<arch>`
    - `libCom/osi/os/posix`
    - `libCom/osi/os/default`

The search order for locating `osd` source files is:

- `libCom/osi/os/<arch>`
- `libCom/osi/os/posix`
- `libCom/osi/os/default`

20.1.3 Locating OSI header files.

When code is compiled the search order for locating header files in `base/include` is:

- `<base>/include/os/<arch>`
- `<base>/include`

20.2 epicsAssert

This is a replacement for ANSI C's `assert`. To use this version just include:

```
#include "epicsAssert.h"
```

instead of

```
#include <assert.h>
```

If an `assert` fails, it calls `errlog` indicating the program's author, file name, and line number. Under each OS there are specialized instructions assisting the user to diagnose the problem and generate a good bug report. For instance, under vxWorks, there are instructions on how to generate a stack trace, and on posix there are instructions about saving the core file. After printing the message the calling thread is suspended.

An author may, before the above include line, optionally define a preprocessor macro named `epicsAssertAuthor` as a string that provides their name and email address if they wish to be contacted when the assertion fires.

20.3 epicsEndian

`epicsEndian.h` provides an operating-system independent means of discovering the native byte order of the CPU which the compiler is targeting, and works for both C and C++ code. It defines the following preprocessor macros, the values of which are integers:

- EPICS_ENDIAN_LITTLE
- EPICS_ENDIAN_BIG
- EPICS_BYTE_ORDER
- EPICS_FLOAT_WORD_ORDER

The latter two macros are defined to be one or other of the first two and may be compared with them to determine conditional compilation or execution of code that performs byte or word swapping as necessary.

20.4 epicsEvent

`epicsEvent.h` contains a C++ and a C description for an event semaphore.

20.4.1 C++ Interface

```
typedef enum {
    epicsEventWaitOK,epicsEventWaitTimeout,epicsEventWaitError
}epicsEventWaitStatus;

typedef enum {epicsEventEmpty,epicsEventFull} epicsEventInitialState;

class epicsEvent{
public:
    epicsEvent(epicsEventInitialState initial=epicsEventEmpty);
    ~epicsEvent();
    void signal();
    void wait(); /*blocks until full*/
    bool wait( double timeOut ); /* false if empty at time out */
    bool tryWait(); /* false if empty */
    void show( unsigned level ) const;

    class invalidSemaphore {}; /* exception */
private:
    ...
};
```

Method	Meaning
epicsEvent	An epicsEvent can be created empty or full. If it is created empty then a wait issued before a signal will block. If created full then the first wait will always succeed. Multiple signals may be issued between waits but have the same effect as a single signal.
~epicsEvent	Remove the event and any resources it uses. Any further use of the semaphore result in unknown (most certainly bad) behavior. No outstanding take can be active when this call is made.
signal	Signal the event i.e. ensures that the next or current call to wait completes. This method may be called from a vxWorks or RTEMS interrupt handler.
wait()	Wait for the event.
wait(double timeOut)	Similar to wait except that if event does not happen the call completes after the specified time out. The return value is (false,true) if the event (did not, did) happen.
tryWait()	Similar to wait except that if event does not happen the call completes immediately. The return value is (false,true) if the event (did not, did) happen.
show	Display information about the semaphore. The information displayed is architecture dependent.

The primary use of an event semaphore is for synchronization. An example of using an event semaphore is a consumer thread that processes requests from one or more producer threads. For example:

- When creating the consumer thread also create an epicsEvent.
  `epicsEvent *pevent = new epicsEvent;`

- The consumer thread has code containing:

```
while(1) {
    pevent->wait();
    while(/*more work*/) {
        /*process work*/
    }
}
```

- Producers create requests and issue the statement:

```
pevent->signal();
```

20.4.2 C Interface

```
typedef struct epicsEventOSD *epicsEventId;

epicsEventId epicsEventCreate(epicsEventInitialState initialState);
epicsEventId epicsEventMustCreate (epicsEventInitialState initialState);
void epicsEventDestroy(epicsEventId id);
void epicsEventSignal(epicsEventId id);
epicsEventWaitStatus epicsEventWait(epicsEventId id);
void epicsEventMustWait(epicsEventId id);
epicsEventWaitStatus epicsEventWaitWithTimeout(epicsEventId id, double timeOut);
epicsEventWaitStatus epicsEventTryWait(epicsEventId id);
void epicsEventShow(epicsEventId id, unsigned int level);
```

Each C routine corresponds to one of the C++ methods. `epicsEventMustCreate` and `epicsEventMustWait` do not return if they fail.

20.5 epicsFindSymbol

`epicsFindSymbol.h` contains the following definition:

```
void * epicsFindSymbol(const char *name);
```

Method	Meaning
epicsFindSymbol	Return the address of the variable name

vxWorks provides a function symFindByName, which finds and returns the address of global variables. The registry, described in the next chapter, provides an alternative but also requires extra work by iocCore and/or user code. If the registry is asked for a name that has not been registered, it calls epicsFindSymbol. If epicsFindSymbol can locate the global symbol it returns the address, otherwise it returns null.

On vxWorks epicsFindSymbol calls symFindByName.

A default version just returns null, i.e. it always fails.

20.6 epicsGeneralTime

The generalTime framework provides a mechanism for several time providers to be present within the system. There are two types of provider, one type for the current time and one type for providing Time Event times. Each time provider has a priority, and installed providers are queried in priority order whenever a time is requested, until one returns successfully. Thus there is a fallback from higher priority providers (smaller value of priority) to lower priority providers (larger value of priority) if the higher priority ones fail. Each architecture has a "last resort" provider, installed at priority 999, usually based on the system clock, which is used in the absence of any other provider.

Targets running vxWorks and RTEMS have an NTP provider installed at priority 100.

There are two interfaces to this framework, epicsGeneralTime.h for consumers that wish to get a time and query the framework, and generalTimeSup.h for providers that supply timestamps.

20.6.1 Consumer interface

`epicsGeneralTime.h` contains the following:

```
void generalTime_Init(void);
int installLastResortEventProvider(void);
void generalTimeResetErrorCounts();
int generalTimeGetErrorCounts();
const char * generalTimeCurrentTpName(void);
const char * generalTimeEventTpName(void);
long generalTimeReport(int interest);
```

Method	Meaning
generalTime_Init	Initialise the framework. This is called automatically by any function that requires the framework. It does not need to be called explicitly.
installLastResortEventProvider	Install a Time Event time provider that returns the current time for any Time Event number. This is optional as it is site policy whether the last resort for a Time Event time in the absence of any working provider should be a failure, or the current time.
generalTimeResetErrorCounts	Reset the internal counter of the number of times the time returned was earlier than when previously requested. Used by device support for bo record with DTYP = "General Time" OUT = "@RSTERRCNT"
generalTimeGetErrorCounts	Return the internal counter of the number of times the time returned was earlier than when previously requested. Used by device support for longin record with DTYP = "General Time" INP = "@GETERRCNT"
generalTimeCurrentTpName	Return the name of the provider that last returned a valid current time, or NULL if none. Used by device support for stringin record with DTYP = "General Time" INP = "@BESTTCP"
generalTimeEventTpName	Return the name of the provider that last returned a valid Time Event time, or NULL if none. Used by device support for stringin record with DTYP = "General Time" INP = "@BESTTEP"
generalTimeReport	Provide information about the installed providers and their current best times.

20.6.2 Provider Interface

`generalTimeSup.h` contains the followi

```
typedef int (*TIMECURRENTFUN)(epicsTimeStamp *pDest);
typedef int (*TIMEEVENTFUN)(epicsTimeStamp *pDest, int event);
int generalTimeCurrentTpRegister(const char *name, int priority,
        TIMECURRENTFUN getCurrent);
int generalTimeEventTpRegister(const char *name, int priority,
        TIMEEVENTFUN getEvent);
int generalTimeGetExceptPriority(epicsTimeStamp *pDest, int *pPriority,
        int ignore_priority);
epicsTimerId generalTimeCreateSyncTimer(epicsTimerCallback cb, void *param);
```

Method	Meaning
generalTimeCurrentTpRegister	Register a current time provider with the framework. The getCurrent routine must return epicsTimeOK if it provided a valid time, or epicsTimeERROR if it could not.
generalTimeEventTpRegister	Register a provider of Time Event times with the framework. The getEvent routine must return epicsTimeOK if it provided a valid time for the requested Time Event, or epicsTimeERROR if it could not. It is an implemetation decision in the provider whether the time returned for a Time Event that has never happened is valid or not.
generalTimeGetExceptProirity	Request the current time from the framework, but exclude providers with priority ignore_priority. This allows providers to synchronise themselves with other higher priority providers. pPriority returns the priority of the provider that supplied the result, which may be higher or lower than ignore_priority.
generalTimeCreateSyncTimer	Helper routine to create an epicsTimer on a common high priority timer queue, which may be used for periodic synchronisation.

If two providers are registered at the same priority number, the first-installed one will be preferred, although the other will still be queried if the first is unable to provide the time when requested.

Some providers may start a task that periodically synchronizes themselves with a higher priority provider, using generalTimeGetExceptPriority to ensure that they are themselves excluded from this time request.

20.6.3 Internal Interface

The generalTime framework also now provides the implementations of epicsTimeGetCurrent() and epicsTimeGetEvent(). If epicsTimeGetEvent() is called with an event number of 0 (epicsTimeEventCurrentTime) then it will get the time from the best available current time provider. Thus providers do not need to provide event times if they do not implement an event system.

20.6.4 Example

Soft device support is provided for ai, bo, longin and stringin records. A typical example is:

```
record(ai, "$(IOC):GTIM_CURTIME") {
  field(DESC, "Get Time")
```

```
  field(DTYP, "General Time")
  field(INP,  "@TIME")
}

record(bo, "$(IOC):GTIM_RSTERR") {
  field(DESC, "Reset ErrorCounts")
  field(DTYP, "General Time")
  field(OUT,  "@RSTERRCNT")
}

record(longin, "$(IOC):GTIM_ERRCNT") {
  field(DESC, "Get ErrorCounts")
  field(DTYP, "General Time")
  field(INP,  "@GETERRCNT")
}

record(stringin, "$(IOC):GTIM_BESTTCP") {
  field(DESC, "Best Time-Current-Provider")
  field(DTYP, "General Time")
  field(INP,  "@BESTTCP")
}

record(stringin, "$(IOC):GTIM_BESTTEP") {
  field(DESC, "Best Time-Event-Provider")
  field(DTYP, "General Time")
  field(INP,  "@BESTTEP")
}
```

20.7 epicsInterrupt

`epicsInterrupt.h` contains the following:

20.7.1 C Interface

```
int epicsInterruptLock();
void epicsInterruptUnlock(int key);
int epicsInterruptIsInterruptContext();
void epicsInterruptContextMessage(const char *message);
```

Method	Meaning

epicsInterruptLock	Lock interrupts and return a key to be passed to epicsInterruptUnlock
	To lock the following is done.
	int key;
	...
	key = epicsInterruptLock();
	...
	epicsInterruptUnlock(key);

epicsInterruptUnlock	Unlock interrupts.
epicsInterruptIsInterruptContext	Return (true, false) if current context is interrupt context.
epicsInterruptContextMessage	Generate a message while interrupt context is true.

20.7.2 Implementation notes

A vxWorks specific version is provided. It maps directly to intLib calls.

An RTEMS version is provided that maps to rtems_ calls.

A default version is provided that uses a global semaphore to lock. This version is intended for operating systems in which iocCore will run as a multi threaded process. The global semaphore is thus only global within the process. This version is intended for use on all except real time operating systems.

The vxWorks implementation will most likely not work on symmetric multiprocessing systems.

The reason epicsInterrupt is needed is:

- callbackRequest and scanOnce can be issued from interrupt level.
- The errlog routines can be called while at interrupt level.

20.8 epicsMath

`epicsMath.h` includes `math.h` and also ensures that `isnan` and `isinf` are defined.

20.9 epicsMessageQueue

`epicsMessageQueue.h` describes a C++ and a C facility for interlocked communication between threads.

20.9.1 C++ Interface

EpicsMessageQueue provides methods for sending messages between threads on a first in, first out basis. It is designed so that a message queue can be used with multiple writer and reader threads

```
class epicsMessageQueue {
public:
    epicsMessageQueue(unsigned int capacity, unsigned int maximumMessageSize);
    ~epicsMessageQueue();
    bool trySend(void *message, unsigned int messageSize);
    bool send(void *message, unsigned int messageSize);
    bool send(void *message, unsigned int messageSize, double timeout);
    int tryReceive(void *message, unsigned int messageBufferSize);
    int receive(void *message, unsigned int messageBufferSize);
    int receive(void *message, unsigned int messageBufferSize, double timeout);
    void show(int level) const;
    int pending() const;

private: // Prevent compiler-generated member functions
    // default constructor, copy constructor, assignment operator
    epicsMessageQueue();
    epicsMessageQueue(const epicsMessageQueue &);
    epicsMessageQueue& operator=(const epicsMessageQueue &);

private: // Data
    ...
};
```

An epicsMessageQueue cannot be assigned to, copy-constructed, or constructed without giving the *capacity* and *maximumMessageSize* arguments. The C++ compiler will object to some of the statements below:

```
epicsMessageQueue mq0();   // Error: default constructor is private
epicsMessageQueue mq1(10, 20); // OK
epicsMessageQueue mq2(t1); // Error: copy constructor is private
epicsMessageQueue *pmq;    // OK, pointer
*pmq = mq1;               // Error: assignment operator is private
pmq = &mq1;               // OK, pointer assignment and address-of
```

Method	Meaning
epicsMessageQueue()	Constructor. The capacity is the maximum number of messages, each containing 0 to maximumMessageSize bytes, that can be stored in the message queue.
~epicsMessageQueue()	Destructor.
trySend()	Try to send a message. Return 0 if the message was sent to a receiver or queued for future delivery. Return -1 if no more messages can be queued or if the message is larger than the queue's maximum message size. This method may be called from a vxWorks or RTEMS interrupt handler.
send()	Send a message. Return 0 if the message was sent to a receiver or queued for future delivery. Return -1 if the timeout, if any, was reached before the message could be sent or queued, or if the message is larger than the queue's maximum message size.
tryReceive()	Try to receive a message. If the message queue is non-empty, the first message on the queue is copied to the specified location and the length of the message is returned. Returns -1 if the message queue is empty. If the pending message is larger than the specified messageBufferSize it may either return -1, or truncate the message. It is most efficient if the messageBufferSize is equal to the maximumMessageSize with which the message queue was created.

Method	Meaning
receive()	Wait until a message is sent and store it in the specified location. The number of bytes in the message is returned. Returns -1 if a message is not received within the timeout interval. If the received message is larger than the specified messageBufferSize it may either return -1, or truncate the message. It is most efficient if the messageBufferSize is equal to the maximumMessageSize with which the message queue was created.
show()	Displays some information about the message queue. The level argument controls the amount of information dispalyed.
pending()	Returns the number of messages presently in the queue.

20.9.2 C interface

```
typedef void *epicsMessageQueueId;
epicsMessageQueueId epicsMessageQueueCreate(unsigned int capacity,
                                            unsigned int maximumMessageSize);
void epicsMessageQueueDestroy(epicsMessageQueueId);
int epicsMessageQueueTrySend(epicsMessageQueueId, void *, unsigned int);
int epicsMessageQueueSend(epicsMessageQueueId, void *, unsigned int);
int epicsMessageQueueSendWithTimeout(epicsMessageQueueId, void *, unsigned int,
                                                                    double);
int epicsMessageQueueTryReceive(epicsMessageQueueId, void *, unsigned int);
int epicsMessageQueueReceive(epicsMessageQueueId, void *, unsigned int);
int epicsMessageQueueReceiveWithTimeout(epicsMessageQueueId, void*,
                                          unsigned int, double);
void epicsMessageQueueShow(epicsMessageQueueId);
int epicsMessageQueuePending(epicsMessageQueueId);
```

Each C function corresponds to one of the C++ methods.

20.10 epicsMutex

`epicsMutex.h` contains both C++ and C descriptions for a mutual exclusion semaphore.

20.10.1 C++ Interface

```
typedef enum {
    epicsMutexLockOK,epicsMutexLockTimeout,epicsMutexLockError
} epicsMutexLockStatus;
class epicsMutex {
public:
    epicsMutex ();
    ~epicsMutex ();
    void lock (); /* blocks until success */
    bool tryLock (); /* true if successful */
    void unlock ();
    void show ( unsigned level ) const;
```

```
    class invalidSemaphore {}; /* exception */
private:
};
```

Method	Meaning
epicsMutex	Create a mutual exclusion semaphore.
~epicsMutex	Remove the semaphore and any resources it uses. Any further use of the semaphore result in unknown (most certainly bad) results.
lock()	Wait until the resource is free. After a successful lock additional, i.e. recursive, locks of any type can be issued but each must have an associated unlock.
tryLock()	Similar to lock except that, if the resource is owned by another thread, the call completes immediately. The return value is (false,true) if the resource (is not, is) owned by the caller.
unlock	Release the resource. If a thread issues recursive locks, there must be an unlock for each lock
show	Display information about the semaphore. The results are architecture dependent.

Mutual exclusion semaphores are for situations requiring mutually exclusive access to resources. A mutual exclusion semaphore may be taken recursively, i.e. can be taken more than once by the owner thread before releasing it. Recursive takes are useful for a set of routines that call each other while working on a mutually exclusive resource.

The typical use of a mutual exclusion semaphore is:

```
    epicsMutex *plock = new epicsMutex;
    ...
    ...
    plock->lock();
    /* process resource */
    plock->unlock();
```

20.10.2 C Interface

```
typedef struct epicsMutexOSD* epicsMutexId;

epicsMutexId epicsMutexCreate(void);
epicsMutexId epicsMutexMustCreate (void);
void epicsMutexDestroy(epicsMutexId id);
void epicsMutexUnlock(epicsMutexId id);
epicsMutexLockStatus epicsMutexLock(epicsMutexId id);
void epicsMutexMustLock(epicsMutexId id);
epicsMutexLockStatus epicsMutexTryLock(epicsMutexId id);
void epicsMutexShow(epicsMutexId id,unsigned  int level);
void epicsMutexShowAll(int onlyLocked,unsigned  int level);
```

Each C routine corresponds to one of the C++ methods. `epicsMutexMustCreate` and `epicsMutexMustLock` do not return if they fail.

20.10.3 Implementation Notes

The implementation:

- Must implement recursive locking
- May implement priority inheritance and be deletion safe

A posix version is implemented via pthreads.

20.11 epicsStdlib

epicsStdlib.h includes stdlib.h and contains definitions for the following functions/macros.

```
double epicsStrtod(const char *str, char **endp);
int epicsScanFloat(const char *str, float *dest);
int epicsScanDouble(const char *str, double *dest);
```

`epicsStrtod` has the same semantics as the C99 function `strtod`. It is provided because some architectures have implementations which do not accept NAN or INFINITY. On architectures which provide an acceptable version of `strtod` this is implemented as a simple macro expansion.

`epicsScanFloat` and `epicsScanDouble` behave like sscanf with a `"%f"` and `"%lf"` format string, respectively. They are provided because some architectures have implementations of scanf which do not accept NAN or INFINITY.

20.12 epicsStdio

epicsStdio.h contains definitions for the following functions.

```
int epicsSnprintf(char *str, size_t size,
    const char *format, ...);
int epicsVsnprintf(char *str, size_t size,
    const char *format, va_list ap);
void epicsTempName(char * pNameBuf, size_t nameBufLength );
FILE * epicsShareAPI epicsTempFile ();
enum TF_RETURN {TF_OK=0, TF_ERROR=1};
enum TF_RETURN truncateFile(const char *pFileName, unsigned size );
FILE * epicsGetStdin(void);
FILE * epicsGetStdout(void);
FILE * epicsGetStderr(void);
FILE * epicsGetThreadStdin(void);
FILE * epicsGetThreadStdout(void);
FILE * epicsGetThreadStderr(void);
void epicsSetThreadStdin(FILE *);
void epicsSetThreadStdout(FILE *);
void epicsSetThreadStderr(FILE *);
int epicsStdoutPrintf(const char *pformat, ...);
```

`epicsSnprintf` and `epicsVsnprintf` are meant to have the same semantics as the C99 functions `snprintf` and `vsnprintf`. They are provided because some architectures do not implement these functions, while others do not implement the correct semantics. If you haven't heard of these C99 functions, `snprintf` is like `sprintf` except that

the `size` argument gives the maximum number of characters (including the trailing zero byte) that may be placed in `str`. Similarly `vsnprintf` is a size-limited version of `vsprintf`. In both cases the return value is supposed to be the number characters (not counting the terminating zero byte) that would be written to `str` if it was large enough to hold them all; the output has been truncated if the return value is `size` or more.

On some operating systems the implementations of these functions may not always return the correct value. If the OS implementation does not correctly return the number of characters that would have been written when the output gets truncated, it is not worth trying to fix this as long as both return `size-1` instead; the resulting string must always be correctly terminated with a zero byte.

Operating systems such as Solaris which follow the Single Unix Specification V2, `epicsSnprintf` and `epicsVsnprintf` do not provide correct C99 semantics for the return value when `size` is given as zero. On these systems `epicsSnprintf` and `epicsVsnprintf` may return an error (a value less than zero) if a buffer length of zero is passed in, so callers should not use that technique.

`epicsTempName` and `epicsTempFile` can be called to get unique filenames and files.

`truncateFile` returns `TF_OK` if the file is less than size bytes or if it was successfully truncated. Returns `TF_ERROR` if the file could not be truncated.

The Stdin/Stdout/Stderr routines allow these file steams to be redirected on a per thread basis, e.g. calling epicsSetThreadStdout will affect only the thread which calls it.

`epicsGetStdin, ..., epicsStdoutPrintf` are not normally called by user code. Instead code that wants to allow redirection needs only to include `epicsStdioRedirect.h`

20.13 epicsStdioRedirect

Including this file cause the following names to be changed:

- stdin becomes epicsGetStdin()
- stdout becomes epicsGetStdout()
- stderr becomes epicsGetStderr()
- printf becomes epicsStdoutPrintf

This is done so that redirection can occur. A primary use of this facility is iocsh. It allows redirection of input and output. In order for it to work, all modules involved in I/O can just include this header.

20.14 epicsThread

`epicsThread.h` contains C++ and C descriptions for a thread.

20.14.1 C Interface

```
typedef void (*EPICSTHREADFUNC)(void *parm);

static const unsigned epicsThreadPriorityMax = 99;
static const unsigned epicsThreadPriorityMin = 0;
/* some generic values */
static const unsigned epicsThreadPriorityLow = 10;
```

```
static const unsigned epicsThreadPriorityMedium = 50;
static const unsigned epicsThreadPriorityHigh = 90;
/* some iocCore specific values */
static const unsigned epicsThreadPriorityCAServerLow = 20;
static const unsigned epicsThreadPriorityCAServerHigh = 40;
static const unsigned epicsThreadPriorityScanLow = 60;
static const unsigned epicsThreadPriorityScanHigh = 70;
static const unsigned epicsThreadPriorityIocsh = 91;
static const unsigned epicsThreadPriorityBaseMax = 91;

/* stack sizes for each stackSizeClass are implementation and CPU dependent */
typedef enum {
    epicsThreadStackSmall, epicsThreadStackMedium, epicsThreadStackBig
} epicsThreadStackSizeClass;

typedef enum {
    epicsThreadBooleanStatusFail, epicsThreadBooleanStatusSuccess
} epicsThreadBooleanStatus;

unsigned int epicsThreadGetStackSize(epicsThreadStackSizeClass size);

typedef int epicsThreadOnceId;
#define EPICS_THREAD_ONCE_INIT 0

void epicsThreadOnce(epicsThreadOnceId *id, EPICSTHREADFUNC, void *arg);

void epicsThreadExitMain(void);

/* (epicsThreadId)0 is guaranteed to be an invalid thread id */
typedef struct epicsThreadOSD *epicsThreadId;

epicsThreadId epicsThreadCreate(const char *name,
    unsigned int priority, unsigned int stackSize,
    EPICSTHREADFUNC funptr,void *parm);
void epicsThreadSuspendSelf(void);
void epicsThreadResume(epicsThreadId id);
unsigned int epicsThreadGetPriority(epicsThreadId id);
unsigned int epicsThreadGetPrioritySelf();
void epicsThreadSetPriority(epicsThreadId id,unsigned int priority);
epicsThreadBooleanStatus epicsThreadHighestPriorityLevelBelow (
        unsigned int priority, unsigned *pPriorityJustBelow);
epicsThreadBooleanStatus epicsThreadLowestPriorityLevelAbove (
        unsigned int priority, unsigned *pPriorityJustAbove);
int epicsThreadIsEqual(epicsThreadId id1, epicsThreadId id2);
int epicsThreadIsSuspended(epicsThreadId id);
void epicsThreadSleep(double seconds);
double epicsThreadSleepQuantum(void);
epicsThreadId epicsThreadGetIdSelf(void);
epicsThreadId epicsThreadGetId(const char *name);

const char * epicsThreadGetNameSelf(void);
void epicsThreadGetName(epicsThreadId id, char *name, size_t size);
int epicsThreadIsOkToBlock(void);
```

```
void epicsThreadSetOkToBlock(int isOkToBlock);

void epicsThreadShowAll(unsigned int level);
void epicsThreadShow(epicsThreadId id,unsigned int level);

typedef void * epicsThreadPrivateId;
epicsThreadPrivateId epicsThreadPrivateCreate(void);
void epicsThreadPrivateDelete(epicsThreadPrivateId id);
void epicsThreadPrivateSet(epicsThreadPrivateId,void *);
void * epicsThreadPrivateGet(epicsThreadPrivateId);
```

Method	Meaning
epicsThreadGetStackSize	Get a stack size value that can be given to epicsThreadCreate. The size argument should be one of the values epicsThreadStackSmall, epicsThreadStackMedium or epicsThreadStackBig.

epicsThreadOnce	This is used as follows:
	void myInitFunc(void * arg)
	{
	...
	}
	epicsThreadOnceId onceFlag = EPICS_THREAD_ONCE_INIT;
	...
	epicsThreadOnce(&onceFlag,myInitFunc,(void *)myParm);
	For each unique epicsThreadOnceId, epicsThreadOnce guarantees
	1) myInitFunc is called only once.
	2) myInitFunc completes before any epicsThreadOnce call completes.
	Note that myInitFunc must not call epicsThreadOnce with the same onceId.

epicsThreadExitMain	If the main routine is done but wants to let other threads run it can call this routine. This should be the last call in main, except the final return. On most systems epicsThreadExitMain never returns. This must only be called by the main thread.
epicsThreadCreate	Create a new thread. The use made of the priority, and stackSize arguments is implementation dependent. Some implementations may ignore one or other of these, but for portability appropriate values should be given for both. The value passed as the stackSize parameter should be obtained by calling epicsThreadGetStackSize. The funptr argument specifies a function that implements the thread, and parm is the single argument passed to funptr. A thread terminates when funptr returns.
epicsThreadSuspendSelf	This causes the calling thread to suspend. The only way it can resume is for another thread to call epicsThreadResume.
epicsThreadResume	Resume a suspended thread. Only do this if you know that it is safe to resume a suspended thread.
epicsThreadGetPriority	Get the priority of the specified thread.
epicsThreadGetPrioritySelf	Get the priority of this thread.
epicsThreadSetPriority	Set a new priority for the specified thread. The result is implementation dependent.
epicsThreadHighestPriorityLevelBelow	Get a priority that is just lower than the specified priority.

Method	Meaning
epicsThreadLowestPriorityLevelAbove	Get a priority that is just above the specified priority.
epicsThreadIsEqual	Compares two threadIds and returns (0,1) if they (are not, are) the same.
epicsThreadIsSuspended	BAD NAME. taskwd needs this call. It really means: Is there something wrong with this thread? This could mean suspended or no longer exists or etc. It is a problem because it is implementation dependent.
epicsThreadSleep	Sleep for the specified period of time, i.e. sleep without using the cpu. If delay is >0 then the thread will sleep at least until the next clock tick. The exact time is determined by the underlying architecture. If delay is <= 0 then a delay of 0 is requested of the underlying architecture. What happens is architecture dependent but often it allows other threads of the same priority to run.
epicsThreadSleepQuantum	This function returns the minimum slumber interval obtainable with epicsThreadSleep() in seconds. On most OS there is a system scheduler interrupt interval which determines the value of this parameter. Knowledge of this parameter is used by the various components of EPICS to improve scheduling of software tasks in time when the reduction of average time scheduling errors is important. If this parameter is unknown or is unpredictable for a particular OS then it is safe to return zero.
epicsThreadGetIdSelf	Get the threadId of the calling thread.
epicsThreadGetId	Get the threadId of the specified thread. A return of 0 means that no thread was found with the specified name.
epicsThreadGetNameSelf	Get the name of the calling thread.
epicsThreadGetName	Get the name of the specified thread. The value is copied to a caller specified buffer so that if the thread terminates the caller is not left with a pointer to something that may no longer exist.
epicsThreadIsOkToBlock	Is it OK for a thread to block? This can be called by support code that does not know if it is called in a thread that should not block. For example the errlog system calls this to decide when messages should be displayed on the console.
epicsThreadSetOkToBlock	When a thread is started the default is that it is not allowed to block. This method can be called to change the state. For example iocsh calls this to specify that it is OK to block.
epicsThreadShowAll	Display info about all threads.
epicsThreadShow	Display info about the specified thread.
epicsThreadPrivateCreate	Thread private variables are intended for use by legacy libraries written for a single threaded environment and which uses a global variable to store private data. The only code in base that currently needs this facility is channel access. A library that needs a private variable should make exactly one call to epicsThreadPrivateCreate. Each thread should call epicsThreadPrivateSet when the thread is created. Each library routine can call epicsThreadPrivateGet each time it is called.
epicsThreadPrivateDelete	Delete a thread private variable.

Method	Meaning
epicsThreadPrivateSet	Set the value for a thread private variable.
epicsThreadPrivateGet	Get the value of a thread private variable, the value is the value set by the call to epicsThreadPrivateSet that was made by the same thread. If called before epicsThreadPrivateSet it returns 0.

epicsThread is meant as a somewhat minimal interface for multithreaded applications. It can be implemented on a wide variety of systems with the restriction that the system MUST support a multithreaded environment. A POSIX pthreads version is provided.

The interface provides the following thread facilities, with restrictions as noted:

- Life cycle - A thread starts life as a result of a call to epicsThreadCreate. It terminates when the thread function returns. It should not return until it has released all resources it uses. If a thread is expected to terminate as a natural part of its life cycle then the thread function must return.
- epicsThreadOnce - This provides the ability to have an initialization function that is guaranteed to be called exactly once.
- main - If a main routine finishes its work but wants to leave other threads running it can call epicsThreadExitMain, which should be the last statement in main.
- Priorities - Ranges between 0 and 99 with a higher number meaning higher priority. A number of constants are defined for iocCore specific threads. The underlying implementation may collapse the range 0 to 99 into a smaller range; even a single priority. User code should never use priorities to guarantee correct behavior.
- Stack Size - epicsThreadCreate accepts a stack size parameter. Three generic sizes are available: small, medium, and large. Portable code should always use one of the generic sizes. Some implementation may ignore the stack size request and use a system default instead. Virtual memory systems providing generous stack sizes can be expected to use the system default.
- epicsThreadId - This is given a value as a result of a call to epicsThreadCreate. A value of 0 always means no thread. If a threadId is used for a thread that has terminated the result is not defined (but will normally lead to bad things happening). Thus code that looks after other threads MUST be aware of threads terminating.

20.14.2 C++ Interface

```
class epicsThreadRunable {
public:
    virtual void run() = 0;
    virtual void stop();
    virtual void show(unsigned int level) const;
};

class epicsShareClass epicsThread {
public:
    epicsThread (epicsThreadRunable &,const char *name, unsigned int stackSize,
        unsigned int priority=epicsThreadPriorityLow);
    virtual ~epicsThread ();
    void start();
    void exitWait ();
    bool exitWait (const double delay );
    void exitWaitRelease (); // noop if not called by managed thread
    static void exit ();
    void resume ();
```

```
    void getName (char *name, size_t size) const;
    epicsThreadId getId () const;
    unsigned int getPriority () const;
    void setPriority (unsigned int);
    bool priorityIsEqual (const epicsThread &otherThread) const;
    bool isSuspended () const;
    bool isCurrentThread () const;
    bool operator == (const epicsThread &rhs) const;
    /* these operate on the current thread */
    static void suspendSelf ();
    static void sleep (double seconds);
    static epicsThread & getSelf ();
    static const char * getNameSelf ();
    static bool isOkToBlock ();
    static void setOkToBlock(bool isOkToBlock) ;
private:
    ...
};
template <class T>
class epicsThreadPrivate {
public:
    epicsThreadPrivate ();
    ~epicsThreadPrivate ();
    T *get () const;
    void set (T *);
    class unableToCreateThreadPrivate {}; // exception
private:
    ...
};
```

The C++ interface is just a wrapper around the C interface. Two differences are the method `start` and the class `epicsThreadRunable`.

The method `start` must be called only after the `epicsThead` object is constructed. It in turn calls the `run` method of the `epicsThreadRunable` object.

Code using the C++ interface code must provide a class that derives from `epicsThreadRunable`. One way to accomplish this is as follows:

```
class myThread: public epicsThreadRunable {
public:
    myThread(int arg,const char *name);
    virtual ~myThread();
    virtual void run();
    epicsThread thread;
    ...
}

myThread::myThread(int arg,const char *name) :
    thread(*this,name,epicsThreadGetStackSize(epicsThreadStackSmall),50)
{
    thread.start();
}

myThread::~myThread() {}
```

```
void myThread::run()
{
    ...
}
```

20.15 epicsTime

`epicsTime.h` contains C++ and C descriptions for time.

20.15.1 Time Related Structures

```
/* epics time stamp for C interface*/
typedef struct epicsTimeStamp {
    epicsUInt32    secPastEpoch;   /* seconds since 0000 Jan 1, 1990 */
    epicsUInt32    nsec;           /* nanoseconds within second */
} epicsTimeStamp;

/*TS_STAMP is deprecated */
#define TS_STAMP epicsTimeStamp

struct timespec; /* POSIX real time */
struct timeval; /* BSD */
struct l_fp; /* NTP timestamp */

// extend ANSI C RTL "struct tm" to include nano seconds within a second
// and a struct tm that is adjusted for the local timezone
struct local_tm_nano_sec {
    struct tm ansi_tm; /* ANSI C time details */
    unsigned long nSec; /* nano seconds extension */
};

// extend ANSI C RTL "struct tm" to includes nano seconds within a second
// and a struct tm that is adjusted for GMT (UTC)
struct gm_tm_nano_sec {
    struct tm ansi_tm; /* ANSI C time details */
    unsigned long nSec; /* nano seconds extension */
};

// wrapping this in a struct allows conversion to and
// from ANSI time_t but does not allow unexpected
// conversions to occur
struct time_t_wrapper {
    time_t ts;
};
```

The above structures are for the various time formats.

- `epicsTimeStamp` - This is the structure used by the C interface for epics time stamps. The C++ interface stores this information in private members. The two elements of the class are:
  - `secPastEpoch` - The number of seconds since January 1, 1990 (the epics epoch).
  - nsec - nanoseconds within a second

  NOTE: `TS_STAMP` is defined for compatibility with existing code.
- `timespec` - This is defined by POSIX Real Time. It requires two mandatory fields:
  - `time_t tv_sec` - Number of seconds since 1970 (The POSIX epoch)
  - `long tv_nsec` - nanoseconds within a second
- `timeval` - BSD and SRV5 Unix timestamp. It has two fields:
  - `time_t tv_sec` - Number of seconds since 1970 (The POSIX epoch)
  - `time_t tv_nsec` - nanoseconds within a second
- `struct l_fp` - Network Time Protocol timestamp. The fields are:
  - l_ui - Number of seconds since 1900 (The NTP epoch)
  - l_uf - Fraction of a second. For example 0x800000000 represents 1/2 second.
- `local_tm_nano_sec and gm_tm_nano_sec` - Defined by epics. It just adds a nanosecond field to `struct tm`.
- `time_t_wrapper` - This is for converting to/from the ANSI C `time_t`. Since `time_t` is usually an elementary type providing a conversion operator from `time_t` to/from `epicsTime` could cause undesirable implicit conversions. Providing a conversion operator to/from a `time_t_wrapper` prevents implicit conversions.

NOTE on conversion. The epics implementation will properly convert between the various formats from the beginning of the EPICS epoch until at least 2038. Unless the underlying architecture support has defective POSIX, BSD/SRV5, or standard C time support the epics implementation should be valid until 2106.

20.15.2 C++ Interface

```
class epicsTime;

class epicsTimeEvent {
    friend class epicsTime;
public:
    epicsTimeEvent (const int &eventName);
private:
    int eventNumber;
};

class epicsTime {
public:
    // exceptions
    class unableToFetchCurrentTime {};
    class formatProblemWithStructTM {};

    epicsTime ();
    epicsTime (const epicsTime &t);

    static epicsTime getEvent (const epicsTimeEvent &event);
    static epicsTime getCurrent ();

    // convert to and from EPICS epicsTimeStamp format
    operator epicsTimeStamp () const;
```

```
epicsTime (const epicsTimeStamp &ts);
epicsTime operator = (const epicsTimeStamp &rhs);

// convert to and from ANSI time_t
operator time_t_wrapper () const;
epicsTime (const time_t_wrapper &tv);
epicsTime operator = (const time_t_wrapper &rhs);

// convert to and from ANSI Cs "struct tm" (with nano seconds)
// adjusted for the local time zone
operator local_tm_nano_sec () const;
epicsTime (const local_tm_nano_sec &ts);
epicsTime operator = (const local_tm_nano_sec &rhs);

// convert to ANSI Cs "struct tm" (with nano seconds)
// adjusted for GM time (UTC)
operator gm_tm_nano_sec () const;

// convert to and from POSIX RT’s "struct timespec"
operator struct timespec () const;
epicsTime (const struct timespec &ts);
epicsTime operator = (const struct timespec &rhs);

// convert to and from BSD’s "struct timeval"
operator struct timeval () const;
epicsTime (const struct timeval &ts);
epicsTime operator = (const struct timeval &rhs);

// convert to and from NTP timestamp format
operator l_fp () const;
epicsTime (const l_fp &);
epicsTime operator = (const l_fp &rhs);

// convert to and from WIN32s FILETIME (implemented only on WIN32)
operator struct _FILETIME () const;
epicsTime ( const struct _FILETIME & );
epicsTime & operator = ( const struct _FILETIME & );

// arithmetic operators
double operator- (const epicsTime &rhs) const; // returns seconds
epicsTime operator+ (const double &rhs) const; // add rhs seconds
epicsTime operator- (const double &rhs) const; // subtract rhs seconds
epicsTime operator+= (const double &rhs); // add rhs seconds
epicsTime operator-= (const double &rhs); // subtract rhs seconds

// comparison operators
bool operator == (const epicsTime &rhs) const;
bool operator != (const epicsTime &rhs) const;
bool operator <= (const epicsTime &rhs) const;
bool operator < (const epicsTime &rhs) const;
bool operator >= (const epicsTime &rhs) const;
bool operator > (const epicsTime &rhs) const;
```

```
    // convert current state to user-specified string
    size_t strftime (char *pBuff, size_t bufLength, const char *pFormat) const;

    // dump current state to standard out
    void show (unsigned interestLevel) const;

    // deprecated
    static void synchronize ();
private:
    ...
};
```

20.15.3 class epicsTimeEvent

```
class epicsShareClass epicsTimeEvent
{
    friend class epicsTime;
public:
    epicsTimeEvent (const int &eventName);
private:
    int eventNumber;
};
```

Method	Meaning
epicsTimeEvent(eventName)	This is the only method provided for this class. Why is it needed?

20.15.4 class epicsTime

Method	Meaning
epicsTime() epicsTime(const epicsTime& t);	The default constructor sets the time to the beginning of the epics epoch.
getEvent	Returns the time for the associated event. See the description of the C routine epicsTimeGetEvent described below for details.
getCurrent	Gets the current time. An example is: `epicsTime time = epicsTime::getCurrent();`

Method	Meaning

convert to/from epicsTimeStamp	Three methods are provided for epicsTimeStamp. A copy constructor, an assignment operator, and a conversion to epicsTimeStamp. Assume the following definitions:
	`epicsTime time;`
	`epicsTimeStamp ts;`
	An example of the copy constructor is:
	`epicsTime time1(ts);`
	An example of the assignment operator is:
	`time = ts;`
	An example of the epicsTimeStamp operator is:
	`ts = time;`

Convert to/from ANSI time_t	Three methods are provided for ANSI time_t. A copy constructor, an assignment operator, and a conversion to time_t_wrapper. The structure time_t_wrapper must be used instead of time_t because undesired conversions could occur: Assume the following definitions:
	`time_t tt;`
	`time_t_wrapper ttw;`
	`epicsTime time;`
	An example of the copy constructor is:
	`ttw.tt = tt;`
	`epicsTime time1(ttw);`
	An example of the assignment operator is:
	`time = ttw;`
	An example of the time_t_wrapper operator is:
	`ttw = time;`
	`tt = ttw.tt;`

convert to and from tm_nano_sec	Three methods are provided for tm_nano_sec A copy constructor, an assignment operator, and a conversion to tm_nano_sec. Assume the following definitions:
	`local_tm_nano_sec ttn;`
	`epicsTime time;`
	An example of the copy constructor is:
	`epicsTime time1(ttn);`
	An example of the assignment operator is:
	`time = ttn;`
	An example of the tm_nano_sec operator is:
	`ttn = time;`

Method	Meaning

convert to and from POSIX RT's "struct timespec"	Three methods are provided for struct timespec. A copy constructor, an assignment operator, and a conversion to struct timespec. Assume the following definitions:
	`struct timespec tts;`
	`epicsTime time;`
	An example of the copy constructor is:
	`epicsTime time1(tts);`
	An example of the assignment operator is:
	`time = tts;`
	An example of the struct timespec operator is:
	`tts = time;`

convert to and from BSD's "struct timeval"	Three methods are provided for struct timeval. A copy constructor, an assignment operator, and a conversion to struct timeval. Assume the following definitions:
	`struct timeval ttv;`
	`epicsTime time;`
	An example of the copy constructor is:
	`epicsTime time1(ttv);`
	An example of the assignment operator is:
	`time = ttv;`
	An example of the struct timeval operator is:
	`ttv = time;`

convert to and from NTP timestamp format	Three methods are provided for ntpTimeStamp. A copy constructor, an assignment operator, and a conversion to ntpTimeStamp. Assume the following definitions:
	`l_fp ntp;`
	`epicsTime time;`
	An example of the copy constructor is:
	`epicsTime time1(ntp);`
	An example of the assignment operator is:
	`time = ntp;`
	An example of the ntpTimeStamp operator is:
	`ntp = time;`

Method	Meaning

arithmetic operators
-
+
+=
-=
	The arithmetic operators allow the difference of two epicsTimes, with the result in seconds. It also allows -, +, +=, and -= where the left hand argument is an epicsTime and the right hand argument is a double. Examples are:
	`epicsTime time, time1, time2;`
	`double t1,t2,t3;`
	`...`
	`t1 = time2 - time1;`
	`time = time1 + 4.5;`
	`time = time2 - t3;`
	`time2 += 6.0;`

Comparison operators
==, |=, <=, <, >=, >
	Two epics times can be compared:
	`epicsTime time1, time2;`
	`...`
	`if(time1<=time2) { ...`

strftime	This is a facility similar to the ANSI C library routine strftime. See K&R for details about strftime. The epicsTime method also provides support for the printing the nanoseconds portion of the time. It looks in the format string for the sequence "%0*n*f" where *n* is the desired precision. It uses this format to convert the nanoseconds value to the requested precision. For example:
	`epicsTime time = epicsTime::getCurrent();`
	`char buf[30];`
	`time.strftime(buf,30,"%Y/%m/%d %H:%M:%S.%06f");`
	`printf("%s\n",buf);`
	Will print the time in the format:
	`2001/01/26 20:50:29.813505`

show	Shows the date/time.

20.15.5 C Interface

```
/* All epicsTime routines return (-1,0) for (failure,success) */
#define epicsTimeOK 0
#define epicsTimeERROR (-1)
/*Some special values for eventNumber*/
#define epicsTimeEventCurrentTime 0
#define epicsTimeEventBestTime -1
#define epicsTimeEventDeviceTime -2

int epicsTimeGetCurrent (epicsTimeStamp *pDest);
int epicsTimeGetEvent (epicsTimeStamp *pDest, int eventNumber);

/* convert to and from ANSI C’s "time_t" */
int epicsTimeToTime_t (time_t *pDest, const epicsTimeStamp *pSrc);
int epicsTimeFromTime_t (epicsTimeStamp *pDest, time_t src);

/*convert to and from ANSI C’s "struct tm" with nano seconds */
int epicsTimeToTM (struct tm *pDest, unsigned long *pNSecDest,
```

```
    const epicsTimeStamp *pSrc);
int epicsTimeToGMTM (struct tm *pDest, unsigned long *pNSecDest,
    const epicsTimeStamp *pSrc);
int epicsTimeFromTM (epicsTimeStamp *pDest, const struct tm *pSrc,
    unsigned long nSecSrc);

/* convert to and from POSIX RT's "struct timespec" */
int epicsTimeToTimespec (struct timespec *pDest, const epicsTimeStamp *pSrc);
int epicsTimeFromTimespec (epicsTimeStamp *pDest, const struct timespec *pSrc);

/* convert to and from BSD's "struct timeval" */
int epicsTimeToTimeval (struct timeval *pDest, const epicsTimeStamp *pSrc);
int epicsTimeFromTimeval (epicsTimeStamp *pDest, const struct timeval *pSrc);
/*arithmetic operations */
double epicsTimeDiffInSeconds (
    const epicsTimeStamp *pLeft, const epicsTimeStamp *pRight);
void epicsTimeAddSeconds (
    epicsTimeStamp *pDest, double secondsToAdd); /* adds seconds to *pDest */

/*comparison operations: returns (0,1) if (false,true) */
int epicsTimeEqual(const epicsTimeStamp *pLeft, const epicsTimeStamp *pRight);
int epicsTimeNotEqual(const epicsTimeStamp *pLeft,const epicsTimeStamp *pRight);
int epicsTimeLessThan(const epicsTimeStamp *pLeft,const epicsTimeStamp *pRight);
int epicsTimeLessThanEqual(
    const epicsTimeStamp *pLeft, const epicsTimeStamp *pRight);
int epicsTimeGreaterThan (
    const epicsTimeStamp *pLeft, const epicsTimeStamp *pRight);
int epicsTimeGreaterThanEqual (
    const epicsTimeStamp *pLeft, const epicsTimeStamp *pRight);
/*convert to ASCII string */
size_t epicsTimeToStrftime (
    char *pBuff, size_t bufLength, const char *pFormat, const epicsTimeStamp
*pTS);

/* dump current state to standard out */
void epicsTimeShow (const epicsTimeStamp *, unsigned interestLevel);
/* OS dependent reentrant versions of the ANSI C interface because */
/* vxWorks gmtime_r interface does not match POSIX standards */
int epicsTime_localtime ( const time_t *clock, struct tm *result );
int epicsTime_gmtime ( const time_t *clock, struct tm *result );
```

The C interface provides most of the features as the C++ interface. The features of the C++ operators are provided as functions.

Note that the epicsTimeGetCurrent and epicsTimeGetEvent routines are now implemented in epicsGeneralTime.c

20.16 osiPoolStatus

`osiPoolStatus.h` contains the following description:

```
int osiSufficentSpaceInPool(void);
```

Method	Meaning
osiSufficentSpaceInPool	Return (true,false) if there is sufficient free memory.

This determines if enough free memory exists to continue.

A vxWorks version returns (true,false) if memFindMax returns (>100000, <=100000) bytes.

The default version always returns true.

20.17 osiProcess

`osiProcess.h` contains the following:

```
typedef enum osiGetUserNameReturn {
    osiGetUserNameFail,
    osiGetUserNameSuccess
}osiGetUserNameReturn;

osiGetUserNameReturn osiGetUserName (char *pBuf, unsigned bufSize);

/*
 * Spawn detached process with named executable, but return
 * osiSpawnDetachedProcessNoSupport if the local OS does not
 * support heavy weight processes.
 */
typedef enum osiSpawnDetachedProcessReturn {
    osiSpawnDetachedProcessFail,
    osiSpawnDetachedProcessSuccess,
    osiSpawnDetachedProcessNoSupport
}osiSpawnDetachedProcessReturn;

osiSpawnDetachedProcessReturn osiSpawnDetachedProcess(
    const char *pProcessName, const char *pBaseExecutableName);
```

Not documented.

20.18 osiSigPipeIgnore

`osiSigPipeIgnore.h` contains the following:

```
void installSigPipeIgnore (void);
```

Not documented.

20.19 osiSock.h

See the header file in <base>/src/libCom/osi.

20.20 Device Support Library

NOTE: EPICS Base only provides vxWorks and RTEMS back-end implementations of these routines. Versions of the back-end routines for other operating systems can be added in a support or IOC application.

20.20.1 Overview

`devLib.h` provides definitions for a library of routines useful for device and driver modules, which are primarily indended for accessing VME devices. If all VME drivers register with these routines then addressing conflicts caused by multiple device/drivers trying to use the same VME addresses will be detected.

20.20.2 Location Probing

20.20.2.1 Read Probe

```
long  devReadProbe(
   unsigned wordSize,
   volatile const void *ptr,
   void *pValueRead);
```

Performs a bus-error-safe atomic read operation width `wordSize` bytes from the `ptr` location, placing the value read (if successful) at `pValueRead`. The routine returns a failure status (non-zero) if a bus error occurred during the read cycle.

20.20.2.2 Write Probe

```
long  devWriteProbe(
   unsigned wordSize,
   volatile void *ptr,
   const void *pValueWritten);
```

Performs a bus-error-safe atomic write operation width `wordSize` which copies the value from `pValueWritten` to the `ptr` location. The routine returns a failure status (non-zero) if a bus error occurred during the write cycle.

20.20.2.3 No Response Probe

```
long devNoResponseProbe(
   epicsAddressType addrType,
   size_t base,
   size_t size);
```

This routine performs a series of read probes for all word sizes from char to long at every naturally aligned location in the range [`base`, `base+size`) for the given bus address type. It returns an error if any location responds or if any such location cannot be mapped.

20.20.3 Registering VME Addresses

20.20.3.1 Definitions of Address Types

```
typedef enum {
   atVMEA16, atVMEA24, atVMEA32,
   atISA,
   atLast /* atLast is the last enum in this list */
} epicsAddressType;

char  *epicsAddressTypeName[] = {
   ”VME A16”, ”VME A24”, ”VME A32”,
   "ISA"
};
```

20.20.3.2 Register Address

```
long  devRegisterAddress(
   const char *pOwnerName,
   epicsAddressType addrType,
   size_t logicalBaseAddress,
   size_t size, /* bytes */
   volatile void **pLocalAddress);
```

This routine is called to register a VME address. The routine keeps a list of all VME address ranges requested and returns an error message if an attempt is made to register any addresses that overlap a range that is already being used. `*pLocalAddress` is set equal to the address as seen by the caller.

20.20.3.3 Print Address Map

```
long  devAddressMap(void)
```

This routine displays the table of registered VME address ranges, including the owner of each registered address.

20.20.3.4 Unregister Address

```
long  devUnregisterAddress(
   epicsAddressType addrType,
   size_t logicalBaseAddress,
   const char *pOwnerName);
```

This routine releases address ranges previously registered by a call to `devRegisterAddress` or `devAllocAddress`.

20.20.3.5 Allocate Address

```
long  devAllocAddress(
   const char *pOwnerName,
   epicsAddressType addrType,
   size_t size,
   unsigned alignment, /*number of low zero bits needed in addr*/
   volatile void **pLocalAddress);
```

This routine is called to request the library to allocate an address block of a particular address type. This is useful for devices that appear in more than one address space and can program the base address of one window using registers found in another window.

20.20.4 Interrupt Connection Routines

20.20.4.1 Connect

```
long  devConnectInterruptVME(
   unsigned vectorNumber,
   void (*pFunction)(void *),
   void  *parameter);
```

Connect ISR `pFunction` up to the VME interrupt `vectorNumber`.

20.20.4.2 Disconnect

```
long  devDisconnectInterruptVME(
   unsigned vectorNumber,
   void (*pFunction)(void *));
```

Disconnects an ISR from its VME interrupt vector. The parameter `pFunction` should be set to the C function pointer that was connected. It is used as a key to prevent a driver from inadvertently removing an interrupt handler that it didn't install.

20.20.4.3 Check If Used

```
int devInterruptInUseVME(
   unsigned vectorNumber);
```

Determines if a VME interrupt vector is in use, returning a boolean value.

20.20.4.4 Enable

```
long devEnableInterruptLevelVME(
   unsigned level);
```

Enable the given VME interrupt level onto the CPU.

20.20.4.5 Disable

```
long devDisableInterruptLevelVME(
   unsigned level);
```

Disable VME interrupt level. This routine should generally never be used, since it is impossible for a driver to know whether any other active drivers are still making use of a particular interrupt level.

20.20.5 Macros for Normalized Analog Values

20.20.5.1 Convert Digital Value to a Normalized Double Value

```
#define devCreateMask(NBITS)((1<<(NBITS))-1)
#define devDigToNml(DIGITAL,NBITS) \
   (((double)(DIGITAL))/devCreateMask(NBITS))
```

20.20.5.2 Convert Normalized Double Value to a Digital Value

```
#define devNmlToDig(NORMAL,NBITS) \
   (((long)(NORMAL)) * devCreateMask(NBITS))
```

20.20.6 Deprecated Interrupt Routines

20.20.6.1 Definitions of Interrupt Types (deprecated)

```
typedef enum {intCPU, intVME, intVXI} epicsInterruptType;
```

The routines that use this typedef have all been deprecated, and currently only exist for backwards compatibility purposes. The typedef will be removed in a future release, along with those routines.

20.20.6.2 Connect (deprecated)

```
long  devConnectInterrupt(
   epicsInterruptType  intType,
   unsigned  vectorNumber,
   void  (*pFunction)(),
   void  *parameter);
```

This routine has been deprecated, and currently only exists for backwards compatibility purposes. Uses of this routine should be converted to call `devConnectInterruptVME` or related routines instead. This routine will be removed in a future release.

20.20.6.3 Disconnect (deprecated)

```
long  devDisconnectInterrupt(
   epicsInterruptType intType,
   unsigned  vectorNumber);
```

This routine has been deprecated, and currently only exists for backwards compatibility purposes. Uses of this routine should be converted to call `devDisconnectInterruptVME` or related routines instead. This routine will be removed in a future release.

20.20.6.4 Enable Level (deprecated)

```
long  devEnableInterruptLevel(
   epicsInterruptType  intType,
   unsigned  level);
```

This routine has been deprecated, and currently only exists for backwards compatibility purposes. Uses of this routine should be converted to call `devEnableInterruptLevelVME` or related routines instead. This routine will be removed in a future release.

20.20.6.5 Disable Level (deprecated)

```
long  devDisableInterruptLevel(
   epicsInterruptType  intType,
   unsigned  level);
```

This routine has been deprecated, and currently only exists for backwards compatibility purposes. Uses of this routine should be converted to call `devDisableInterruptLevelVME` or related routines instead. This routine will be removed in a future release.

20.21 vxWorks Specific routines

The routines described in this section are included in a application by the Makfile command:

```
<appl>_OBJS_vxWorks += $(EPICS_BASE_BIN)/vxComLibrary
```

20.21.1 iocClock

This provides a clock for vxWorks by using Network Time Protocal (NTP) client calls. It is required for all vxWorks IOCs. It also provides the `date` command.

20.21.2 veclist

For VME systems this shows the interrupt vectors.

20.21.3 logMsgToErrlog

This traps all calls to logMsg and sends them to errlogPrintf.

20.21.4 drvTS

This is a driver that supports hardware event systems. It is documented in `TSdriver.html`, which is in the `documentation` directory of base. Unless TSinit is called before iocInit it will not be used.

20.21.5 camacLib.h

This was included with 3.13.

20.21.6 epicsDynLink

This is provides symFindByNameEPICS. It is only provided for device/driver support that has not been converted to use epicsFindSymbol. Some day epicsDynLink will no longer be supported.

20.21.7 module_types.h

It is only provided for device/driver support that has not been converted to use OSI features of base. Some day it will no longer be supported. Instead of using this drivers should accept a configure command that specifies the information provided by `module_types.h`

20.21.8 task_params.h

It is only provided for device/driver support that has not been converted to use OSI features of base. Some day it will no longer be supported.

20.21.9 vxComLibrary

This is a routine that causes iocClock, drvTS, epicsDynLink, logMsgToErrlog and veclist to be loaded.

Chapter 21: Registry

Under vxWorks osiFindGlobalSymbol can be used to dynamically bind to record, device, and driver support and functions for use with subroutine records. Since on some systems this always returns failure, a registry facility is provided to implement the binding. The basic idea is that any storage meant to be "globally" accessable must be registered before it can be accessed by other code.

A perl script is provided that reads the xxxApp.dbd file and produces a C source file containing a routine xxx_registerRecordDeviceDriver, which registers all record/device/driver/function support defined in the xxxApp.dbd file.

21.1 Registry.h

```
int registryAdd(void *registryID,const char *name,void *data);
void *registryFind(void *registryID,const char *name);
int registrySetTableSize(int size);
void registryFree();
int registryDump(void);
```

This is the code which does the work. Each different set of things to register must have its own unique ID. Everything to be registered is stored in the same gpHash table.

Routine registrySetTableSize is provided in case the default hash table size (1024 entries) is not sufficient.

21.2 registryRecordType.h

```
typedef int (*computeSizeOffset)(dbRecordType *pdbRecordType);

typedef struct recordTypeLocation {
struct rset *prset;
computeSizeOffset sizeOffset;
}recordTypeLocation;


int registryRecordTypeAdd(const char *name,recordTypeLocation *prtl);
recordTypeLocation *registryRecordTypeFind(const char *name);
```

Some features:

- Access to both the record support entry table and to the routine which computes the size and offset of each field are provided
- Type safe access is provided.

21.3 registryDeviceSupport.h

```
int registryDeviceSupportAdd(const char *name,struct dset *pdset)
struct dset *registryDeviceSupportFind(const char *name);
```

This provides access to the device support entry table.

21.4 registryDriverSupport.h

```
int registryDriverSupportAdd(const char *name,struct drvet *pdrvet);
struct drvet *registryDriverSupportFind(const char *name);

/* The following function is generated by registerRecordDeviceDriver/pl */
int registerRecordDeviceDriver(DBBASE *pdbbase);
```

This provides access to the driver support table.

21.5 registryFunction.h

```
typedef void (*REGISTRYFUNCTION)(void);

typedef struct registryFunctionRef {
    const char      *name;
    REGISTRYFUNCTION addr;
}registryFunctionRef;

/* c interface definitions */
int registryFunctionAdd(const char *name,REGISTRYFUNCTION func);
REGISTRYFUNCTION registryFunctionFind(const char *name);
int registryFunctionRefAdd(
    registryFunctionRef ref[],int nfunctions);
```

`registryFunctionAdd` registers a single function. `registryFunctionRefAdd` registers several functions.

For example subroutines for subRecord could be registered as follows:

```
#include <stdio.h>
#include "subRecord.h"

typedef long (*processMethod)(subRecord *precord);

static long mySubInit(subRecord *precord, processMethod process)
{
    printf("%s mySubInit process %p\n",precord->name, (void*) process);
    return(0);
}

static long mySubProcess(subRecord *precord)
{
    printf("%s mySubProcess\n",precord->name);
```

```
    return(0);
}
static registryFunctionRef mySubRef[] = {
    {"mySubInit",(REGISTRYFUNCTION)mySubInit},
    {"mySubProcess",(REGISTRYFUNCTION)mySubProcess}
};

void mySub(void)
{
    registryFunctionRefAdd(mySubRef,NELEMENTS(mySubRef));
}
epicsExportRegistrar(mySub);
```

The example registers these functions at application startup using an entry in the dbd file, which are converted by the registerRecordDeviceDriver.pl script into the necessary registration C source code. The dbd file entry is:

```
registrar("mySub")
```

The functions could also be registered using the `epicsRegisterFunction` macro in the C source file:

```
epicsRegisterFunction(mySubInit);
epicsRegisterFunction(mySubProcess);
```

and the `function` keyword in the application database definition:

```
function(mySubInit)
function(mySubProcess)
```

21.6 registerRecordDeviceDriver.c

A version of this is provided for vxWorks. This version makes it unnecessary to use registerRecordDeviceDriver.pl or register other external names. Thus for vxWorks everything can work almost exactly like it did in release 3.13.x

21.7 registerRecordDeviceDriver.pl

This is the perl script which creates a C source file that registers record/device/driver/function support. Make rules:

- execute this script using the dbd file created by dbExpand
- compile the resulting C file
- Make the object file part of the xxxLib file

Chapter 22: Database Structures

22.1 Overview

This chapter describes the internal structures describing an IOC database. It is of interest to EPICS system developers but serious application developers may also find it useful. This chapter is intended to make it easier to understand the IOC source listings. It also gives a list of the header files used by IOC Code.

22.2 Include Files

This section lists the files in base/include that are of most interest to IOC Application Developers:

alarm.h alarmString.h - These files contain definitions for all alarm status and severity values.

cadef.h caerr.h caeventmask.h - These files are of interest to anyone writing channel access clients.

callback.h - The definitions for the General Purpose callback system.

dbAccess.h - Definitions for the runtime database access routines.

dbBase.h - Definitions for the structures used to store an EPICS database.

dbDefs.h - A catchall file for definitions that have no other reasonable place to appear.

dbFldTypes.h - Definitions for `DBF_xxx` and `DBR_xxx` types.

dbScan.h - Definitions for the scanning system.

dbStaticLib.h - The static databases access system.

db_access.h db_addr.h - Old database access.

devLib.h - The device support library

devSup.h - Device Support Modules

drvSup.h - Driver Support Modules

ellLib.h - A library that is provides the same functions as the vxWorks `lstLib`. All routines start with `ell` instead of `lst`. The `ellLib` routines work on both IOCs and on UNIX.

epicsPrint.h errMdef.h - EPICS error handling system

fast_lock.h - The FASTLOCK routines.

freeList.h - A general purpose free list facility

gpHash.h - A general purpose hash library.

guigroup.h - The guigroup definitions.

i**nitHooks.h** - Definitions used by `initHooks.c` routines.

link.h - Link definitions

module_types.h - VME hardware configuration. **SHOULD NOT BE USED BY NEW SUPPORT.**

recSup.h - The record global routines.

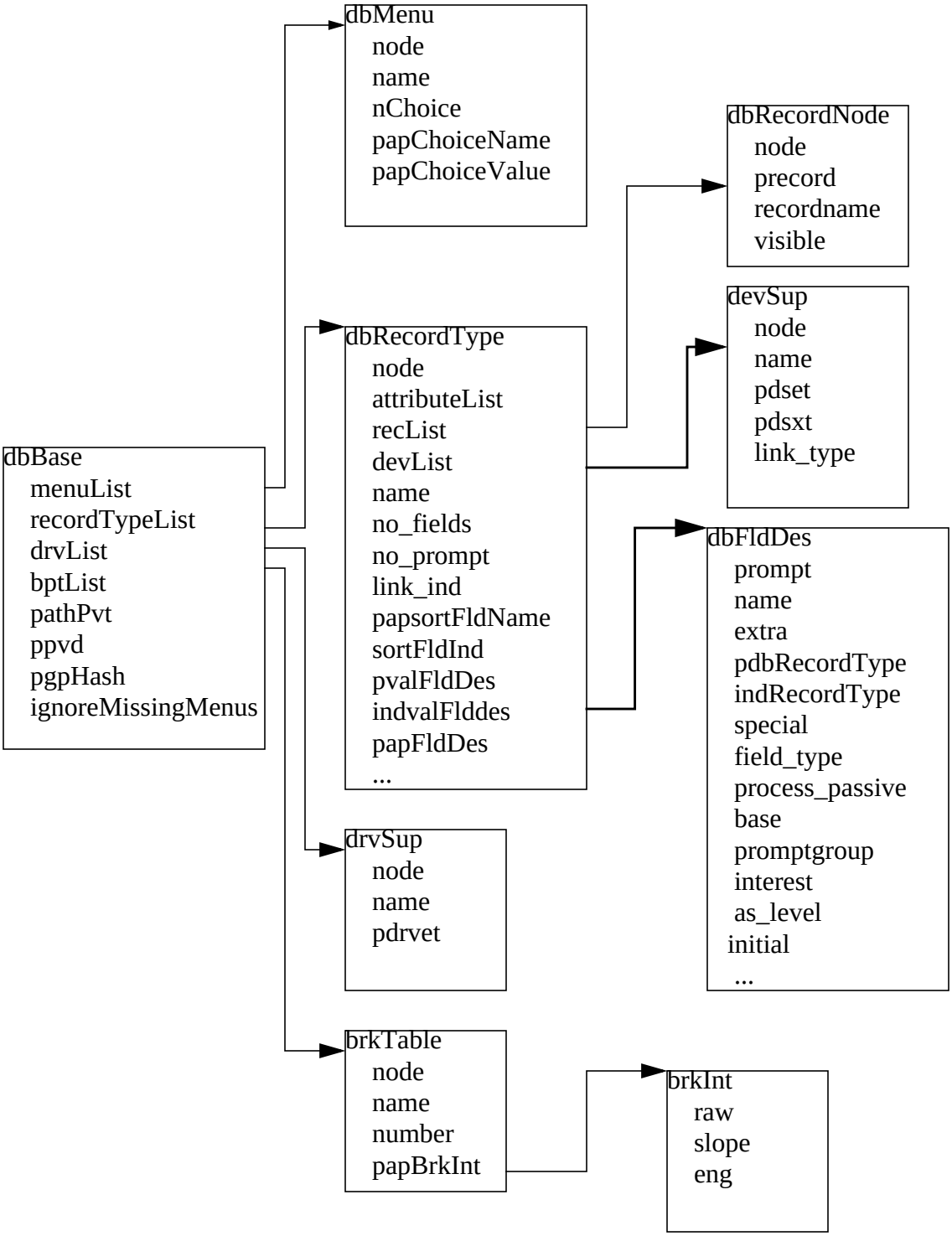
special.h - Definitions for special fields, i.e. `SPC_xxx`.

task_params.h - Definitions for task priorities, stack space, etc.

taskwd.h - Task Watchdog System

tsDefs.h - Time stamp routines. Will also have to look at `base/src/libCom/tsSubr.c`

22.3 Structures



Chapter 23: INDEX

A

AB_IO - link field value . . . 105
Access Security . . . 125
  Configuration File . . . 126
  Initialization . . . 128
Access Security Group . . . 129
Access Security Level . . . 138
add_record . . . 189
addpath . . . 92, 94
adjustment.h . . . 275
adjustToWorstCaseAlignment . . . 275
algorithm . . . 259
Alloc/Free DBENTRY . . . 197
allocate . . . 267
ANSI . . . 69
archclean . . . 40
asAddClient . . . 135
asAddMember . . . 134
ascar . . . 154
asChangeClient . . . 135
asChangeGroup . . . 135
ascheck . . . 128
asCheckGet(. . . 136
asCheckPut . . . 136
asCompute . . . 137
asComputeAllAsg . . . 136
asComputeAsg . . . 137
asdbdump . . . 140, 152
asdbdumpFP . . . 140
asDbGetAsl . . . 139
asDbGetMemberPvt . . . 139
asDump . . . 137
asDumpFP . . . 137
asDumpHag . . . 137
asDumpHagFP . . . 137
asDumpHash . . . 138
asDumpHashFP . . . 138
asDumpMem . . . 138
asDumpMemFP . . . 138
asDumpRules . . . 137
asDumpRulesFP . . . 137
asDumpUag . . . 137
asDumpUagFP . . . 137
ASG . . . 126
ASG - access security configuration . . . 127
asGetClientPvt . . . 136
asGetMemberPvt . . . 135
asInit . . . 120, 129, 139, 152
asInitAsyn . . . 139
asInitFile . . . 134
asInitFP . . . 134
asInitialize . . . 134
ASL . . . 126
asl - field definition rules . . . 96
asl_level - field definition . . . 97
ASL0 . . . 138
ASL1 . . . 138
asphag . . . 140, 153
asphagFP . . . 140
aspmem . . . 140, 153
aspmemFP . . . 140
asprules . . . 140, 153
asprulesFP . . . 140
aspuag . . . 140, 152
aspuagFP . . . 140
asPutClientPvt . . . 136
asPutMemberPvt . . . 135
asPvt in DBADDR . . . 213
asRegisterClientCallback . . . 136
asRemoveClient . . . 136
asRemoveMember . . . 134
asSetFilename . . . 128, 139, 152
asSetSubstitutions . . . 129, 139
asSubInit . . . 129, 140
asSubProcess . . . 129, 140
astac . . . 139
asTrapWriteAfter . . . 136, 142
asTrapWriteBefore . . . 136, 142
asTrapWriteId . . . 142
asTrapWriteListener . . . 142
asTrapWriteMessage . . . 142
asTrapWriteRegisterListener . . . 142
asTrapWriteUnregisterListener . . . 142
asynchronous device support example . . . 185
aToIPAddr . . . 274

B

base - field definition . . . 98
base - field definition rules . . . 96
base.dbd . . . 42
BBGPIB_IO - link field value . . . 106
BIN_INSTALLS . . . 59, 72
BITBUS_IO - link field value . . . 105
borland.bat . . . 77
breakpoint table - database definition . . . 103
Breakpoint Tables . . . 41, 107
Breakpoints . . . 147
breaktable . . . 93
bucketLib.h . . . 255
Build Facility . . . 31
Build software prerequisites . . . 33
BuildingR3.13AppsWithR3.14.html . . . 76
BuildingR3.13ExtensionsWithR3.14.html . . . 76

C

C++ library . . . 259
ca_put_callback . . . 87
Cached Puts . . . 87
CALC - access security configuration . . . 128
CALC_ERR_ . . . 255

calcArgUsage 255
calcErrorStr 255
calcPerform 255
CALLBACK 231
callback.h 231
callbackCancelDelayed 233
callbackGetUser 232–233
callbackInit 119, 232
callbackRequest 232–233
callbackRequestDelayed 233
callbackRequestProcessCallback 232–233
callbackRequestProcessCallbackDelayed 233
callbackSetCallback 232
callbackSetPriority 232
callbackSetProcess 232–233
callbackSetQueueSize 121, 233–234
callbackSetUser 232
calloc 275
callocMustSucceed 275
CAMAC_IO - link field value 105
camacLib.h 312
cancel 266
cantProceed 275
cantProceed.h 275
casr 153
cdCommands 118
Cexp 22
Channel Access 23
channel access link 79
Channel Access Monitors 225
checkAlarms 173
choice 92
choice_string - device definition 101
class templates 259
CLASSES 71
clean 39
ClockTime_Report 151
ClockTime_Shutdown 151
CMPLR 69
comment - Database Definitions 95
Compiler options 44
computeSizeOffset 313
CONFIG 73
CONFIG.CrossCommon 73
CONFIG.gnuCommon 73
CONFIG_ADDONS 73
CONFIG_APP_INCLUDE 35
CONFIG_BASE 73
CONFIG_BASE_VERSION 73
CONFIG_COMMON 73
CONFIG_ENV 73
CONFIG_SITE 34, 73
CONFIG_SITE.Common.target 34
CONFIG_SITE.Common.vxWorksCommon 34
CONFIG_SITE.host.Common 34
CONFIG_SITE.host.host 34
CONFIG_SITE.host.target 34
CONFIG_SITE_ENV 34, 73
Configurating base 34
Configure files 73
configure/os File 74
configure/tool File 74
CONSTANT - link field value 105
constant link 79
ConvertingR3.13AppsToR3.14.html 76
convertRelease.pl 74–75
coreRelease 155
coreRelese 119
cp.pl 75
createTimer 266
cross target 32
CROSS_COMPILER_HOST_ARCHS 32
CROSS_COMPILER_TARGET_ARCHS 32, 35–36
CROSS_OPT 69
CROSS_WARN 69
cvsclean 40, 75
cvt_dbaddr - Record Support Routine 176
cvtBitsToUlong 260
cvtCharToString 260
cvtDoubleToCompactString 260
cvtDoubleToExpString 260
cvtDoubleToString 260
cvtFast.h 260
cvtFloatToCompactString 260
cvtFloatToExpString 260
cvtFloatToString 260
cvtLongToHexString 260
cvtLongToOctalString 260
cvtLongToString 260
cvtShortToString 260
cvtUcharToString 260
cvtUlongToBits 260
cvtUlongToString 260
cvtUshortToString 260
CXXCMPLR 69

D

database access routines - List of 214
Database Definition 42–43
Database Definition File 91
database definitions 91
Database Files 43
Database Format - Summary 91
database link 79
Database Link Guidelines 82
Database Links 79
Database Locking 80
Database Scanning 81
DB 44, 71
DB install files 44
DB_INSTALLS 44, 71
DB_MAX_CHOICES 211
db_post_events 225
dba 146
dbAccess.h 211
dbAdd 212
dbAddPath 198
DBADDR 213
dbAllocBase 196
dbAllocEntry 197
dbAllocForm 206
dbap 148
dbb 148
dbBkptInit 120
dbBufferSize 221

dbc . . . 148
dbCaAddLink . . . 227
dbCaAddLinkCallback . . . 227
dbCaGetAlarmLimits . . . 230
dbCaGetAttributes . . . 229
dbCaGetControlLimits . . . 230
dbCaGetGraphicLimits . . . 230
dbCaGetLink . . . 228
dbCaGetPrecision . . . 230
dbCaGetSevr . . . 229
dbCaGetTimeStamp . . . 229
dbCaGetUnits . . . 230
dbCaLinkInit . . . 119, 227
dbCaPause . . . 121
dbCaPutLink . . . 228
dbCaPutLinkCallback . . . 228
dbcar . . . 154, 156
dbCaRemoveLink . . . 228
dbCaRun . . . 121
dbCopyEntry . . . 198
dbCopyEntryContents . . . 198
dbCopyRecord . . . 202–203
dbCreateRecord . . . 202
dbCvtLinkToConstant . . . 205
dbCvtLinkToPvlink . . . 205
DBD . . . 41–43, 71
dbd . . . 148
DBD install files . . . 43
DBD_INSTALLS . . . 43, 71
dbDefs.h . . . 211, 275
dbDeleteInfo . . . 208
dbDeleteRecord . . . 202
DBDINC . . . 41–42, 71
dbDumpBreaktable . . . 208
dbDumpDevice . . . 158, 208
dbDumpDriver . . . 159, 208
dbDumpField . . . 158
dbDumpFldDes . . . 208
dbDumpFunction . . . 208
dbDumpMenu . . . 158, 208
dbDumpPath . . . 208
dbDumpRecord . . . 208
dbDumpRecords . . . 159, 209
dbDumpRecordType . . . 158, 208
dbDumpRegistrar . . . 208
dbDumpVariable . . . 208
DBE_ALARM . . . 175
DBE_LOG . . . 175
DBE_VAL . . . 175
dbel . . . 154
dbExpand . . . 42, 112, 209
DBF_CHAR . . . 211
DBF_DEVICE . . . 212
DBF_DOUBLE . . . 212
DBF_ENUM . . . 212
DBF_FLOAT . . . 212
DBF_FWDLINK . . . 212
DBF_INLINK . . . 212
DBF_LONG . . . 212
DBF_MENU . . . 212
DBF_NOACCESS . . . 212
DBF_OUTLINK . . . 212
DBF_SHORT . . . 212
DBF_STRING . . . 211
DBF_UCHAR . . . 212
DBF_ULONG . . . 212
DBF_USHORT . . . 212
dbFindBrkTable . . . 208
dbFindField . . . 203
dbFindInfo . . . 207
dbFindMenu . . . 204
dbFindRecord . . . 202
dbFindRecordType . . . 199
dbFinishEntry . . . 197
dbFirstField . . . 200
dbFirstInfo . . . 207
dbFirstRecord . . . 202
dbFirstRecordType . . . 199
dbFldTypes.h . . . 211
dbFoundField . . . 200, 203
dbFreeBase . . . 197
dbFreeEntry . . . 197
dbFreeForm . . . 206
dbGet . . . 217
dbGetDefaultName . . . 201
dbGetField . . . 217
dbGetFieldIndex . . . 222
dbGetFieldName . . . 200
dbGetFieldType . . . 200
dbGetFormPrompt . . . 206
dbGetFormValue . . . 206
dbGetInfo . . . 208
dbGetInfoName . . . 207
dbGetInfoPointer . . . 207
dbGetInfoString . . . 207
dbGetLink . . . 217
dbGetLinkDBFtype . . . 223
dbGetLinkField . . . 205
dbGetLinkType . . . 205
dbGetMenuChoices . . . 204
dbGetMenuIndex . . . 204
dbGetMenuIndexFromString . . . 204
dbGetMenuStringFromIndex . . . 204
dbGetNelements . . . 222
dbGetNFields . . . 200
dbGetNLinks . . . 205
dbGetNMenuChoices . . . 204
dbGetNRecords . . . 202
dbGetNRecordTypes . . . 199
dbGetPdbAddrFromLink . . . 222
dbGetPrompt . . . 201
dbGetPromptGroup . . . 201
dbGetRange . . . 203
dbGetRecordAttribute . . . 201
dbGetRecordName . . . 202
dbGetRecordTypeName . . . 200
dbGetRset . . . 222
dbGetString . . . 203
dbgf . . . 146
dbgrep . . . 146
dbhcr . . . 150, 157
dbInitEntry . . . 197
dbInvisibleRecord . . . 203
dbior . . . 149
dbIsDefaultValue . . . 203
dbIsLinkConnected . . . 222
dbIsValueField . . . 222
dbIsVisibleRecord . . . 203

dbl 145
dbLoadDatabase 112
dbLoadRecords 113
dbLoadTemplate 113
dbLockGetLockId 226
dbLockInitRecords 120, 226
dbLockSetGblLock 226
dbLockSetGblUnlock 226
dbLockSetMerge 226
dbLockSetRecordLock 227
dbLockSetSplitSl 226
dblsr 156
dbmf.h 261
dbmfFree 261
dbmfFreeChunks 261
dbmfInit 261
dbmfMalloc 261
dbmfShow 261
dbNameToAddr 216
dbNextField 200
dbNextInfo 207
dbNextRecord 202
dbNextRecordType 199
dbNotifyAdd 221
dbNotifyCancel 221
dbNotifyCompletion 221
dbnr 147
dbp 148
dbPath 198
dbpf 146
dbpr 147
dbProcess 224
dbPut 219
dbPutAttribute 107, 224
dbPutField 218
dbPutForm 206
dbPutInfo 208
dbPutInfoPointer 207
dbPutInfoString 207
dbPutLink 218
dbPutMenuIndex 204
dbPutNotify 87, 219–220
dbPutNotifyInit 120
dbPutRecordAttribute 201
dbPutString 203
dbPvdDump 159, 208
dbPvdTableSize 121
DBR_AL_DOUBLE 215
DBR_AL_LONG 215
DBR_CHAR 215
DBR_CTRL_DOUBLE 215
DBR_CTRL_LONG 215
DBR_DOUBLE 215
DBR_ENUM 215
DBR_ENUM_STRS 215
dbr_field_type in DBADDR 213
DBR_FLOAT 215
DBR_GR_DOUBLE 215
DBR_GR_LONG 215
DBR_LONG 215
DBR_PRECISION 215
DBR_PUT_ACKS 215–216
DBR_PUT_ACKT 215–216
DBR_SHORT 215
DBR_STATUS 215
DBR_STRING 215
DBR_TIME 215
DBR_UCHAR 215
DBR_ULONG 215
DBR_UNITS 215
DBR_USHORT 215
dbReadDatabase 198
dbReadDatabaseFP 198
dbReadTest 115
dbRenameRecord 203
dbReportDeviceConfig 208
dbs 148
dbScan.h 239
dbScanFwdLink 224
dbScanLink 224
dbScanLock 226
dbScanPassive 224
dbScanUnlock 226
dbstat 149
dbtgf 155
dbToMenuH 109
dbToRecordtypeH 109–110
dbtpf 155
dbtpn 156
dbtr 147
dbTranslateEscape 275
dbValueSize 221
dbVerify 203
dbVerifyForm 206
dbVisibleRecord 203
dbWriteBreaktable 198
dbWriteBreaktableFP 198
dbWriteDevice 198
dbWriteDeviceFP 198
dbWriteDriver 198
dbWriteDriverFP 198
dbWriteFunctionFP 198
dbWriteMenu 198
dbWriteMenuFP 198
dbWriteRecord 199
dbWriteRecordFP 199
dbWriteRecordType 198
dbWriteRecordTypeFP 198
dbWriteRegistrarFP 198
dbWriteVariableFP 198
DCT_FWDLINK 196
DCT_INLINK 196
DCT_INTEGER 196
DCT_LINK_CONSTANT 205
DCT_LINK_DEVICE 205
DCT_LINK_FORM 205
DCT_LINK_PV 205
DCT_MENU 196
DCT_MENUFORM 196
DCT_NOACCESS 196
DCT_OUTLINK 196
DCT_REAL 196
DCT_STRING 196
del_record 190
destroy 266
devAddressMap 309
devAllocAddress 309
devConnectInterrupt 311

devConnectInterruptVME . . . 310
devCreateMask . . . 310
devDisableInterruptLevel . . . 311
devDisableInterruptLevelVME . . . 310
devDisconnectInterrupt . . . 311
devDisconnectInterruptVME . . . 310
devEnableInterruptLevel . . . 311
devEnableInterruptLevelVME . . . 310
device . . . 92
device - database definition . . . 100
Device Support Entry Table . . . 169
devInterruptInUseVME . . . 310
devNmlToDig . . . 310
devNoResponseProbe . . . 308
devReadProbe . . . 308
devRegisterAddress . . . 309
devUnregisterAddress . . . 309
devWriteProbe . . . 308
Directory structure . . . 31
distclean . . . 39
DLL_LIBS . . . 50
Doc file . . . 53
DOCS . . . 53, 71
Documentation Files . . . 75
driver . . . 92
driver - database definition . . . 101
Driver Support Entry Table Example . . . 192
drvet_name - driver definition . . . 101
drvTS . . . 312
DSET . . . 169
dset - dbCommon . . . 183
dset_name - device definition . . . 101
dtyp - dbCommon . . . 183

E

E2DB_FLAGS . . . 71
ellAdd . . . 262
ellConcat . . . 262
ellCount . . . 262
ellDelete . . . 262
ellExtract . . . 262
ellFind . . . 262
ellFirst . . . 262
ellFree . . . 262
ellGet . . . 262
ellInit . . . 262
ellInsert . . . 262
ellLast . . . 262
ellLib.h . . . 262
ELLLIST . . . 262
ellNext . . . 262
ELLNODE . . . 262
ellNStep . . . 262
ellNth . . . 262
ellPrevious . . . 262
ellVerify . . . 262
eltc . . . 149, 164
eng_value - breakpoint table . . . 103
Environment Prerequisites . . . 33
Environment Variables . . . 123
envPaths . . . 117
EPICS . . . 7, 23
  Basic Attributes . . . 23
  Hardware/Software Platforms . . . 24
  Overview . . . 7
EPICS_CA_ADDR_LIST . . . 123
EPICS_CA_AUTO_ADDR_LIST . . . 123
EPICS_CA_CONN_TMO . . . 123
EPICS_CA_MAX_ARRAY_BYTES . . . 123
EPICS_CA_REPEATER_PORT . . . 123
EPICS_CA_SERVER_PORT . . . 123
EPICS_CAS_BEACON_PERIOD . . . 123
EPICS_HOST_ARCH . . . 33
EPICS_IOC_LOG_FILE_COMMAND . . . 165
EPICS_IOC_LOG_FILE_LIMIT . . . 165
EPICS_IOC_LOG_FILE_NAME . . . 165
EPICS_IOC_LOG_INET . . . 123
EPICS_IOC_LOG_PORT . . . 123, 166
EPICS_THREAD_ONCE_INIT . . . 294
EPICS_TS_NTP_INET . . . 123
epicsAddressType . . . 309
epicsAddressTypeName . . . 309
epicsAlgorithm.h . . . 259
epicsAssert . . . 282
epicsAtExit . . . 259
epicsAtThreadExit . . . 259
epicsConvert.h . . . 275
epicsConvertDoubleToFloat . . . 275
epicsDynLink . . . 312
epicsEndian.h . . . 282
epicsEnvSet . . . 123
epicsEnvShow . . . 124, 155
epicsEvent . . . 282
epicsEvent.h . . . 282
epicsEventCreate . . . 284
epicsEventDestroy . . . 284
epicsEventId . . . 284
epicsEventMustCreate . . . 284
epicsEventMustWait . . . 284
epicsEventShow . . . 284
epicsEventSignal . . . 284
epicsEventTryWait . . . 284
epicsEventWait . . . 284
epicsEventWaitError . . . 283
epicsEventWaitOK . . . 283
epicsEventWaitStatus . . . 283
epicsEventWaitTimeout . . . 283
epicsEventWaitWithTimeout . . . 284
epicsExit . . . 259
epicsExitCallAtExits . . . 259
epicsExitCallAtThreadExits . . . 259
epicsExport . . . 15
epicsExportAddress . . . 15, 102
epicsExportRegistrar . . . 101
epicsFindSymbol . . . 284
epicsFindSymbol.h . . . 284
epicsGeneralTime . . . 285
epicsGeneralTime.h . . . 285
epicsGetStderr . . . 292
epicsGetStdin . . . 292
epicsGetStdout . . . 292
epicsGetThreadStderr . . . 292
epicsGetThreadStdin . . . 292
epicsGetThreadStdout . . . 292
EpicsHostArch . . . 76

EpicsHostArch.pl 34, 76
epicsInterrupt 287
epicsInterrupt.h 287
epicsInterruptContextMessage 287
epicsInterruptIsInterruptContext 287
epicsInterruptLock 287
epicsInterruptType 311
epicsInterruptUnlock 287
epicsMath 288
epicsMath.h 288
epicsMax 259
epicsMessageQueue 288–290
epicsMessageQueueCreate 290
epicsMessageQueueDestroy 290
epicsMessageQueuePending 290
epicsMessageQueueReceive 290
epicsMessageQueueReceiveWithTimeout 290
epicsMessageQueueSend 290
epicsMessageQueueSendWithTimeout 290
epicsMessageQueueShow 290
epicsMessageQueueTryReceive 290
epicsMessageQueueTrySend 290
epicsMin 259
epicsMutex 290
epicsMutex.h 290
epicsMutexCreate 291
epicsMutexDestroy 291
epicsMutexId 291
epicsMutexLock 291
epicsMutexLockError 290
epicsMutexLockOK 290
epicsMutexLockStatus 290
epicsMutexLockTimeout 290
epicsMutexMustCreate 291
epicsMutexMustLock 291
epicsMutexShow 291
epicsMutexShowAll 291
epicsMutexTryLock 291
epicsMutexUnlock 291
epicsParamShow 155
epicsPrintf 163
epicsPrtEnvParams 124
epicsRegisterFunction 15, 103, 315
epicsRingBytes.h 262
epicsRingBytesCreate 262
epicsRingBytesDelete 262
epicsRingBytesFlush 262
epicsRingBytesFreeBytes 262
epicsRingBytesGet 262
epicsRingBytesId 262
epicsRingBytesIsEmpty 262
epicsRingBytesIsFull 262
epicsRingBytesPut 262
epicsRingBytesSize 262
epicsRingBytesUsedBytes 262
epicsRingPointer 263
epicsRingPointer.h 263, 288
epicsRtemsInitHooks.h 119
epicsRtemsInitPostSetBootConfigFromNVRAM 119
epicsRtemsInitPreSetBootConfigFromNVRAM 118
epicsScanDouble 292
epicsScanFloat 292
epicsSetThreadStderr 292
epicsSetThreadStdin 292
epicsSetThreadStdout 292
epicsShareAPI 277
epicsShareFunc 277
epicsSnprintf 292
epicsStdio 292
epicsStdio.h 292
epicsStdioRedirect 293
epicsStdlib 292
epicsStdlib.h 292
epicsStdoutPrintf 292
epicsStrCaseCmp 275
epicsStrDup 276
epicsStrGlobMatch 276
epicsString.h 275
epicsStrnCaseCmp 275
epicsStrPrintEscaped 276
epicsStrSnPrintEscaped 276
epicsStrtod 292
epicsStrtok_r 276
epicsSwap 259
epicsTempFile 292
epicsTempName 292
epicsThread 293, 297
epicsThread.h 293
epicsThreadBooleanStatus 294
epicsThreadBooleanStatusFail 294
epicsThreadBooleanStatusSuccess 294
epicsThreadCreate 294–295
epicsThreadExitMain 294–295
EPICSTHREADFUNC 293
epicsThreadGetId 294, 296
epicsThreadGetIdSelf 294, 296
epicsThreadGetName 294, 296
epicsThreadGetNameSelf 294, 296
epicsThreadGetPriority 294–295
epicsThreadGetPrioritySelf 294–295
epicsThreadGetStackSize 294–295
epicsThreadHighestPriorityLevelBelow 294–295
epicsThreadId 294
epicsThreadInit 294
epicsThreadIsEqual 294, 296
epicsThreadIsOkToBlock 294, 296
epicsThreadIsSuspended 294, 296
epicsThreadLowestPriorityLevelAbove 294, 296
epicsThreadOnce 294–295
epicsThreadOnceId 294
epicsThreadPriorityChannelAccessServer 294
epicsThreadPriorityHigh 294
epicsThreadPriorityLow 293
epicsThreadPriorityMax 293
epicsThreadPriorityMedium 294
epicsThreadPriorityMin 293
epicsThreadPriorityScanHigh 294
epicsThreadPriorityScanLow 294
epicsThreadPrivateCreate 295–296
epicsThreadPrivateDelete 295–296
epicsThreadPrivateGet 295, 297
epicsThreadPrivateId 295
epicsThreadPrivateSet 295, 297
epicsThreadResume 294–295
epicsThreadRunable 297
epicsThreadSetOkToBlock 295–296
epicsThreadSetPriority 294–295
epicsThreadShow 295–296

epicsThreadShowAll . . . 295–296
epicsThreadSleep . . . 294, 296
epicsThreadSleepQuantum . . . 294, 296
epicsThreadStackBig . . . 294
epicsThreadStackMedium . . . 294
epicsThreadStackSizeClass . . . 294
epicsThreadStackSmall . . . 294
epicsThreadSuspendSelf . . . 294–295
epicsTime . . . 299–300, 302, 305
epicsTime.h . . . 299
epicsTimeEvent . . . 300, 302
epicsTimeGetCurrent . . . 286
epicsTimeGetEvent . . . 286
epicsTimer . . . 265–266
epicsTimer.h . . . 265
epicsTimerId . . . 268
epicsTimerNotify . . . 266
epicsTimerQueueActive . . . 267
epicsTimerQueueId . . . 268
epicsTimerQueueNotify . . . 267
epicsTimerQueuePassive . . . 267
epicsTimeStamp . . . 299
epicsTypes.h . . . 276
epicsUnitTest.h . . . 277
epicsVprintf . . . 163
epicsVsnprintf . . . 292
errlog Listeners . . . 163
errlogAddListener . . . 163
errlogFatal . . . 162
errlogFlush . . . 162
errlogGetSevEnumString . . . 162
errlogGetSevToLog . . . 162
errlogInfo . . . 162
errlogInit . . . 121, 164
errlogInit2 . . . 164
errlogListener . . . 163
errlogMajor . . . 162
errlogMessage . . . 161
errlogMinor . . . 162
errlogPrintf . . . 161, 180
errlogRemoveListener . . . 163
errlogSetSevToLog . . . 162
errlogSevEnum . . . 162
errlogSevPrintf . . . 162
errlogSevVprintf . . . 162
errlogThread . . . 164
errlogVprintf . . . 161
errMessage . . . 162
errPrintf . . . 162–163
Escape Sequence . . . 93
Event . . . 237
Event - Scan Type . . . 237
Event Scanning . . . 242
EVNT - Scan Related Field . . . 238
exit . . . 249
expire . . . 266
Extended device support . . . 183, 188
extra - field definition rules . . . 96
extra_info - field definition . . . 98

F

field . . . 92
field definition rules . . . 96
field value - record instance definition . . . 104
field_name - field definition . . . 96
field_name - record instance definition . . . 104
field_size in DBADDR . . . 213
field_type - field definition . . . 96
field_type in DBADDR . . . 213
filename extension conventions . . . 94
filterWarnings.pl . . . 75
freeList.h . . . 271
freeListCalloc . . . 271
freeListCleanup . . . 271
freeListFree . . . 271
freeListInitPvt . . . 271
freeListItemsAvail . . . 271
freeListMalloc . . . 271
fullpathname . . . 75
function . . . 15, 315
function templates . . . 259
function_name - function definition . . . 103
function_name - registrar definition . . . 101
FWDLINK . . . 79

G

generalTime . . . 285
generalTime_Init . . . 285
generalTimeCreateSyncTimer . . . 286
generalTimeCurrentTpName . . . 285
generalTimeCurrentTpRegister . . . 286
generalTimeEventTpName . . . 285
generalTimeEventTpRegister . . . 286
generalTimeGetErrorCounts . . . 285
generalTimeGetExceptPriority . . . 286
generalTimeReport . . . 151, 285
generalTimeResetErrorCounts . . . 285
generalTimeSup.h . . . 286
get_alarm_double Record Support Routine . . . 179
get_array_info - Record Support Routine . . . 177
get_control_double - Record Support Routine . . . 179
get_enum_str - record Support Routine . . . 178
get_enum_strs - record Support Routine . . . 178
get_graphic_double - example . . . 172
get_graphic_double - Record Support Routine . . . 178
get_ioint_info . . . 241
get_ioint_info - device support routine . . . 187
get_precision - Record Support Routine . . . 177
get_units - .example . . . 172
get_units - Record Support Routine . . . 177
getExpireDelay . . . 266
getExpireInfo . . . 266
gft . . . 157
GNU make . . . 33
gnumake . . . 39
gphAdd . . . 272
gpHash.h . . . 271
gphDelete . . . 272
gphDump . . . 272

gphDumpFP 272
GPHENTRY 271
gphFind 272
gphFreeMem 272
gphInitPvt 271
GPIB_IO - link field value 105
grecord 93
gui_group - field definition 97
Guidelines for Asynchronous Records 85
Guidelines for Synchronous Records 84

H

HAG 126–128
Header dependencies 40
help 249
Host makefile targets 37
HOST_OPT 69
HOST_WARN 69
Html 53
HTMLS 53, 71
HTMLS_DIR 71

I

I/O Event - Scan Type 237
I/O Event scanned 237
I/O Event Scanning 240, 243
INC 53, 70
include 92
include - Database Definitions 94
Include File Generation 109
Include files 53
Infinite Loop 86
INFIX_TO_POSTFIX_SIZE 255
info_name - record instance definition 106
info_value - record instance definition 106
Infomation item pointer 107
Information Item 107
init - device support routine 187
init - Record Support Routine 176
init_record - device support routine 187
init_record - example 170
init_record - record support routine 176
init_value - field definition 97
initDatabase 120
initDevSup 120
initDrvSup 119
initHookFunction 122
initHookName 122
initHookRegister 122
initHooks 122
initHookState 122
initial - field definition rules 96
Initialize Logging 124
initialProcess 120
initPeriodic 244
initRecSup 120
INLINK 79
INP - access security configuration 128
Input/Output Controller 7
  Hardware/Software Platforms 24
  Software Components 25
INPUTRC 250
INST_IO - link field value 106
Install Directories 31
Install Directory definitions 34
INSTALL_LOCATION 31, 34, 72
INSTALL_LOCATION_APP 31
INSTALL_LOCATION_EXTENSIONS 31
installEpics.pl 74–75
Installing Other Binaries 59
Installing Other Libraries 60
installLastResortEventProvider 151, 285
interest - field definition rules 96
interest_level - field definition 98
interruptAccept 121
IOC 23
  See Input/Out Controller
IOC Error Logging 161
Ioc makefile targets 37
iocBuild 119, 121
iocClock 312
iocInit 119
iocLogClient 166
iocLogInit 124
iocLogServer 165
iocPause 119, 121
iocRun 119, 121
iocsh 250
iocsh.h 250
IOCSH_HISTSIZE 250
IOCSH_PS1 250
iocshArg 251
iocshCmd 250
iocshFuncDef 251
iocshRegister 251
iocshSystemCommand 249
isinf 288
isnan 288
ISO C++ 259

J

JAR 61, 71
JAR_INPUT 61, 72
JAR_MANIFEST 61, 72
JAVA 61
java C header file 71
Java class files 60
Java classes 71
Java Example 61
Java jar file 61
Java native methods 62
JAVAINC 62, 71

K

Keywords 92
KnownProblems.html 76

L

LAN 23
Lex and yac 54
LEXOPT 71
LIB_INSTALLS 60, 72
LIB_LDFLAGS 69
LIB_LIBS 49–50, 67
LIB_OBJLIBS 48, 66
LIB_OBJS 48, 65
LIB_RCS 60
LIB_SRCS 47, 65
LIB_SYS_LIBS 50, 67
LIBOBJS 49
Libraries 46
LIBRARY 63
Library example 50
Library link order 50
library name 46
Library object file 48
Library Source file 47
Library version number 50
LIBRARY_HOST 47, 63–64
LIBRARY_IOC 46, 64
LIBSRCS 47, 65
Linear Conversion 107
link options 44
link.h 211
LINK_ALARM 80
link_type - device definition 100
LINR 107
Loadable libraries 51
LOADABLE LIBRARY 64
LOADABLE_LIBRARY 51
LOADABLE_LIBRARY_HOST 51, 64
Local Area Network
  Hardware/Software Platforms 24
logClientCreate 272
logClientFlush 272
logClientId 272
logClientInit 272
logClientSend 272
logClientSendMessage 273
logClientShow 272

M

macCreateHandle 273
macDeleteHandle 274
macEnvExpand 274
macExpandString 273
macGetValue 273
macInstallMacros 274
macLib.h 273
macParseDefns 274
macPopScope 274
macPushScope 274
macPutValue 273
macReportMacros 274
Macro Substitution 93
macSuppressWarning 273
Make 39
Make commands 39
Make targets 40
makeConfigAppInclude.pl 74
Makefile 74
Makefiles 37–38
makeIncludeDbd 75
makeMakefile 75
makeMakefileInclude.pl 75
malloc 275
mallocMustSucceed 275
MANIFEST 72
MAX_STRING_SIZE 211
Maximize Severity 80
menu 92
menu - field definition rules 96
menuConvert 107
Menus 42
menuScan.dbd 238
mkdir.pl 75
mkmf.pl 75
module_types.h 312
monitor - example 174
MOTLOAD 21
MS 80
MSI 44
Multiple Definitions 94
munch.pl 75
mv.pl 75

N

name - breakpoint table 103
name_CFLAGS 45, 68
name_CPPFLAGS 46, 68
name_CXXFLAGS 45, 68
name_DEPENDS 44
name_DIR 67
name_DLL_LIBS 50
name_INCLUDES 45, 69
name_LDFLAGS 46, 69
name_LDOBJS 49, 56, 66
name_LIBS 49–50, 57, 67
name_OBJLIBS 48, 55, 66
name_OBJS 48, 55, 66
name_RCS 60, 72
name_SNCFLAGS 71
name_SRCS 47, 52, 56, 65
name_SYS_LIBS 50, 57, 67
name_TEMPLATE 44
NMS 80
no_elements in DBADDR 213
NOTRAPWRITE 127
NPP 80
NTP 285
NTPTime_Report 151

O

Object Files 52

OBJLIB 51, 64
OBJLIB_OBJS 51, 64
OBJLIB_SRCS 51, 64
OBJS 52, 70
OBJS_HOST 52, 70
OBJS_IOC 52, 70
Operator Interface
  Hardware/Software Platforms 24
OPI 23
OS_CLASS 36
osclass 36
OSI_PATH_LIST_SEPARATOR 277
OSI_PATH_SEPARATOR 277
osiFindGlobalSymbol 284
osiMutex.h 306
osiPoolStatus.h 306
osiProcess.h 307
osiSem.h 307
osiSigPipeIgnore.h 307
osiSock.h 274, 308
osiSufficentSpaceInPool 306
OUTLINK 79
Overview of Record Processing 167
PROD_RCS 60
PROD_SRCS 56, 65
PROD_SYS_LIBS 58, 67
PROD_VERSION 58
product libraries 49, 56
Product link order 57
product name 54
product object file 55
product source file 56
product version number 58
Products 54
prompt - field definition rules 96
prompt_value - field definition 97
. 96
Psuedo field 107
put_array_info - Record Support Routine 177
put_enum_str - Record Support Routine 178
putNotify 87
putNotifyCanceled 221
putNotifyInit 220
putNotifyOK 221
PV_LINK - link field value 105
PVNAME_SZ 211

P

Passive 237
Passive - Scan Type 237
path 92
path - Database Definitions 94
Path requirements 33
pdbbase 195
Periodic - Scan Type 237
Periodic Scanning 244
periodicTask 245
Perl 33
pfield in DBADDR 213
pfldDes in DBADDR 213
pft 157
PHAS - Scan Related Field 238
POSIX 41
Posix C source code 41
post_event 240, 243
postfix 255
postfix.h 255
PP 80
pp - field definition rules 96
pp_value - field definition 98
PPCBUG 21
precord - DBADDR 213
PRIO - Scan Related Field 238
process - example 171
process - Record Support Routine 176
process - record support routine 82
Process Passive 80
PROD 54, 62
PROD_HOST 54
PROD_IOC 54, 62
PROD_LDFLAGS 69
PROD_LIBS 57, 67
PROD_OBJLIBS 55, 66
PROD_OBJS 55, 65

Q

Quoted String 93

R

RANLIBFLAGS 71
raw_value - breakpoint table 103
RCS 60, 72
README.1st 75
README.darwin.html 76
README.hpux 76
README.html 75
README.niCpu030 76
README.WIN32 75
realclean 39
realuninstall 39
rebuild 39
recGblDbaddrError 180
recGblFwdLink 181
recGblGetAlarmDouble 181
recGblGetControlDouble 181
recGblGetGraphicDouble 180
recGblGetPrec 181
recGblGetTimeStamp 181
recGblInitConstantLink 181
recGblRecordError 180
recGblRecsupError 180
recGblResetAlarms 179
recGblSetSevr 179
record 93
record attribute 107
record instance - database definition 104
Record Instance File 91
Record Processing 82
Record Support Entry Table 168

record type - Database Definition 95
Record Type Definitions 41
record_name - record instance definition 104
record_type - device definition 100
record_type - record instance definition 104
record_type - record type definition 96
recordtype 92
Registering support routines 43
registerRecordDeviceDriver 314
registerRecordDeviceDriver.c 315
registerRecordDeviceDriver.pl 315
registrar 15, 93, 252
  iocsh commands 252
registrar - database defintion 101
Registry.h 313
registryAdd 313
registryDeviceSupport.h 314
registryDeviceSupportAdd 314
registryDeviceSupportFind 314
registryDriverSupport.h 314
registryDriverSupportAdd. 314
registryDriverSupportFind 314
registryDump 313
registryFind 313
registryFree 313
registryFunction.h 314
registryFunctionAdd 314
registryFunctionFind. 314
registryFunctionRef 314
registryFunctionRefAdd 314
registryRecordTypeAdd 313
registrySetTableSize 313
RELEASE 35–36, 73
release 267
RELEASE_DBDFLAGS 35
RELEASE_INCLUDES 35
RELEASE_NOTES.html 76
ReleaseChecklist.html. 76
replaceVAR.pl 75
report - device support routine 187
report - Record Support Routine. 175
resource files 60
resourceLib.h. 260
RF_IO - link field value 106
ringPointer. 263
ringPointerCreate 264
ringPointerDelete 265
ringPointerFlush 265
ringPointerGetFree 265
ringPointerGetSize 265
ringPointerGetUsed. 265
ringPointerId 264
ringPointerIsEmpty 265
ringPointerIsFull 265
ringPointerPop 265
ringPointerPush. 265
rm.pl 75
RSET. 168
RSET - example 169
rsrv_init 121
rsrv_pause 121
rsrv_run 121
RULE 128
RULES 73
RULES.Db 73
RULES.ioc 74
RULES_ARCHS. 73
RULES_BUILD 73
RULES_DIRS. 74
RULES_INCLUDE 35
RULES_JAVA 74
RULES_TOP. 74
runTest. 278
runTestFunc. 277

S

SCAN - Scan Related Field 237
Scan Once - Scan Type 237
Scan Related Database Fields 237
SCAN_1ST_PERIODIC. 239
scanAdd. 239
scanDelete 239
scanInit 239
scanIoInit. 243
scanIoRequest 244
scanOnce 122, 245
scanOnceSetQueueSize. 121, 245
scanPause 121, 239
scanpel. 150
scanPeriod 240
scanpiol 150
scanppl 150
scanRun. 121, 239
SCH2EDIF_FLAGS 71
SCRIPT. 52
SCRIPT_HOST 53
SCRIPT_IOC 53
SCRIPTS. 70
Scripts 52
SCRIPTS_HOST 70
SCRIPTS_IOC 70
secPastEpoch. 299
SHARED_LIBRARIES 33, 46, 64
shareLib.h 277
show 249
SHRLIB_VERSION. 50, 64
Site.cshrc. 76
Site.profile. 76
size - field definition rules. 96
size_value - field definition. 98
Slope Conversion 107
SNCFLAGS 71
Source file dirs 40
SPC_ALARMACK. 97
SPC_AS 98
SPC_CALC. 98
SPC_DBADDR. 98
SPC_LINCONV 98
SPC_MOD 98
SPC_NOMOD 97
SPC_RESET 98
SPC_SCAN. 97
special - field definition rules 96
special - Record Support Routine 176
special in DBADDR 213

special_value - field definition 97
Specifying libraries 56
Specifying libraries dependancies. 49
spy 249
SRC_DIRS 41
SRCS. 47, 56, 64
standard C++ library 259
start 266
Startup Files 76
Startup files 34
State Notation Programs 52
STATIC_BUILD 69
status codes 164
std::max. 259
std::min 259
std::swap 259
STRICT. 69
strtod 292
struct dbAddr 212
struct dsxt 189
struct putNotify 220
synchronous device support example 183
SYS_PROD_LIBS 57, 68
system 249

T

T_A 37
Table of Makefile definitions 62
TARGETS. 59, 72
task_params.h 312
taskwd.h 235
taskwdAnyInsert 236
taskwdAnyRemove 236
taskwdInit 119
taskwdInsert 235
taskwdMonitor 235
taskwdMonitorAdd 235
taskwdMonitorDel 235
taskwdRemove 235
taskwdShow 236
TCL libraries. 60
TCLINDEX. 60, 70
TCLLIBNAME. 60, 70
TEMPLATES 54, 71
Templates 54
templates 259
TEMPLATES_DIR 71
TERM 250
Test

Harness 277
Test Products. 58
Test Scripts 59
testAbort 277
TESTCLASSES 71
testDiag 277
testDone 277
testFail. 277
testHarness 277
TESTJAVA 61
testMain.h 278
testOk 277
testOk1 277
testOkV 277
testPass 277
testPlan 277
TESTPROD 58, 63
TESTPROD_HOST 58, 63
TESTPROD_IOC 58, 63
TESTSCRIPTS 59, 63
TESTSCRIPTS_HOST. 59, 63
TESTSCRIPTS_IOC 59, 63
testSkip 277
testTodoBegin 277
testTodoEnd 277
Time Event 285
time provider. 285
top 31
Tornado II 33
tpn 157
TRAD 69
TRAPWRITE 127, 142
truncateFile 277, 292
truncateFile.h 277
tsBTree.h. 261
tsDLList.h 261
TSdriver.html 76
tsFreeList.h 261
tsMinMax.h. 261
tsSLList.h 261
type - variable definition 102

U

UAG 126–128
UDF. 174
udf 174
uninstall. 39
Unquoted String 93
USER_DBDFLAGS 42
USER_VPATH 72
USR_CFLAGS 45, 68
USR_CPPFLAGS 45, 68
USR_CXXFLAG 45
USR_CXXFLAGS 68
USR_DBDFLAGS 71
USR_INCLUDES. 44, 68
USR_JAVACFLAGS. 61, 72
USR_JAVAHFLAGS 62, 72
USR_LDFLAGS. 45, 69
USR_LIBS 49–50, 57, 67
USR_OBJLIBS. 48, 55, 66
USR_OBJS 48, 55, 65
USR_SRCS. 47, 56, 65
USR_SYS_LIBS. 50, 58, 67

V

VALID_BUILDS 37
var 249
variable 15, 93

variable_name - variable definition. 102
veclist 154, 312
VME_IO - link field value 105
vxComLibrary. 312
VXI_IO - link field value 106
vxWorks 33
vxWorks startup script 118

W

win32.bat. 77

Y

YACCOPT 71